

CS 341: Algorithms

Lecture 11: Depth-first search

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based on lecture notes by many other CS341 instructors

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Depth-first search

Going depth-first

The idea:

- travel as deep as possible, as long as you can
- when you can't go further, backtrack.

DFS implementations are based on stacks, either **implicitly** (recursion) or **explicitly** (as with queues for BFS).

Recursive algorithm

DFS(G)

$G = (V, E)$: a graph with n vertices, given by adjacency lists

1. let **visited** be an array of size n , with all entries set to **false**
2. **for all** v in V
3. **if** **visited**[v] is **false**
4. **explore**(v)

explore(v)

1. **visited**[v] = **true**
2. **for all** w neighbour of v **do**
3. **if** **visited**[w] = **false**
4. **explore**(w)

Remark: can add parent array as in BFS

Basic properties

Claim (“white path lemma”)

When we start exploring v , any w that can be connected to v by a path of **unvisited** vertices will be visited before **explore**(v) is finished.

Proof. Same as for **BFS**(s).

Claim

If w is visited during **explore**(v), there is a path $v \rightsquigarrow w$.

Proof. Same as for **BFS**(s).

Consequences

Shortest paths: no

Runtime: still $O(n + m)$

Connected components:

- let v_1, \dots, v_k be the indices from which we enter **explore** in **DFS**
- then for all j , **explore**(v_j) visits exactly the connected component of v_j
- so **DFS** gives a partition of G into rooted trees T_1, \dots, T_k (**DFS forest**)
(no common vertex, no connecting edge)

Ancestors and descendants

Definition. Suppose the DFS forest is T_1, \dots, T_k and let u, v be two vertices

- u is an **ancestor** of v iff they are on the same T_i and u is on the path $\text{root} \rightsquigarrow v$
- v is a **descendant** of u iff u is an ancestor of v
- $u = v$ is OK

Claim

All edges in G connect a vertex to one of its descendants or ancestors.

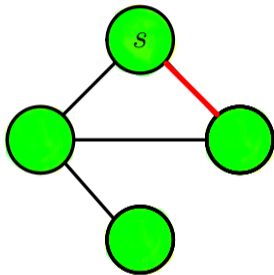
Proof. Let $\{v, w\}$ be an edge, and suppose we explore from v first.

Then when we explore from v , (v, w) is an unvisited path between v and w , so w will become a descendant of v (white path lemma)

Back edges

Definition.

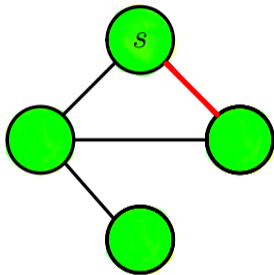
- a **back edge** is an edge in G connecting an ancestor to a descendant, which is **not** a tree edge.



Back edges

Definition.

- a **back edge** is an edge in G connecting an ancestor to a descendant, which is **not** a tree edge.



Observation

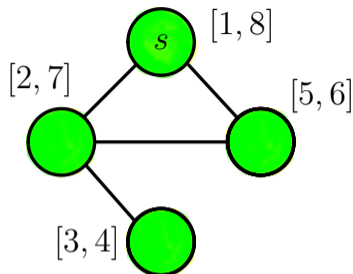
All edges are either **tree edges** or **back edges** (previous slide).

Start and finish times

Set a global variable t to 1 initially, create two arrays `start` and `finish`, and change **explore**:

```
explore( $v$ )
1.   visited[ $v$ ] = true
2.   start[ $v$ ] =  $t$ 
3.    $t++$ 
4.   for all  $w$  neighbour of  $v$  do
5.       if visited[ $w$ ] = false
6.           explore( $w$ )
7.   finish[ $v$ ] =  $t$ 
8.    $t++$ 
```

Example



Observation

time intervals are either contained in one another, or disjoint

Proof: if u starts before v , then

- either u finishes before v starts (disjoint intervals)
- or u is still on the program stack when v starts, then v finishes before u does (inclusion)

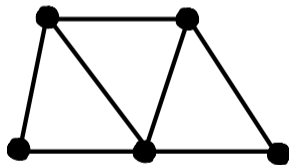
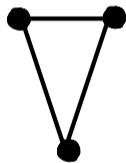
Cut vertices

Biconnectivity

Definition: $G = (V, E)$ **biconnected** if

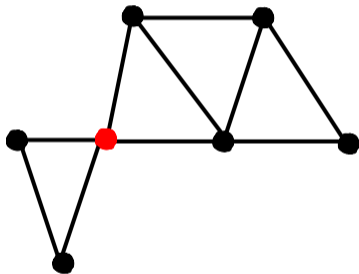
- G is connected
- G stays connected if we remove any vertex (and all edges that contain it)

Two biconnected graphs:



Cut vertices

Definition: for G connected, a vertex v in G is a **cut vertex** if removing v (and all edges that contain it) makes G disconnected. Also called **articulation point**.

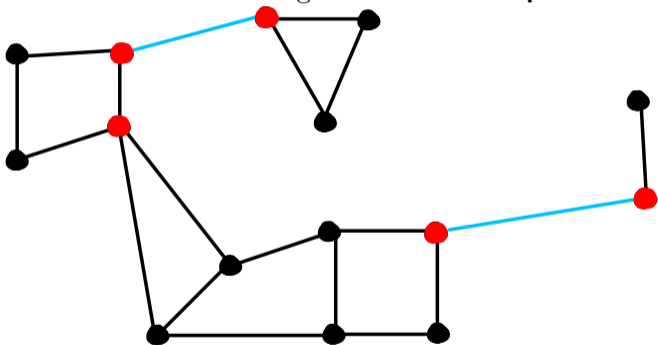


biconnected \iff no cut vertex

Aside: the shape of a connected undirected graph

Call **biconnected component** a biconnected subgraph that is not contained in a larger one (two **edges** are in the same biconnected component iff there is a cycle that contains them)

Then G can be seen as a tree of alternating **biconnected components** and **cut vertices**

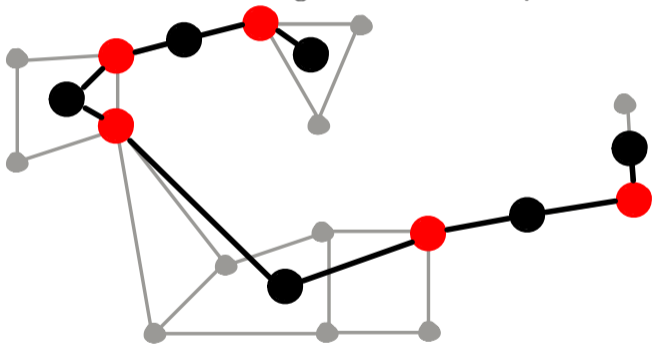


Remark: blue edges are **cut edges (bridges)**: removing them makes the graph disconnected

Aside: the shape of a connected undirected graph

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Then G can be seen as a tree of alternating **biconnected components** and **cut vertices**



Finding the cut vertices (G connected)

Setup: we start from a **rooted DFS tree** T , knowing parent and level.

Warm-up

The root s is a cut vertex if and only if **it has more than one child**.

Proof.

- if s has one child, removing s leaves T connected. So s not a cut vertex.
- suppose s has subtrees S_1, \dots, S_k , $k > 1$.

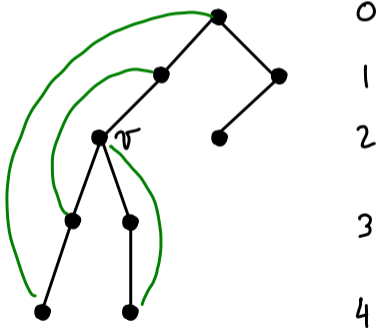
Key property: no edge connecting S_i to S_j for $i \neq j$. So removing s creates k connected components.

Finding the cut vertices (G connected)

Definition: for a vertex v , let

- $a(v) = \min\{\text{level}[w], \{v, w\} \text{ edge}\}$
- $m(v) = \min\{a(w), w \text{ descendant of } v\}$

(v is a descendant of v)



$$a(v) = 1$$
$$m(v) = 0$$

Using the values $m(v)$

Claim

For any v (except the root), v is a cut vertex if and only if **it has a child w with $m(w) \geq \text{level}[v]$.**

Proof

- Take a child w of v , let T_w be the subtree at w . Let also T_v be the subtree at v .
- If $m(w) < \text{level}[v]$, then there is an edge from T_w to a vertex above v . After removing v , T_w remains connected to the root.
- If $m(w) \geq \text{level}[v]$, then **all edges originating from T_w end in T_v .**

Proof: any edge originating from a vertex x in T_w ends at a level at least $\text{level}[v]$, and connects x to one of its ancestors or descendants (key property)

So after removing v , T_w is disconnected from the root (which is still here)

Runtime

Observation:

- if v has children w_1, \dots, w_k , then $m(v) = \min\{a(v), m(w_1), \dots, m(w_k)\}$

Consequence:

- DFS tree in $O(m)$
- computing $a(v)$ is $O(d_v)$
- knowing all $m(w_1), \dots, m(w_k)$, we get $m(v)$ in $O(d_v)$
- testing the cut-vertex condition at v is $O(d_v)$
- total $O(m)$

$d_v = \text{degree of } v$

Exercise

- write the pseudo-code
- find the bridges