CS 240 – Data Structures and Data Management

Module 5: Other Dictionary Implementations

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Based on lecture notes by many previous cs240 instructors

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Outline

- Dictionaries with Lists Revisited
 - Dictionary ADT
 - implementations so far
 - Skip Lists
 - Biased Search Requests

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- Dictionaries with Lists Revisited
 - Dictionary ADT
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Dictionary ADT: Implementations thus far

- A dictionary is a collection of key-value pairs (KVPs)
 - search, insert, and delete
- Realizations
 - Balanced search trees (AVL trees)
 - $\Theta(\log n)$ search, insert, and delete
 - complex code and not necessarily the fastest running time in practice
 - Binary search trees
 - $\Theta(height)$ search, insert and delete
 - simpler than AVL tree, randomization helps efficiency
 - Ordered array
 - simple implementation, $\Theta(\log n)$ search
 - $\Theta(n)$ insert and delete
 - Ordered linked list
 - simple implementation
 - $\Theta(n)$ search, insert and delete
 - search is the bottleneck, insert and delete would be $\Theta(1)$ if do search first and account for its running time separately

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65

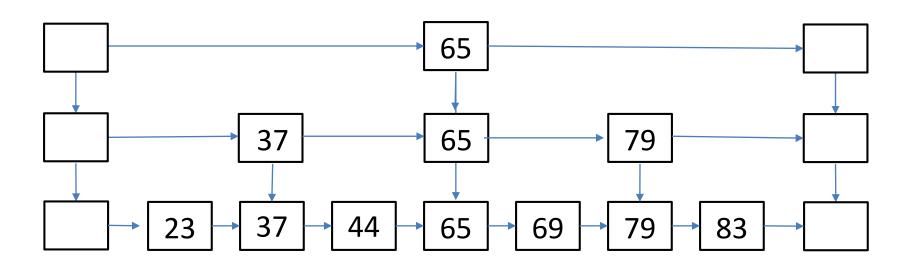
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efficient search (like binary search) in ordered linked list?

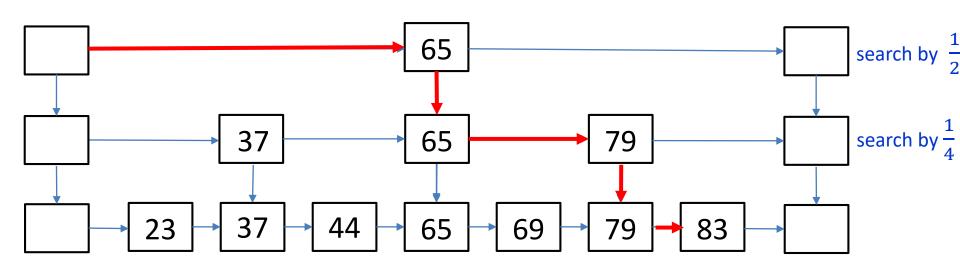
Outline

- Dictionaries with Lists Revisited
 - Dictionary ADT
 - implementations so far
 - Skip Lists
 - Re-ordering items

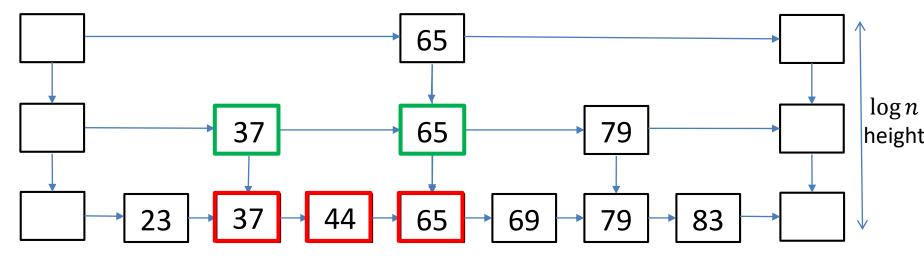
- Build a hierarchy of linked lists to imitate binary search in ordered linked list wi
 - start from the bottom list and take every second item in the list above
 - downward links are needed to navigate from list above to the list below



- Search goes through the higher lists while possible, before dropping down to the list below
 - top list enables search by ½ of the list, next by ¼ of the list, and so on
- Search(83)

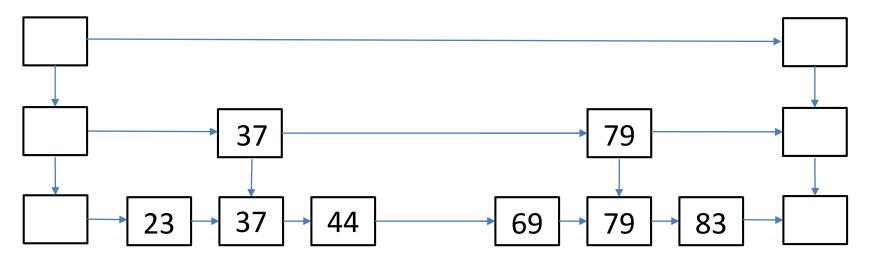


- Hierarchy of linked lists
 - each list has 1/2 of items from the list below
 - total number of linked lists (height) is log n
 - total number of nodes $\leq 2n$



- When searching, go through the highest level possible
 - thus visit at most two items at each level, and total time to search $\Theta(\log n)$

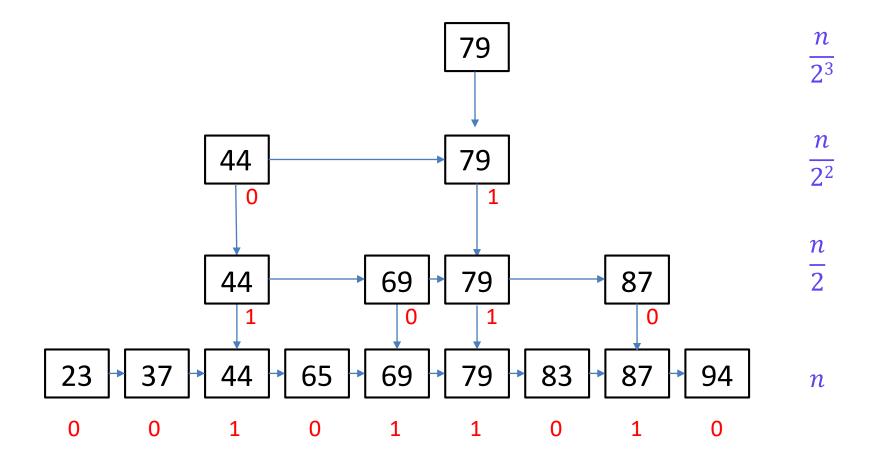
Deleted 65, no longer every second item is in the list above



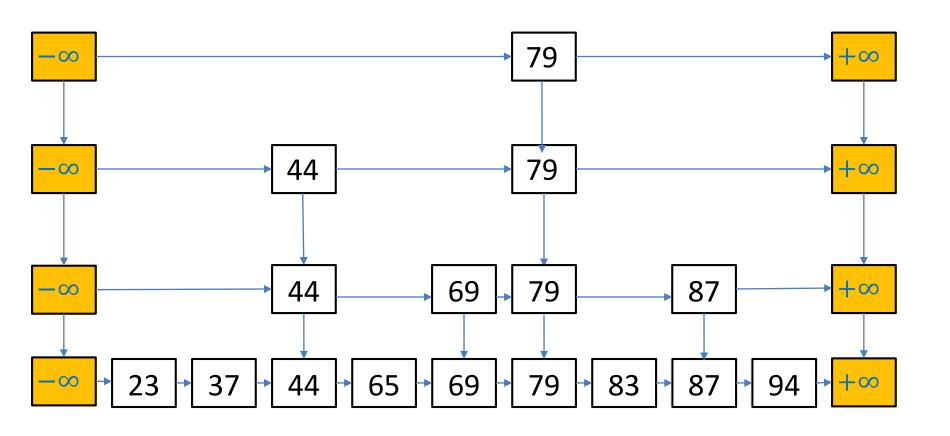
- Big problem: deletion or insertion of items ruins 'every second item is in the list above' property
 - crucial property for efficiency
- Thus the hierarchy of linked lists works only for static dictionary
 - know all items beforehand, and do not insert or delete
 - but in static case an ordered array is more efficient in practice (no links)
- Randomization enables hierarchical linked list with efficient insert and delete
 - instead of requiring a deterministic subset of items in list above, randomly chose a subset of the items in the list above

- For next level, choose each item from previous level with probability ½ (coin toss)
- *i*th list is expected to have $n/2^i$ nodes
- Expect about log(n) lists in total

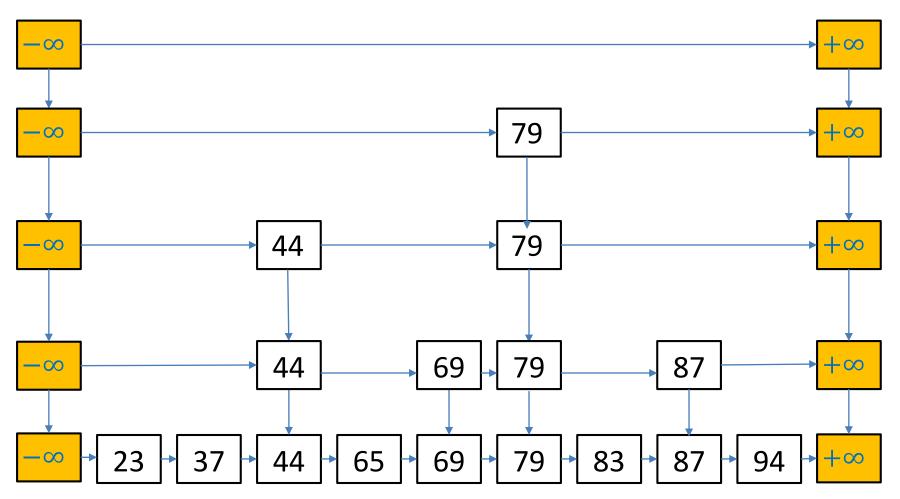
expected number of nodes



- Insert 'boundary' nodes with special sentinel symbols $-\infty$ and $+\infty$
 - to simplify code for searching

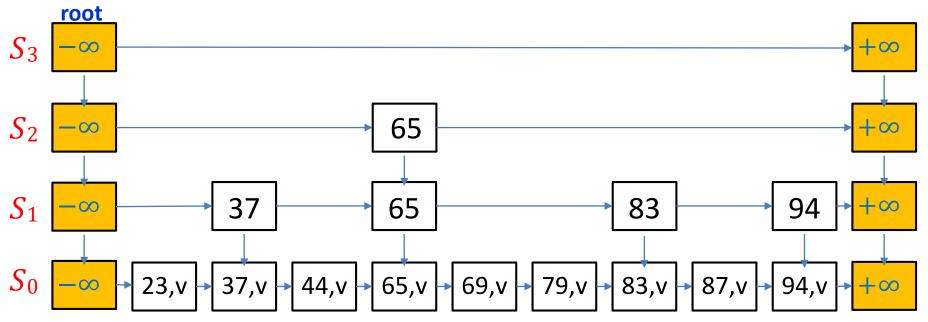


- Insert sentinel only level, with only $-\infty$ and $+\infty$
 - to simplify code for searching



Skip Lists [Pugh'1989]

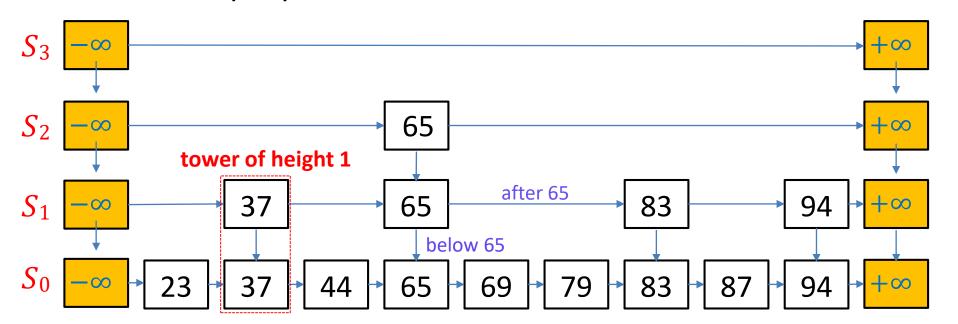
- A hierarchy S of ordered linked lists (*levels*) $S_0, S_1, ..., S_h$
 - S_0 contains the KVPs of S in non-decreasing order
 - other lists store only keys
 - each S_i contains special keys (sentinels) $-\infty$ and $+\infty$
 - each S_i is randomly generated subsequence of S_{i-1} i.e., $S_0 \supseteq S_1 \supseteq ... \supseteq S_h$
 - S_h contains only sentinels, the left sentinel is the root



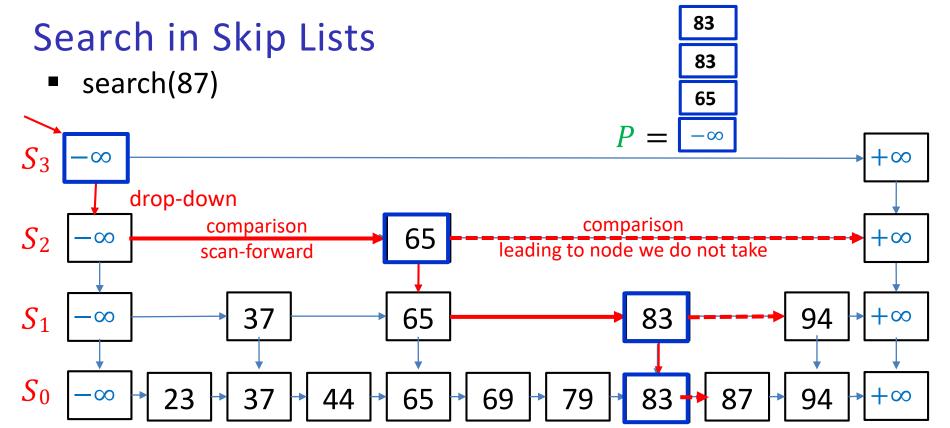
• n is number of KVP (number of items stored); in this example, n=9

Skip Lists

Show only keys from now on



- Each KVP belongs to a tower of nodes
 - tower height is number of nodes 1
- Height of the skip list is the maximum height of any tower
 - height is 3 in this example
- Each node p has references to after(p) and below(p)
- There are (usually) more nodes than keys



- For each level, predecessor of key k is
 - If key k is present at the level: node before node with key k
 - if key k is not present at the level: node before node where k would have been
- P collects predecessors of key k for all levels
 - nodes where we drop down and the rightmost node in S_0 with key < k
 - these are needed for insert/delete
- k is in skip list if and only if P.top().after has key k

Search in Skip Lists

```
getPredecessors(k)
         p \leftarrow root
         P \leftarrow stack of nodes, initially containing p
         while p. below \neq NIL do // keep dropping down until reach S_0
             p \leftarrow p. below
             while p, after, key < k do
                     p \leftarrow p. after //move to the right
              P.push(p)
                           // this is next predecessor
         return P
```

```
skipList::search(k) \\ P \leftarrow getPredecessors(k) \\ q \leftarrow P.top() \qquad //predecessor of $k$ in $S_0$ \\ if $q.after.key = k$ return $q.after$ \\ else return 'not found, but would be after $q'$
```

Insert in Skip Lists

```
S_3 if in S_2, then insert new item with probability ½ S_2 if in S_1, then insert new item with probability ½ S_1 insert new item with probability ½ S_0 insert new item
```

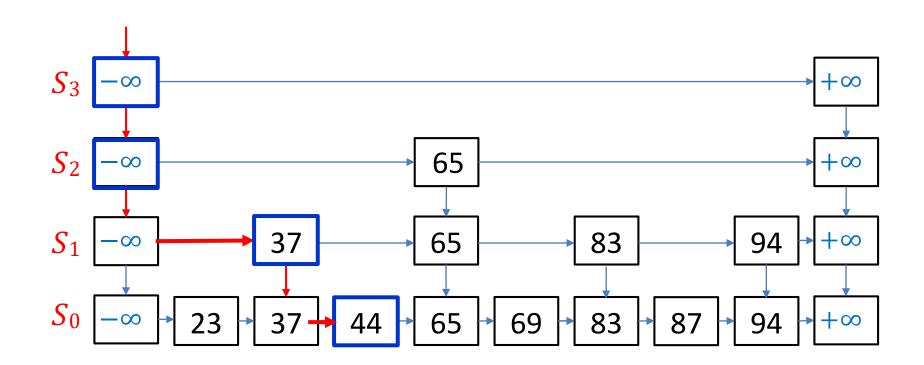
- Keep "tossing a coin" until T appears
- Insert into S_0 and as many other S_i as there are heads
- Examples
 - H, H, T (insert into S_0, S_1, S_2) \Rightarrow will say i = 2
 - H,T (insert into S_0, S_1) \Rightarrow will say i=1
 - T (insert into S_0) \Rightarrow will say i = 0

- skipList::insert(52, v)
- coin tosses: $H, T \Rightarrow i = 1$
- getPredecessors(52)

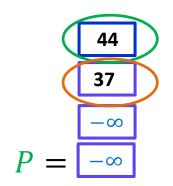
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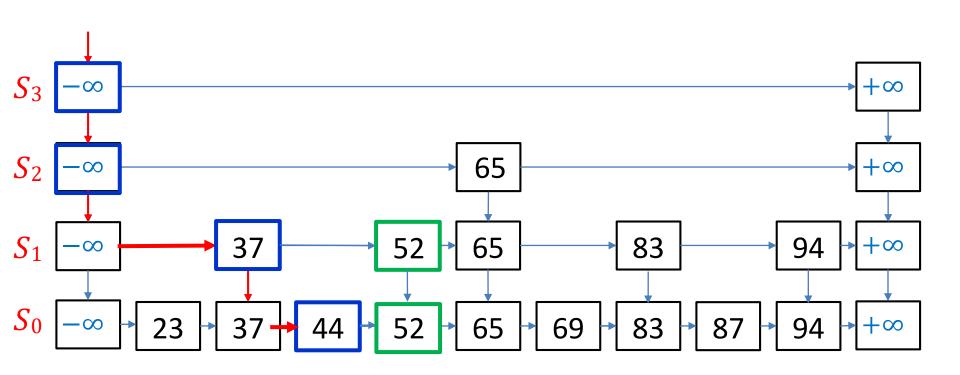
 $-\infty$

P = −∞

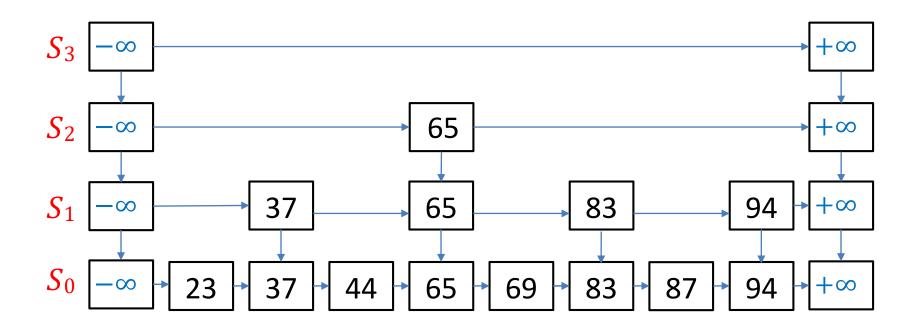


- skipList::insert(52, v)
- coin tosses: $H, T \Rightarrow i = 1$
- getPredecessors(52)
- now insert into S_0 and S_1

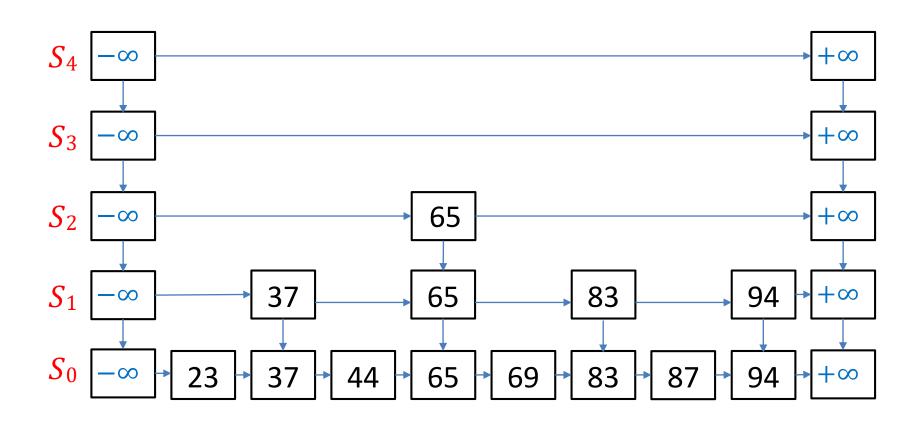




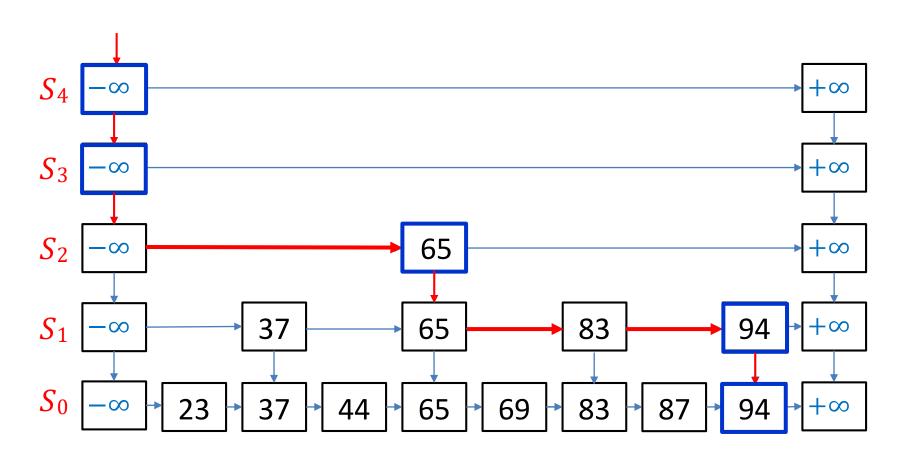
- skipList::insert(100, v)
- coin tosses: $H, H, H, T \Rightarrow i = 3$
- first increase height



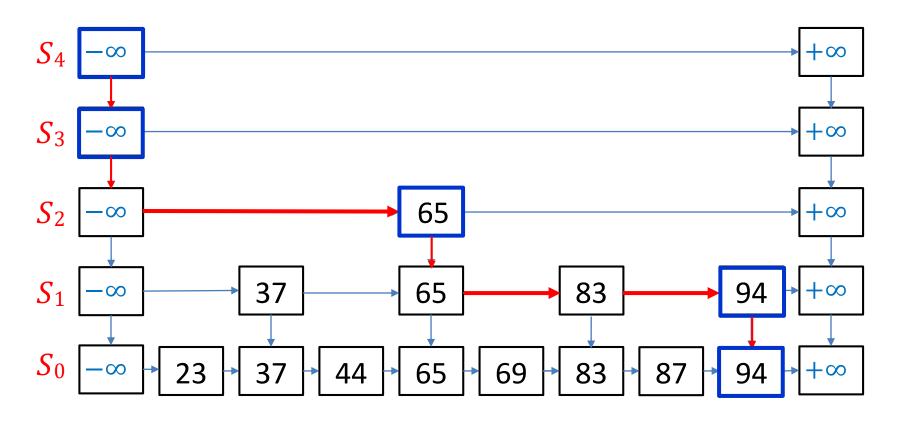
- skipList::insert(100, v)
- coin tosses: $H, H, H, T \Rightarrow i = 3$
- first increase height
- next getPredecessors (100)



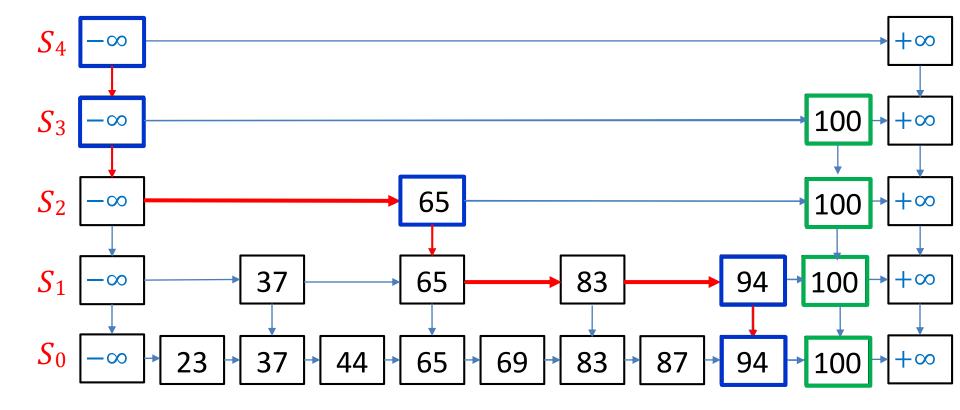
- skipList::insert(100, v)
- coin tosses: $H, H, H, T \Rightarrow i = 3$
- first increase height
- next getPredecessors (100)



- skipList::insert(100, v)
- coin tosses: $H, H, H, T \Rightarrow i = 3$
- first increase height
- next *getPredecessors* (100)
- insert new key



- skipList::insert(100, v)
- coin tosses: $H, H, H, T \Rightarrow i = 3$
- first increase height
- next getPredecessors (100)
- insert new key

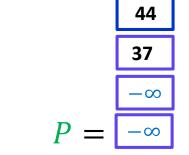


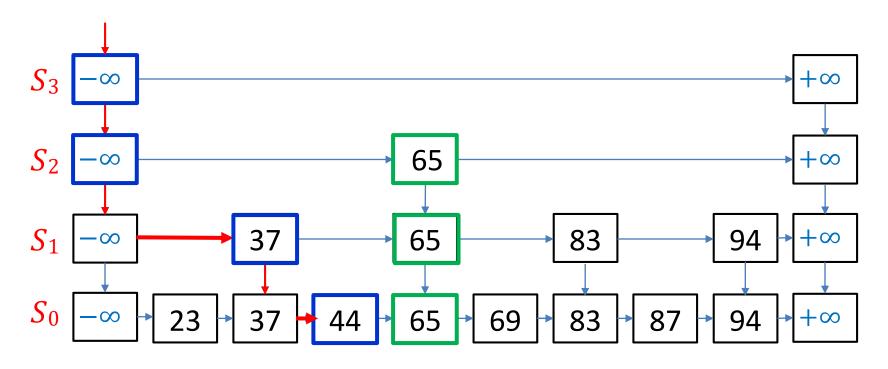
Insert in Skip Lists

```
skipList::insert(k, v)
       for (i \leftarrow 0; random(2) = 1; i \leftarrow i + 1) {}
                                                                             // random tower height
       for (h \leftarrow 0, p \leftarrow root. below; p \neq NILL; p \leftarrow p. bellow) do h + +
       while i > h
                                                               // increase skip-list height if needed
           root \leftarrow new sentinel-only list linked in appropriately
            h++
       P \leftarrow getPredecessors(k)
       p \leftarrow P \cdot pop()
       zBellow \leftarrow \text{new node with } (k, v) \text{ inserted after } p \qquad // \text{ insert } (k, v) \text{ in } S_0
       while i > 0
                                                                              // insert k in S_1 S_2,..., S_k
            p \leftarrow P pop()
            z \leftarrow new node with k added after p
            z.below \leftarrow zBellow
            zBellow \leftarrow z
           i \leftarrow i - 1
```

Example: Delete in Skip Lists

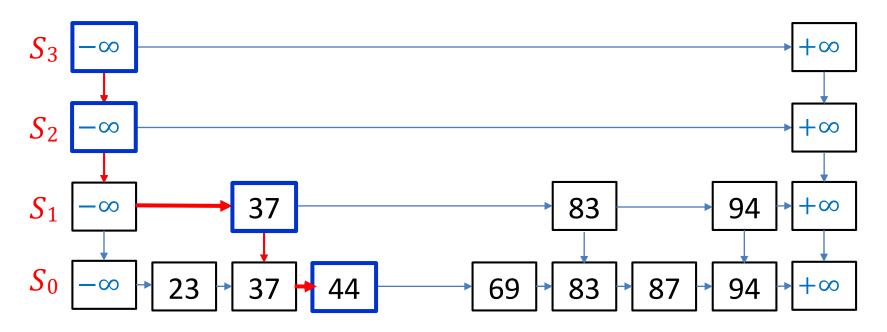
- skipList::delete(65)
 - first *getPredecessors*(*S*, 65)
 - then delete key 65 from all S_i
 - P has predecessor of each node to be deleted





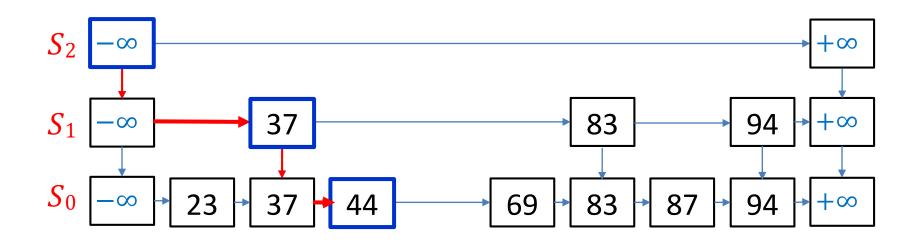
Example: Delete in Skip Lists

- skipList::delete(65)
 - first *getPredecessors*(*S*, 65)
 - then delete key 65 from all S_i
 - P has predecessor of each node to be deleted
 - height decrease: delete all unnecessary S_i , if any



Example: Delete in Skip Lists

- skipList::delete(65)
 - first *getPredecessors*(*S*, 65)
 - then delete key 65 from all S_i
 - P has predecessor of each node to be deleted
 - height decrease: delete all unnecessary S_i , if any



Delete in Skip Lists

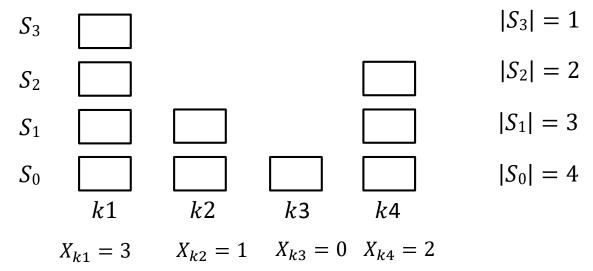
```
skipList::delete(k)
         P \leftarrow getPredecessors(k)
         while P is non-empty
                                                     // predecessor of k in some layer
                 p \leftarrow P.pop()
                 if p. after. key = k
                      p.after \leftarrow p.after.after
                                                     // no more copies of k
                 else break
          p \leftarrow \text{left sentinel of the root-list}
         while p. below. after is the \infty sentinel
            // the two top lists are both only sentinels, remove one
            p.below \leftarrow p.below.below // removes the second empty list
            p.after.below \leftarrow p.after.below.below
```

Let
$$X_k$$
 be the height of tower for key k
$$P(X_k \ge 1) = \frac{1}{2} \qquad P(X_k \ge 2) = \frac{1}{2} \cdot \frac{1}{2} \qquad P(X_k \ge 3) = \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2}$$
 toss $HH....$

$$P(X_k \ge 3) = \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2}$$

In general
$$P(X_k \ge i) = P(H \ H \ \dots \ H) = \left(\frac{1}{2}\right)^i$$
i times

- In the worst case, the height of a tower could be arbitrary large
 - no bound on height in terms of n
- Operations could be arbitrarily slow, and space requirements arbitrarily large
 - but this is exceedingly unlikely
- Let us analyse expected run-time and space-usage (randomized data structure)



- Let X_k be the height of tower for key k, we know $P(X_k \ge i) = \frac{1}{2^i}$
- If $X_k \ge i$ then list S_i includes key k
- Let $|S_i|$ be the number of keys in list S_i
 - sentinels do not count towards the length
 - S_0 always contains all n keys

$$S_3$$
 $I_{3, k1} = 1$ $I_{3, k2} = 0$ $I_{3, k3} = 0$ $I_{3, k4} = 0$ $|S_3| = 1$ $|S_2| = 2$ $|S_3| = 1$ $|S_2| = 2$ $|S_3| = 1$ $|S_3| = 1$

- Let X_k be the height of tower for key k, we know $P(X_k \ge i) = \frac{1}{2^i}$
- If $X_k \ge i$ then list S_i includes key k
- Let $|S_i|$ be the number of keys in list S_i
- Let $I_{i,k} = \begin{cases} 0 & \text{if } X_k < i \\ 1 & \text{if } X_k \ge i \end{cases} = \begin{cases} 0 & \text{if list } S_i \text{ does not include key } k \\ 1 & \text{if list } S_i \text{ includes key } k \end{cases}$
- $|S_i| = \sum_{k \in \mathcal{V}_k} I_{i,k}$
- $E[|S_i|] = E\left[\sum_{k \in \mathcal{Y}} I_{i,k}\right] = \sum_{k \in \mathcal{Y}} E[I_{i,k}] = \sum_{k \in \mathcal{Y}} P(I_{i,k} = 1) = \sum_{k \in \mathcal{Y}} P(X_k \ge i) = \sum_{k \in \mathcal{Y}} \frac{1}{2^i} = \frac{n}{2^i}$
 - The expected length of list S_i is $\frac{n}{2^i}$

• $|S_i|$ is number of keys in list S_i

$$\bullet \quad E[|S_i|] = \frac{n}{2^i}$$

Let
$$I_i = \begin{cases} 0 & \text{if } |S_i| = 0 \\ 1 & \text{if } |S_i| \ge 1 \end{cases}$$

 S_4 has only sentinels

$$I_4 = 0$$

$$S_3$$

$$I_3 = 1$$

$$S_2$$

$$I_2=1$$

$$S_1$$

$$I_1 = 1$$

$$S_0$$

$$k1$$
 $k2$

- $h = 1 + \sum_{i>1} I_i$ (here +1 is for the sentinel-only level)
- Since $I_i \le 1$ we have that $E[I_i] \le 1$
- Since $I_i \leq |S_i|$ we have that $E[I_i] \leq E[|S_i|] = \frac{n}{2^i}$
- For ease of derivation, assume n is a power of 2

■
$$E[h] = E\left[1 + \sum_{i \ge 1} I_i\right] = 1 + \sum_{i \ge 1}^{\log n} E[I_i] + \sum_{i = 1 + \log n}^{\infty} E[I_i]$$

 $\leq 1 + \sum_{i = 1}^{\log n} 1 + \sum_{i = 1 + \log n}^{\infty} \frac{n}{2^i}$
 $\leq 1 + \log n + \sum_{i = 0}^{\infty} \frac{n}{2^{i+1 + \log n}}$

 S_4 has only sentinels

$$I_4 = 0$$

 S_3

 $I_3 = 1$

• $|S_i|$ is number of keys in Liet S.

$$\bullet \quad E[|S_i|] = \frac{n}{2^i}$$

Let
$$I_i = \begin{cases} 0 & \text{if } |S_i| = 0 \\ 1 & \text{if } |S_i| \ge 0 \end{cases}$$

•
$$h = 1 + \sum_{i>1} I_i$$
 (here +

- Since $I_i \leq 1$ we have that
- Since $I_i \leq |S_i|$ we have
- For ease of derivation, a

$$\sum_{i=0}^{\infty} \frac{n}{2^{i+1+\log n}} = \sum_{i=0}^{\infty} \frac{n}{2^{i}2^{1}2^{\log n}}$$

$$=\frac{1}{2}\sum_{i=0}^{\infty}\frac{n}{2^{i}n}$$

$$=\frac{1}{2}\sum_{i=0}^{\infty}\frac{1}{2^i}=\frac{1}{2}2=1$$

For ease of derivation, a
$$E[h] = E\left[1 + \sum_{i \ge 1} I_i\right] = S = \sum_{i=0}^{\infty} \frac{1}{2^i} = 1 + \frac{1}{2} + \frac{1}{2^2} + \frac{1}{2^3} + \cdots$$
$$2S = \sum_{i=0}^{\infty} \frac{2}{2^i} = 2 + 1 + \frac{1}{2} + \frac{1}{2^2} + \cdots$$

$$2S = \sum_{i=0}^{\infty} \frac{2}{2^{i}} = 2 + 1 + \frac{1}{2} + \frac{1}{2^{2}} + \cdots$$

$$2S - S = 2$$

 $|S_i|$ is number of keys in list S_i

$$\bullet \quad E[|S_i|] = \frac{n}{2^i}$$

Let $I_i = \begin{cases} 0 & \text{if } |S_i| = 0 \\ 1 & \text{if } |S_i| \ge 1 \end{cases}$

 S_4 has only sentinels

$$S_4$$
 has only sentinels

 S_3

 S_2

 S_1

 S_0

k2

*k*3

$$I_2 = 1$$

 $I_4 = 0$

 $I_3 = 1$

*k*4

$$I_1 = 1$$

- $h = 1 + \sum_{i>1} I_i$ (here +1 is for the sentinel-only level)
- Since $I_i \leq 1$ we have that $E[I_i] \leq 1$
- Since $I_i \leq |S_i|$ we have that $E[I_i] \leq E[|S_i|] = \frac{\pi}{2i}$
- For ease of derivation, assume n is a power of 2

■
$$E[h] = E\left[1 + \sum_{i \ge 1} I_i\right] = 1 + \sum_{i \ge 1}^{\log n} E[I_i] + \sum_{i = 1 + \log n}^{\infty} E[I_i]$$

$$\le 1 + \sum_{i = 1}^{\log n} 1 + \sum_{i = 1 + \log n}^{\infty} \frac{n}{2^i}$$

$$\le 1 + \log n + \sum_{i = 0}^{\infty} \frac{n}{2^{i+1 + \log n}}$$

$$= 1 + \log n + 1$$

Expected skip list height $\leq 2 + \log n$

Skip List Analysis: Expected Space

- We need space for nodes storing sentinels and nodes storing keys
- Space for nodes storing sentinels
 - there are 2h + 2 sentinels, where h be the skip list height
 - $E[h] \leq 2 + \log n$
 - expected space for sentinels is at most

$$E[2h + 2] = 2E[h] + 2 \le 6 + 2\log n$$

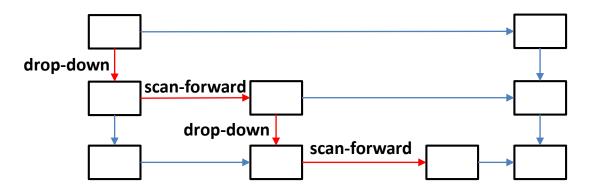
- Space for nodes storing keys
 - Let $|S_i|$ be the number of keys in list S_i

$$\bullet \quad E[|S_i|] = \frac{n}{2^i}$$

• expected space for keys is $E\left|\sum |S_i|\right| = \sum_{i>0} E[|S_i|] = \sum_{i>0} \frac{n}{2^i} = 2n$

Total expected space is $\Theta(n)$

Skip List Analysis: Expected Running Time



- search, insert, and delete are dominated by the runtime of getPredecessors
- So we analyze the expected time of getPredecessors
 - runtime is proportional to number of 'drop-down' and 'scan-forward'
- We 'drop-down' h times, where h is skip list height
 - expected height h is $O(\log n)$
 - total expected time spent on 'drop-down' operations is $O(\log n)$
- Will show next that expected number of 'scan-forward' is also $O(\log n)$
- So total expected running time is $O(\log n)$

Expected Number of Scan-Forward Operations

- Number 'scan-forward' at level i
 - assume i < h (if i = h, then we are at the top list and do not scan forward at all)
 - let v be leftmost key in S_i we visit during search
 - we v reached by dropping down from S_{i+1}
 - let w be the key right after v
 - height of tower of w in this case is at least i
- S_{i+1} v w
- what is the probability of scanning from v to w?
 - if we do scan forward from v to w, then w did not exist in S_{i+1}
 - otherwise, we would scan forward from v to w in S_{i+1}
- Thus if we do scan forward from v to w, then the tower of w has height i
 - $P(\text{tower of } w \text{ has height } i | \text{tower of } w \text{ has height at least } i) = \frac{1}{2}$
 - scan forward (i.e. at least one scan) from v to w with probability at most $\frac{1}{2}$
 - 'at most' because we could scan-down down if search key < w
 - repeating argument, probability of scan-forward at least l times is at most $(1/2)^l$

$$E[\# \text{ scan-forward at level } i] = \sum_{l \ge 1} l \cdot P(\text{scans} = l) = \sum_{l \ge 1} P(\text{scans} \ge l) \le \sum_{l \ge 1} \frac{1}{2^l} = 1$$
theory

Expected Number of Scan-Forward Operations

- At level i < h: $E[number of scan-forward] \le 1$
- Also, expected number of scan-forward at level i < number of keys at level S_i
 - $|S_i|$ is the number of keys in list on level i, and $E[|S_i|] = \frac{n}{2^i}$
- For ease of derivation, assume n is a power of 2
- Expected number of scan-forward over all levels

$$\sum_{i \geq 0} E[\# \text{ of scan-forward at level } i] =$$

$$= \sum_{i=1}^{\log n} E[\# \text{ of scan-for at level } i] + \sum_{i=1+\log n}^{\infty} E[\# \text{ of scan-for at level } i]$$

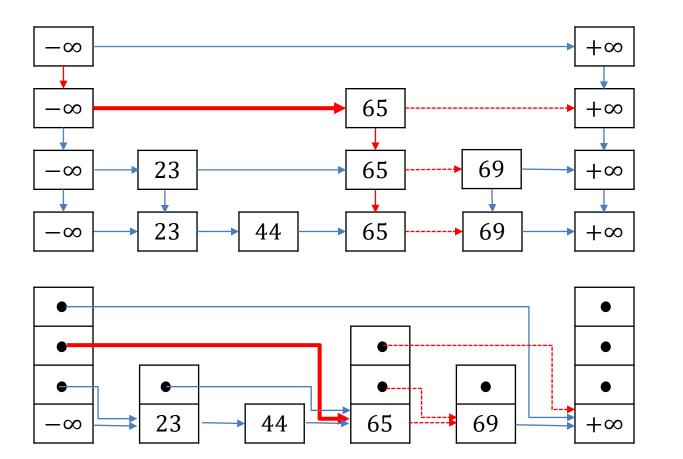
$$\leq \sum_{i=1}^{\log n} 1 + \sum_{i=1+\log n}^{\infty} \frac{n}{2^i}$$

$$\leq \log n + 1$$

• Expected number of scan-forwards is $O(\log n)$

Arrays Instead of Linked Lists

- As described now, they are no faster than randomized binary search trees
- Can save links by implementing each tower as an array
 - this not only saves space, but gives better running time in practice
 - when 'scan-forward', we know the correct array location to look at (level i)
- Search(67)



Summary of Skip Lists

- For a skip list with n items
 - expected space usage is O(n)
 - expected running time for search, insert, delete is $O(\log n)$
- Two efficiency improvements
 - use arrays for key towers for more efficient implementation
 - can show: a biased coin-flip to determine tower-height gives smaller expected run-times
- With arrays and biased coin-flip skip lists are fast in practice and easy to implement

Outline

- Dictionaries with Lists Revisited
 - Dictionary ADT
 - implementations so far
 - Skip Lists
 - Biased Search Requests

Improving Unsorted Lists/Arrays

- Unordered lists/arrays are among simplest data structures to implement
- But for Dictionary ADT
 - inefficient *search*: $\Theta(n)$
- Can we make search in unordered lists/arrays more effective in practice?
 - No if items are accessed equally likely
 - can show average-case search is $\Theta(n)$
 - Yes if the search requests are biased
 - some items are accessed much more frequently than others
 - 80/20 rule: 80% of outcomes result from 20% of causes
 - access = insertion or successful search
 - frequently accessed items should be in the front
 - two cases
 - know the access distribution beforehand
 - optimal static ordering
 - do not know access distribution beforehand
 - dynamic ordering

Optimal Static Ordering

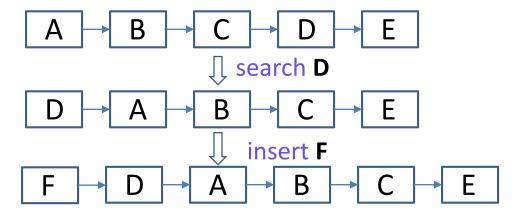
key	А	В	С	D	E
frequency of access	2	8	1	10	5
access probability	2 26	8 26	1 26	10 26	5 26

• Order
$$A B C D E has expected cost $\frac{2}{26} \cdot 1 + \frac{8}{26} \cdot 2 + \frac{1}{26} \cdot 3 + \frac{10}{26} \cdot 4 + \frac{5}{26} \cdot 5 \approx 3.31$$$

- Order D B E A C has expected cost $\frac{10}{26} \cdot 1 + \frac{8}{26} \cdot 2 + \frac{5}{26} \cdot 3 + \frac{2}{26} \cdot 4 + \frac{1}{26} \cdot 5 \approx 2.54$
- Claim: ordering items by non-increasing access-probability minimizes expected access cost, i.e. best static ordering
 - static ordering: order of items does not change
- Proof Idea: for any other ordering, exchanging two items that are out-oforder according to access probabilities makes total cost increase

Dynamic Ordering

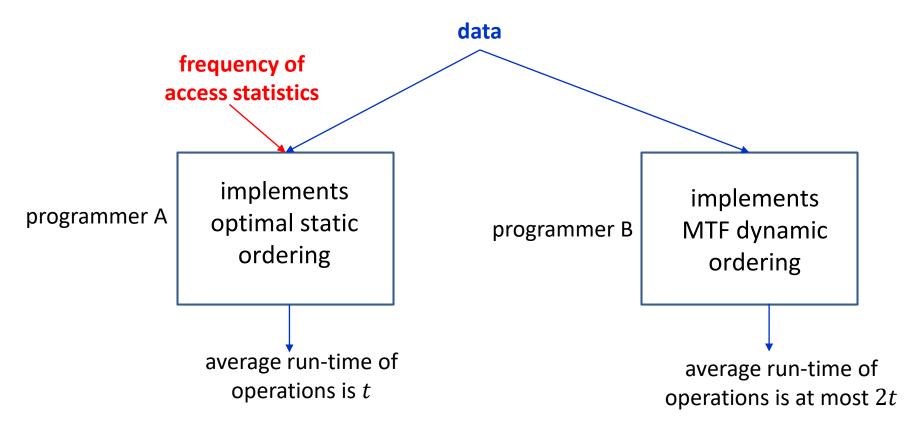
- Dynamic ordering: order of items is allowed to change
- What if we do not know the access probabilities ahead of time?
- Rule of thumb: recently accessed item is likely to be accessed soon again
- Move-To-Front heuristic (MTF): after search, move the accessed item to the front
 - additionally, in list: always insert at the front



- We can also do MTF on an array
 - but should then insert and search from back so that we have room to grow

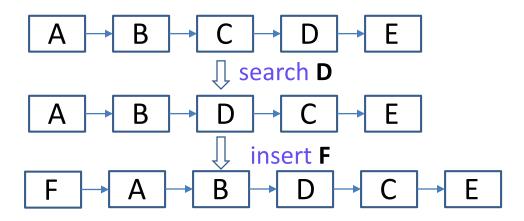
Dynamic Ordering: MTF

- Can show: MTF is "2-competitive"
 - no more than twice as bad as the optimal "offline" ordering



Dynamic Ordering: Other Heuristics

Transpose heuristic: Upon a successful search, swap accessed item with the immediately preceding item



- Avoids drastic changes MTF might do, while still adapting to access patterns
- Frequency-count heuristic: Keep counters how often items were accessed, and sort in non-decreasing order
 - works well in practice, but requires extra space

Summary of Biased Search Requests

- We are unlikely to know the access-probabilities of items, so optimal static order is mostly of theoretical interest
- For any dynamic reordering heuristic, some sequence will defeat it
 - have $\Theta(n)$ access cost for each item
- MTF and Frequency-Count work well in practice
- For MTF can prove theoretical guarantees
- There is very little overhead for MTF and other strategies, they should be applied whenever unordered arrays or lists are used