CS 240 – Data Structures and Data Management

#### Module 7: Dictionaries via Hashing

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#### Based on lecture notes by many previous cs240 instructors

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### Outline

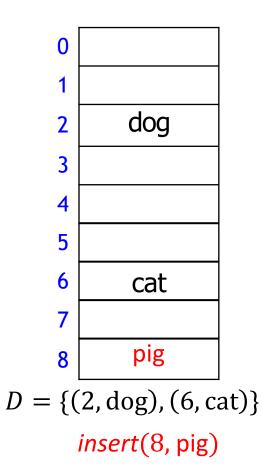
- Dictionaries via Hashing
  - Hashing Introduction
  - Hashing with Chaining
  - Open Addressing
    - probe sequences
    - cuckoo hashing
  - Hash Function Strategies

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### **Direct Addressing**

- Special situation: every key k is integer with  $0 \le k < M$
- Direct addressing implementation
  - store (k, v) in array A of size M via  $A[k] \leftarrow v$
  - search(k): check if A[k] is empty
  - $insert(k, v): A[k] \leftarrow v$



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 $D = \{(2, dog), (6, cat), (8, pig)\}$ delete(2)

## **Direct Addressing**

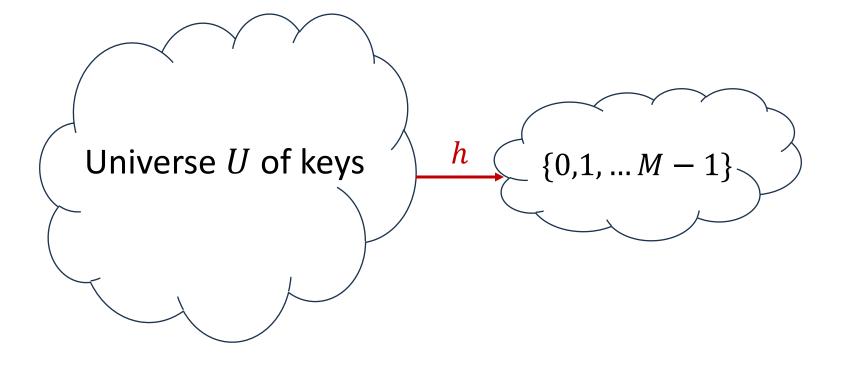
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  - search(k): check if A[k] is empty
  - $insert(k, v): A[k] \leftarrow v$
  - $delete(k): A[k] \leftarrow empty$
  - all operations are O(1)
  - total storage is  $\Theta(M)$
  - Drawbacks
    - 1. space is wasteful if  $n \ll M$
    - 2. keys must be integers



 $D = \{(6, cat), (8, pig)\}$ 

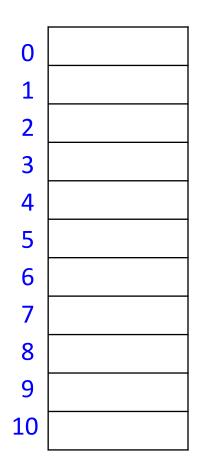
### Hashing

• Idea: first map keys to a smaller integer range and then use direct addressing



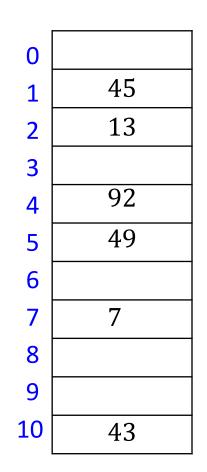
# Hashing

- Idea: first map keys to a smaller integer range and then use direct addressing
- Assumption: keys come from some *universe U* 
  - typically  $U = \{0, 1, ...\}$ , sometimes U is finite
- Design hash function  $h: U \rightarrow \{0, 1, \dots, M 1\}$ 
  - h(k) is called *hash value* of k
  - example:  $h(k) = k \mod M$
  - will see other choices later
- Store dictionary in array *T* of size *M*, called *hash table*
- Item with key k wants to be stored in *slot* h(k) of array T
- Example
  - U = N, M = 11,  $h(k) = k \mod 11$
  - keys 7, 13, 43, 45, 49, 92



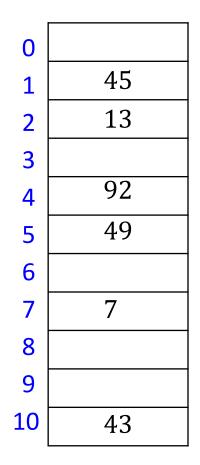
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- Example
  - U = N, M = 11,  $h(k) = k \mod 11$
  - keys 7, 13, 43, 45, 49, 92
  - as usual, store KVP, but show only keys
- Typically choose  $M \in \Theta(n)$ 
  - shrink or expand the hash table dynamically as items inserted/deleted
- There are good reasons for choosing *M* to be a prime number



# Hash Functions and Collisions

- Hash function
  - should be fast, O(1), to compute
- Generally hash function h is not injective
  - many keys can map to the same integer, example
    - $h(k) = k \mod 11$ ,
    - h(46) = 2 = h(13)
- Collision: want to insert (k, v), but T[h(k)] is occupied
- Two main strategies to deal with collisions
  - 1. Chaining: allow multiple items at each table location
  - 2. Open addressing: alternative slots in array
    - probe sequence: many alternative locations
      - linear probing
      - double hashing
    - cuckoo hashing: just one alternative location



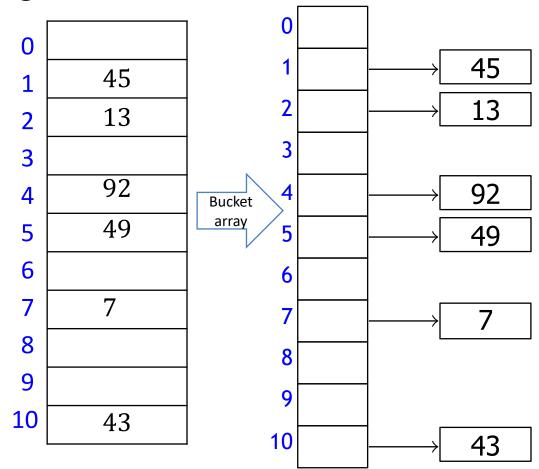
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### Hashing with Chaining

$$M = 11, h(k) = k \mod 11$$

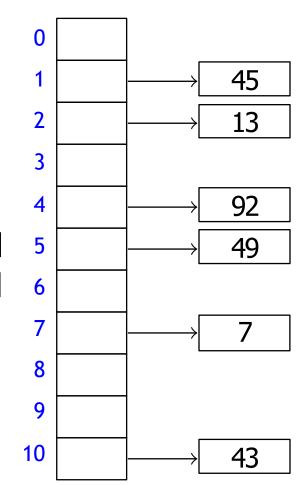
- Each slot is a *bucket* containing 0 or more KVPs
  - bucket can be implemented by any dictionary
  - even another hash table
  - simplest approach is unsorted linked list dictionary in each bucket
    - this is called chaining

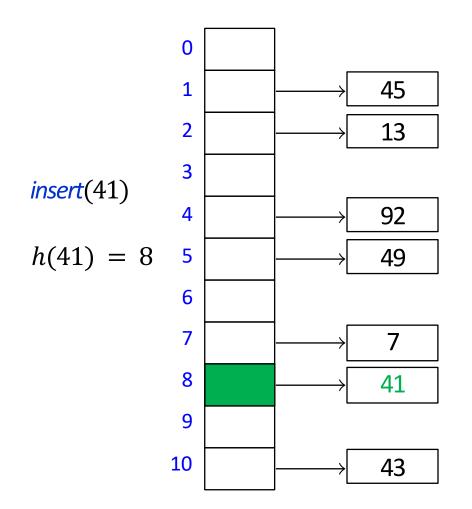


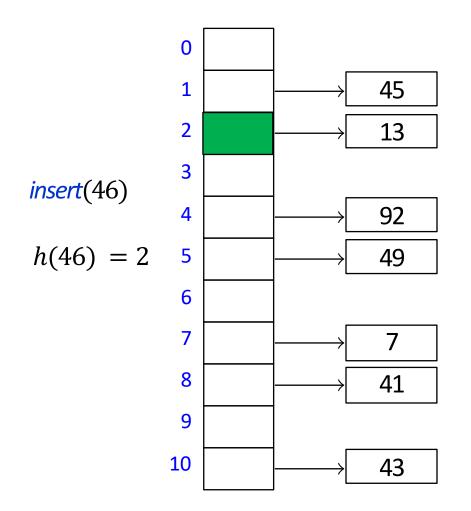
# Hashing with Chaining

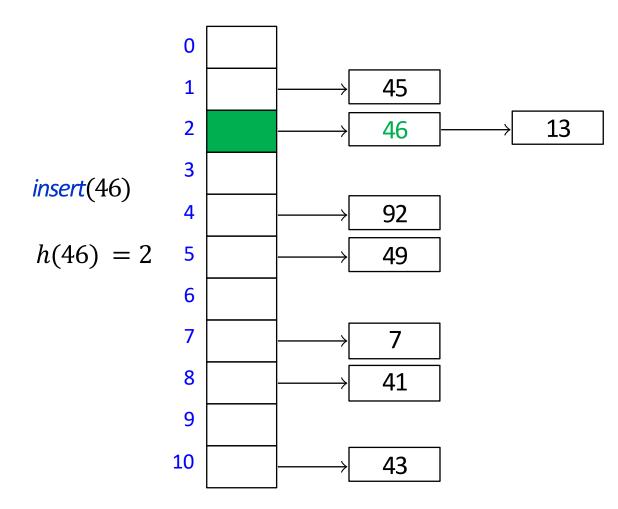
Operations

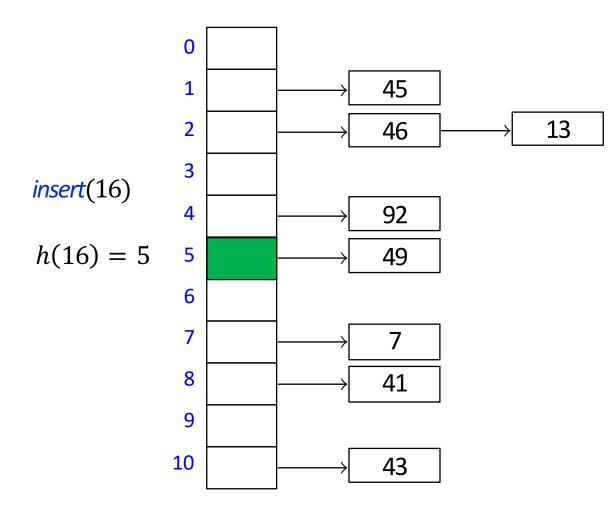
- search(k): look for key k in the list at T[h(k)]
  - apply MTF heuristic
- *insert*(k, v): add (k, v) to the *front* of list at T [h(k)]
- delete(k): search and delete from the list at T[h(k)]

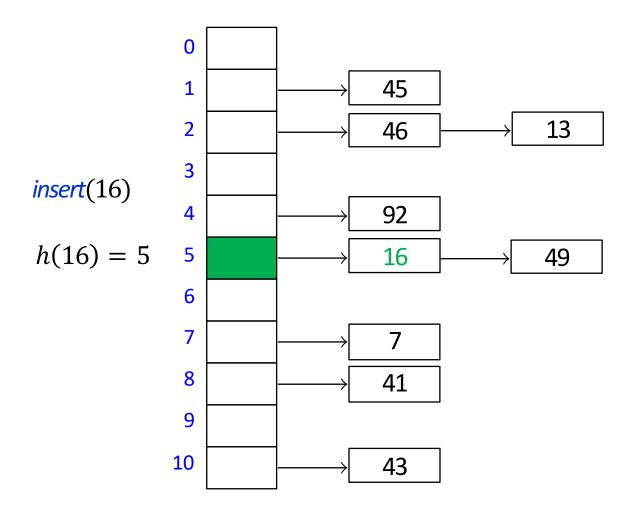


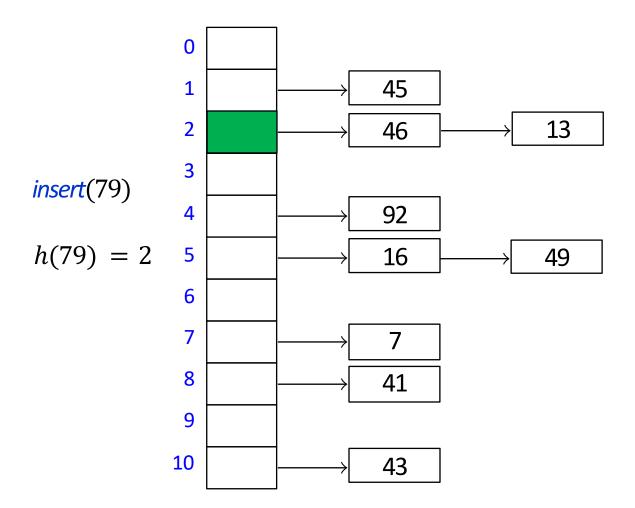


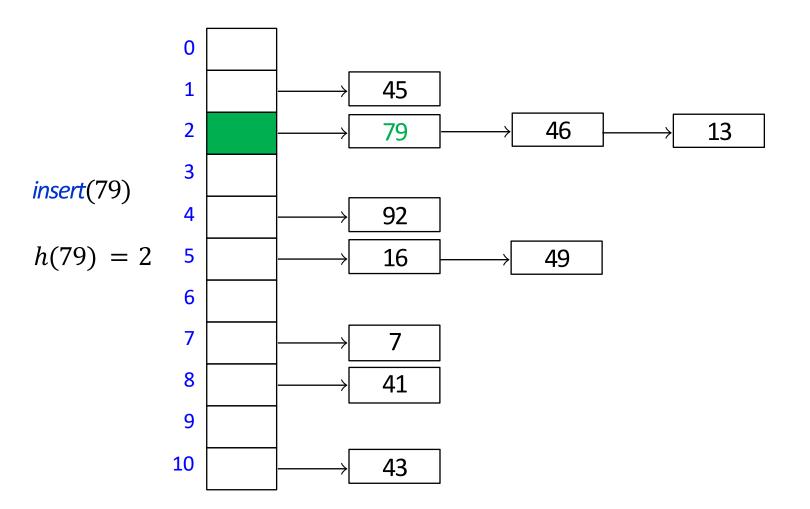






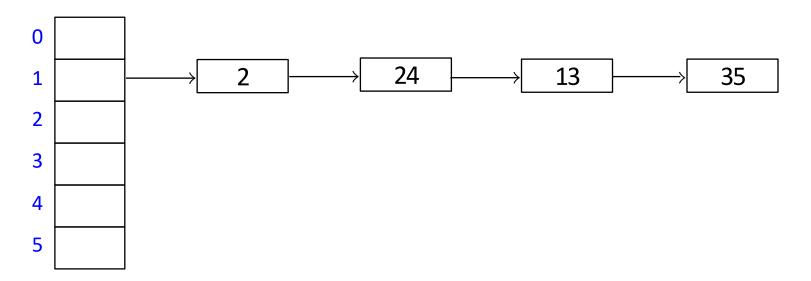






# Hashing with Chaining: Running Time

- *insert* is  $\Theta(1)$ 
  - unordered linked list insertion
- search and delete  $\Theta(1 + \text{length of list at } T[h(k)])$ 
  - **not**  $\Theta($ length of list at T[h(k)]), as list length can be 0
- In the worst case all n items hash to same array index
  - hash table is essentially a list, and *search* and *delete*  $\Theta(n)$



### Hashing with Chaining: Worst Case Running Time

- When can all *n* items hash to the same array index?
  - 1. For bad hash function, i.e. h(k) = 10
  - 2. For *any* hash function, if universe is large enough, there are *n* keys that hash to the same slot

Proof:

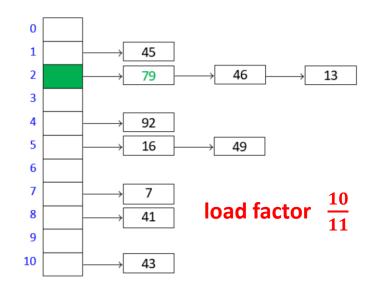
- let  $|U| \ge M(n-1) + 1$
- suppose at most n-1 keys hash to each table slot

$$\begin{array}{c|c}
0 & M-1 \\
\hline
n-1 & n-1 & n-1 & n-1 & n-1 \\
\hline
M(n-1) & & & \\
\end{array}$$

- then there at most M(n-1) elements in U, contradiction
- The user may need to insert n keys that happen to hash to same slot

# Hashing with Chaining: Average Case Runtime?

- Define *load factor*  $\alpha = \frac{n}{M}$ 
  - *n* is the number of items
  - *M* is the size of hash table
- Average bucket size  $= \frac{n}{M} = \alpha$



- This **does not** imply that average-case runtime of search and delete is  $\Theta(1 + \alpha)$ 
  - consider the case when user inserts keys which all hash to the same slot
  - average bucket-size is still α
  - but search and delete nevertheless take  $\Theta(n)$  on average
  - message: when you hear 'average', ask 'average over what'
- To get meaningful average-case bounds, we need some assumptions on hashfunction and keys the user will insert
  - hard to make realistic assumptions
- Easier to switch to *randomized* hashing

# Hashing with Chaining: Randomization

- How can we randomize?
  - cannot insert at a random location, as key k must hash to the hash value h(k)
- Idea: assume the hash-function is chosen randomly from a set of all hash functions
- This is called Uniform Hashing Assumption (UHA): any possible hash-function is equally likely to be chosen
  - not realistic, but this assumption makes analysis easier

**Uniform Hashing Assumption Properties** 

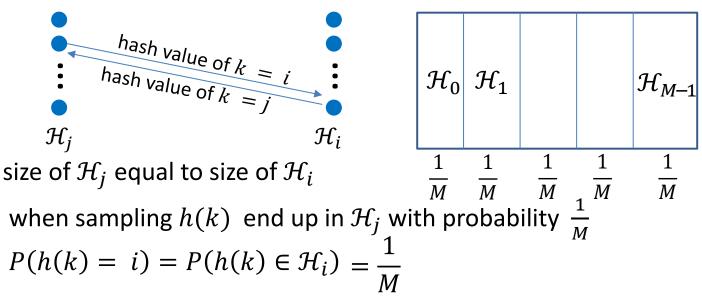
Under UHA (any hash-function is chosen equally likely )

1. 
$$P(h(k) = i) = \frac{1}{M}$$
 for any key k and slot i

Proof:

Let k, i be some key and slot

Let  $\mathcal{H}_j$  (for  $j = 0, \dots M - 1$ ) be set of hash-functions h s.t. h(k) = jFor  $j \neq i$ , one-to-one map between  $\mathcal{H}_i$  and  $\mathcal{H}_i$ 



2. hash-values of any two keys are independent of each other P(h(k) = i and h(k') = j) = P(h(k) = i)P(h(k') = j)Proof: ...

### Hashing with Chaining with Randomly Chosen Hash Function

• 
$$P(h(k) = i) = \frac{1}{M}$$
 for any key k and slot i

load factor  $\alpha = \frac{n}{M}$ 

**Claim**: for any key k, the expected size of bucket T[h(k)] is at most  $1 + \alpha$ **Proof**:

- Let h(k) = i
- Case 1: k is not in the dictionary
  - then each of *n* dictionary items hashes to *i* with probability  $\frac{1}{M}$
  - let  $I_q^i = 1$  if key q hashes to i and  $I_q^i = 0$  otherwise
  - $E[|T[i]|] = E\left[\sum_{\text{keys } q} I_q^i\right] = \sum_{\text{keys } q} E[I_q^i] = \sum_{\text{keys } q} Pr(I_q^i = 1) = \frac{n}{M} \le 1 + \alpha$
- Case 2: k is in the dictionary
  - T(i) definitely has key k
  - the remaining n-1 dictionary items hash to *i* with probability  $\frac{1}{M}$

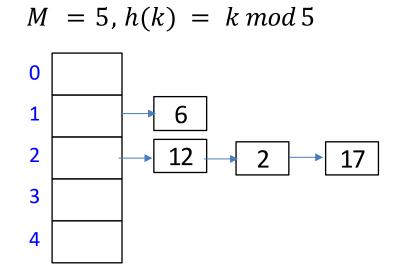
• 
$$E[|T[i]|] = 1 + \frac{n-1}{M} \le 1 + \alpha$$

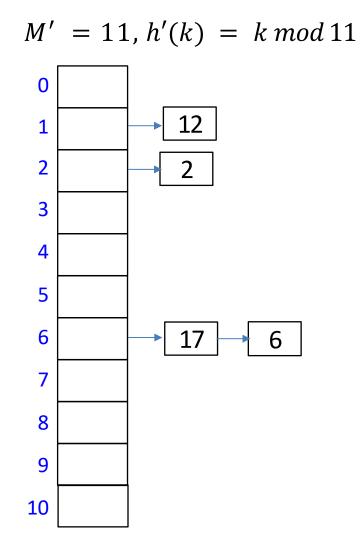
- *search, delete* have runtime  $\Theta(1 + \text{size of bucket } T[h(k)])$
- Expected runtime of search and delete is  $\Theta(1 + \alpha)$ , insert is  $\Theta(1)$

### Load factor and re-hashing

- Load factor  $\alpha = \frac{n}{M}$
- Expected *space* is  $\Theta(M + n) = \Theta(n/\alpha + n)$ , expected *time* is  $\Theta(1 + \alpha)$ 
  - if we maintain  $\alpha \in \Theta(1)$ , expected running time is O(1) and space is  $\Theta(n)$
- Maintaining hash array of appropriate size
  - start with small M
  - during insert/delete, update n
  - if load factor becomes too big, i.e.  $\alpha = \frac{n}{M} > maxLoadF$ , rehash
    - chose new  $M' \approx 2M$
    - find a new random hash function h' that maps U into  $\{0, 1, \dots M' 1\}$
    - create new hash table T' of size M'
    - reinsert each KVP from T into T'
    - update  $T \leftarrow T'$ ,  $h \leftarrow h'$
  - if load factor becomes too small, i.e.  $\alpha = \frac{n}{M} < minLoadF$ , rehash with smaller *M*'
- Rehashing costs  $\Theta(M + n)$  but happens rarely, cost amortized over all operations

### Rehashing when Load Factor Too Large





### **Randomization in Practice**

- Uniform Hashing Assumption is not possible to satisfy in practice
- In practice can chose a random hash function from a certain *family* of hash function
- The following family of functions is often used
  - choose prime number p > M and random  $a, b \in \{0, \dots, p-1\}, a \neq 0$
  - $h(k) = ((ak + b) \mod p) \mod M$
  - can show that the expected runtime of search/delete hold in this case

# Hashing with Chaining Summary

- Rehash so that  $\alpha \in \Theta(1)$
- Rehashing costs  $\Theta(M + n)$  time (plus the time to find a new hash function)
- Rehashing happens rarely enough that we can ignore this term when amortizing over all operations
- We should also re-hash when  $\alpha$  gets too small, so that  $M \in \Theta(n)$  and the space is always  $\Theta(n)$
- The amortized expected cost for hashing with changing is and the space is O(1)
  - assuming uniform hashing and  $\alpha \in \Theta(1)$  throughout
- Theoretically perfect, but slow in practice

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# **Open Addressing**

- Chaining wastes space on links
- Can we resolve collisions in the array *H*?
- Idea: each hash table entry holds only one item, but key k can go in multiple locations
- Probe sequence
  - search and insert follow a probe sequence of possible locations for key k

 $h(k, 0), h(k, 1), h(k, 2), \dots$ 

until an empty spot is found

h(k,2)
h(k,0)
$b(l_{1}, 1)$
h(k, 1)

### **Open Addressing: Linear Probing**

- Linear probing is the simplest method for probe sequence
  - If h(k) is occupied, place item in the next available location
    - probe sequence is
      - h(k,0) = h(k)
      - h(k, 1) = h(k) + 1

• 
$$h(k, 2) = h(k) + 2$$

- etc...
- Assume circular array, i.e. modular arithmetic

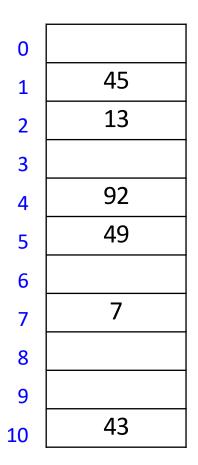
• 
$$h(k,i) = (h(k) + i) \mod M$$

### Linear Probing Example

 $M = 11, h(k) = k \mod 11$ 

*insert*(41)

$$h(41) = 8$$

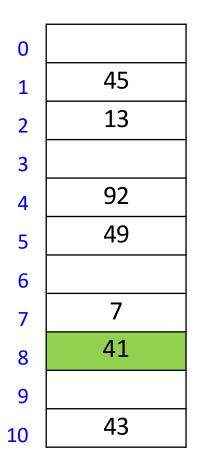


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### Linear Probing Example

 $M = 11, h(k) = k \mod 11$ 

insert(84)

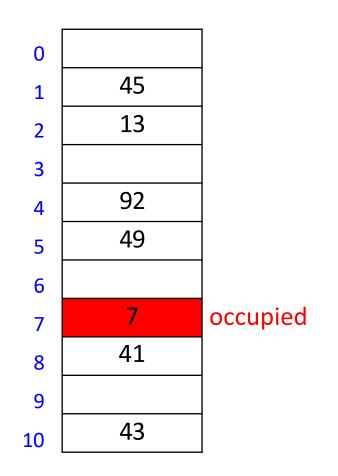
$$h(84) = 7$$

$$\begin{array}{c|ccccc} 0 & & & \\ 1 & 45 \\ 2 & 13 \\ 3 & & \\ 3 & & \\ 4 & 92 \\ 5 & 49 \\ 6 & & \\ 7 & 7 \\ 8 & 49 \\ 6 & & \\ 7 & 7 \\ 8 & 41 \\ 9 & & \\ 10 & 43 \\ \end{array}$$

 $M = 11, h(k) = k \mod 11$ 

insert(84)

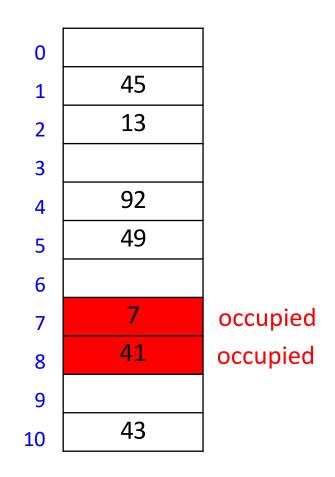
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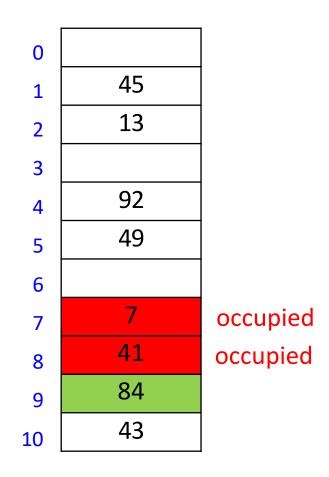
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insert(84)

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# **Linear Probing Formula**

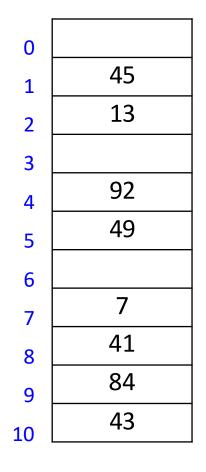
Linear probing explores positions

$$h(k,i) = (h(k) + i) \mod M$$

- for i = 0, 1, ... until an empty location is found
- where h(k) is some hash function

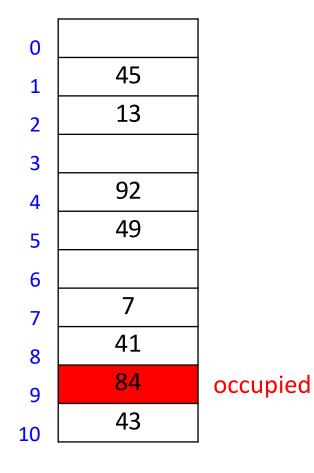
$$M = 11, h(k) = k \mod 11$$
  
 $h(k, i) = (h(k) + i) \mod M$  for sequence  $i = 0, 1, ...$ 

insert(20) h(20) = 9 $h(20, 0) = (9 + 0) \mod 11 = 9$ 



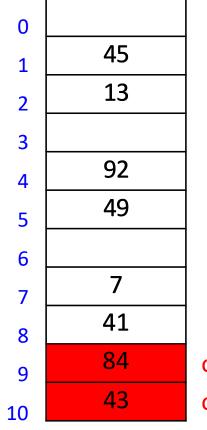
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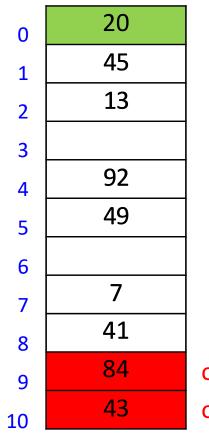
insert(20)h(20) = 9 $h(20, 1) = (9 + 1) \mod 11 = 10$ 



occupied occupied

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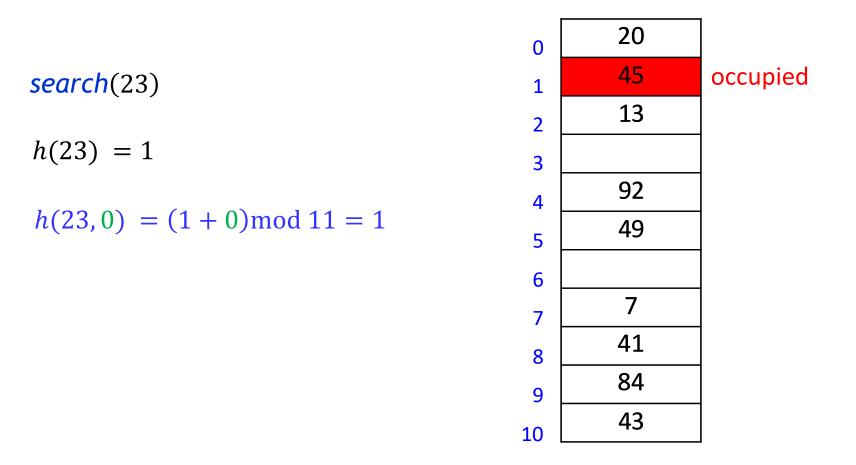
*insert*(20) h(20) = 9 $h(20, 2) = (9 + 2) \mod 11 = 0$ 



occupied occupied

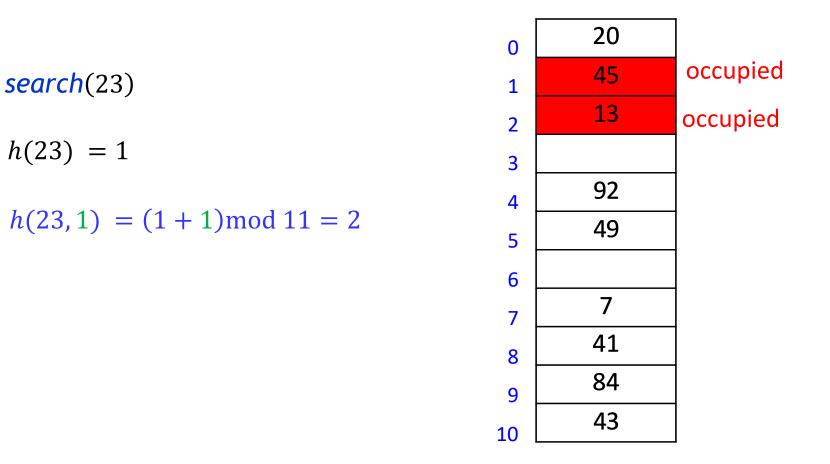
### Linear probing example: Search

$$M = 11, h(k) = k \mod 11$$
  
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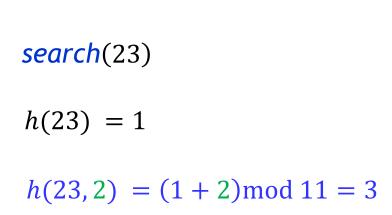
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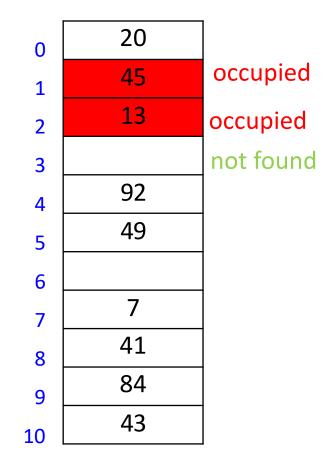
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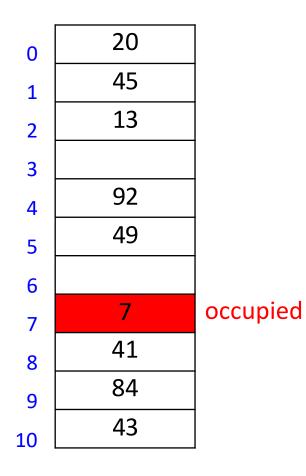
 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

delete(84)h(84) = 7 $h(84, 0) = (7 + 0) \mod 11 = 7$ 

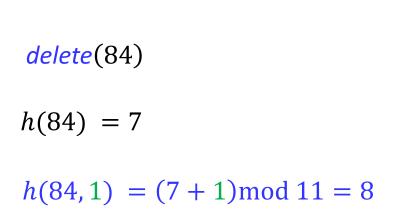
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7	7
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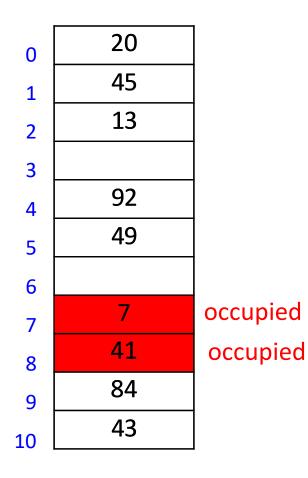
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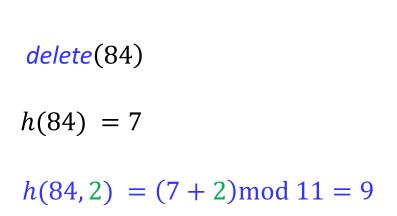


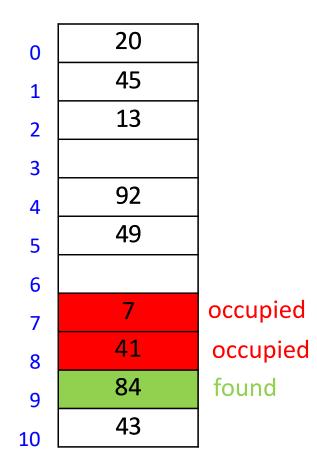
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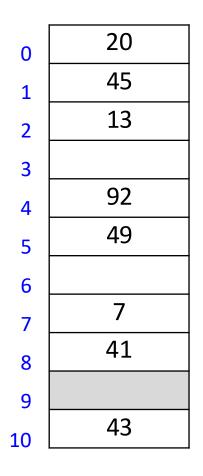
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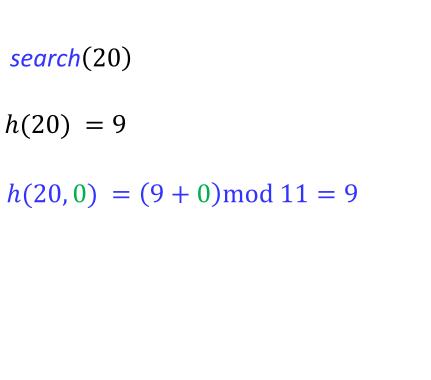


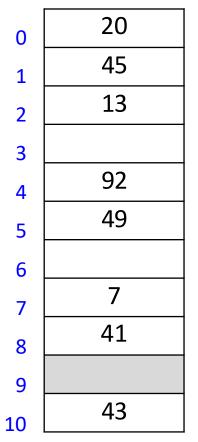
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 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...





not found

# **Open Addressing**

- delete becomes problematic
  - cannot leave an *empty* spot behind
    - next search might otherwise not go far enough
  - Idea: lazy deletion
    - mark spot as *deleted* (rather than *empty*)
    - continue searching past *deleted* spots
    - insert in empty or *deleted* spot
    - keep track of how many items are *deleted* and rehash if there are too many
      - to keep space  $\Theta(n)$

 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

0	20
<i>delete</i> (84) 1	45
2	13
h(84) = 7 3	
$h(84,0) = (7+0) \mod 11 = 7$ 4	92
5	49
$h(84, 1) = (7 + 1) \mod 11 = 8$ <sup>6</sup>	
7	7
$h(84,2) = (7+2) \mod 11 = 9$ 8	41
9	84

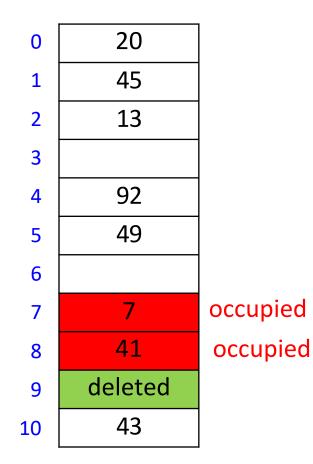
occupied occupied found

43

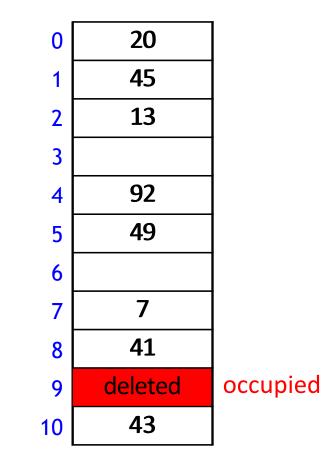
10

 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

delete(84)
h(84) = 7
$h(84,0) = (7+0) \mod 11 = 7$
$h(84, 1) = (7 + 1) \mod 11 = 8$
$h(84,2) = (7+2) \mod 11 = 9$



 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

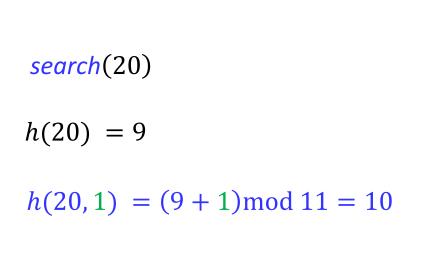


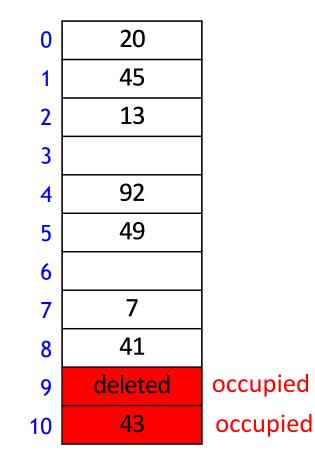
search(20)

h(20) = 9

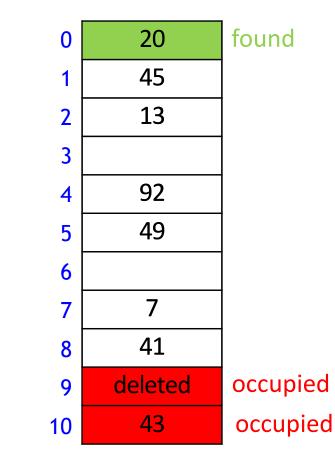
 $h(20,0) = (9+0) \mod 11 = 9$ 

 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...





 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...



search(20)

h(20) = 9

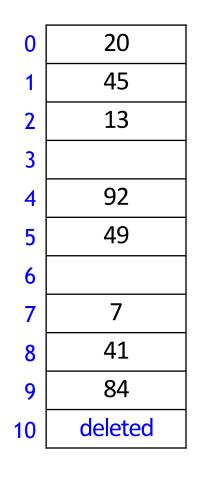
 $h(20,2) = (9+2) \mod 11 = 0$ 

 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

insert(10)

h(10) = 10

 $h(10,0) = (10+0) \mod 11 = 10$ 

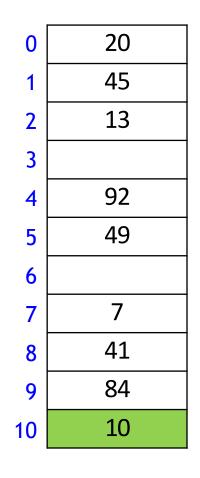


 $M = 11, h(k) = k \mod 11$  $h(k, i) = (h(k) + i) \mod M$  for sequence i = 0, 1, ...

insert(10)

h(10) = 10

 $h(10,0) = (10+0) \mod 11 = 10$ 



# **Open Addressing**

- Can use lazy deletion for other data structures
  - mark as deleted items in AVL tree instead of actual deletion
  - if a lot of items are deleted, rebuild AVL tree
- While in other data structures lazy deletion can be used to improve performance, in probing lazy deletion is required for correct performance

# **Probe Sequence Operations**

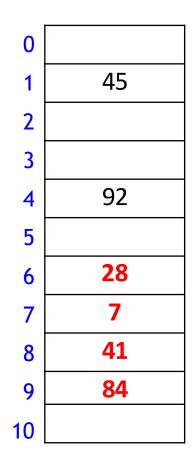
probe-sequence::insert(T, (k, v)) for (i = 0; i < M; i + +)if T [h(k, i)] is empty or deleted T [h(k, i)] = (k, v)return success return failure to insert

- Stop inserting after *M* tries
  - provided  $\alpha < 1$ , linear probing does not need this
  - some probing methods need this
- If insert fails, call rehash

probe-sequence::search(T,k)
for (i = 0; i < M; i + +)
if T [h(k,i)] is empty
return item-not-found
if T [h(k,i)] has key k return T [h(k,i)]
// T [h(k,i)] = deleted or not in the data structure
// therefore keep searching
return item not found</pre>

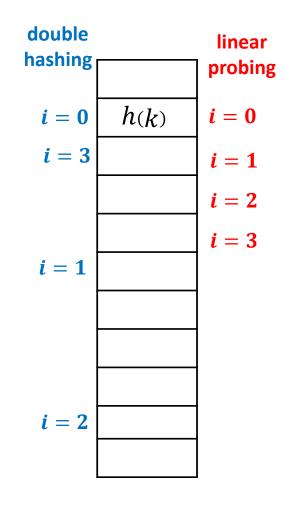
# Linear probing drawbacks

- Entries tend to cluster into contiguous regions
- Many probes for each search, insert, and delete
- How to avoid clustering?



# **Double Hashing Motivation**

- Linear probing attempts inserting into consecutive locations, i.e. step size 1
   h(k) h(k) + 1 h(k) + 2
- To avoid consecutive locations, let each key have its own step size
   h(k) h(k) + 1 · step(k) h(k) + 2 · step(k)
- This helps to avoid the clustering side effect
- For each key k, probe sequence is always the same
- Example
  - for k = 14, probe sequence is always
    - 4, 7, 10, 13
  - for k = 24, probe sequence is always
    - **5**, 10, 15, 20

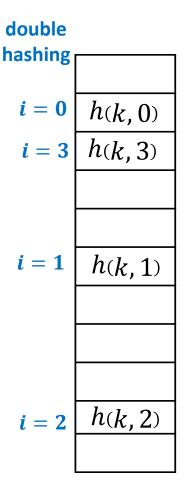


# **Double Hashing**

Double hashing : open addressing with probe sequence

 $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M$  for i = 0,1,...

- Where
  - $h_1$  is a secondary hash function (step size) s.t.  $h_1(k) \neq 0$
  - *h*<sub>1</sub>(*k*) is relative prime with *M* for all keys *k*
    - otherwise probe-sequence does not explore the entire hash table
    - easiest to choose M prime, and ensure  $h_1(k) < M$
- Double hashing with a good secondary hash function does not cause the bad clustering produced by linear probing
- search, insert, delete work as in linear probing, but with this different probe sequence
  - linear probing is a special case of double hashing with  $h_1(k) = 1$



#### Independent Hash functions

- When two hash functions  $h_0$ ,  $h_1$  are required, they should be independent  $P(h_0(k) = i, h_1(k) = j) = P(h_0(k) = i) P(h_1(k) = j)$
- Using two modular hash-functions may lead to dependencies
- Better idea: use *multiplicative method* for second hash function
  - let 0 < *A* < 1

• 
$$h(k) = \lfloor M(kA - \lfloor kA \rfloor) \rfloor$$

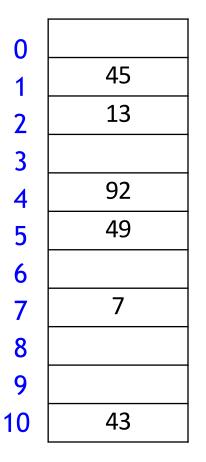
 $0 \leq \text{fractional part of } kA < 1$ 

 $0 \le M \cdot (\text{fractional part of } kA) < M$ 

- Example: M = 11, A = 0.2
  - $h(34) = [11 \cdot (34 \cdot 0.2 [34 \cdot 0.2])] = [11 \cdot (6.8 [6.8])] = [11 \cdot 0.8] = 8$
- Multiplying with A scrambles the keys
  - should use at least  $\log |U| + \log |M|$  bits of A
- $A = \varphi = \frac{\sqrt{5}-1}{2} \approx 0.618033988749$  works well
- For double hashing, to ensure 0 < h(k) < M, use  $h_1(k) = \lfloor (M - 1)(kA - \lfloor kA \rfloor) \rfloor + 1$

for table size  $M - 1: 0 \le \text{values} \le M - 1$ 

 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 



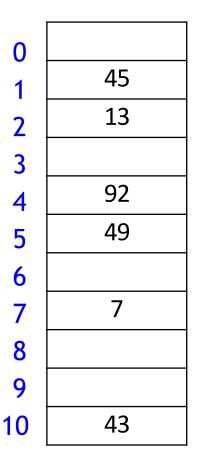
 $\sqrt{5}-1$ 

2

 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

insert(41)  

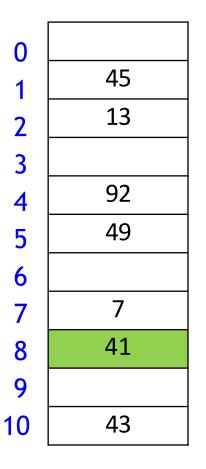
$$h_0(41) = 8$$
  
 $h_1(41) = 4$   
 $h(41, 0) = (8 + 0 \cdot 4) \mod 11 = 8$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

insert(41)  

$$h_0(41) = 8$$
  
 $h_1(41) = 4$   
 $h(41, 0) = (8 + 0 \cdot 4) \mod 11 = 8$ 

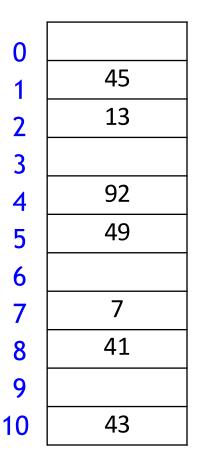


 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

7

insert(194)  

$$h_0(194) = 7$$
  
 $h_1(194) = 9$   
 $h(194, 0) = (7 + 0 \cdot 9) \mod 11 =$ 

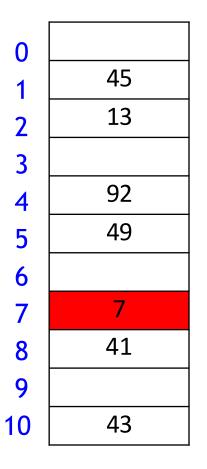


 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

7

insert(194)  

$$h_0(194) = 7$$
  
 $h_1(194) = 9$   
 $h(194, 0) = (7 + 0 \cdot 9) \mod 11 =$ 

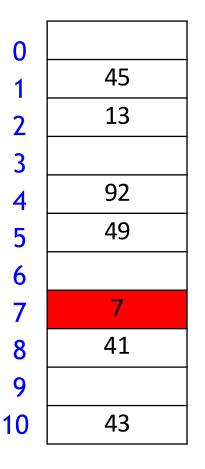


 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

5

insert(194)  

$$h_0(194) = 7$$
  
 $h_1(194) = 9$   
 $h(194, 1) = (7 + 1 \cdot 9) \mod 11 =$ 

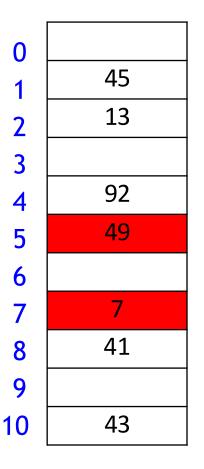


 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

5

insert(194)  

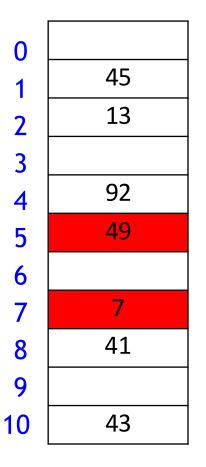
$$h_0(194) = 7$$
  
 $h_1(194) = 9$   
 $h(194, 1) = (7 + 1 \cdot 9) \mod 11 =$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

insert(194)  

$$h_0(194) = 7$$
  
 $h_1(194) = 9$   
 $h(194, 2) = (7 + 2 \cdot 9) \mod 11 = 3$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 10(\varphi k - \lfloor \varphi k \rfloor) \rfloor + 1$  $h(k,i) = (h_0(k) + i \cdot h_1(k)) \mod M \text{ for sequence } i = 0,1, \dots$ 

$$insert(194)$$

$$h_0(194) = 7$$

$$h_1(194) = 9$$

$$h(104, 2) = (7 + 2, 9) \mod 11 = 7$$

 $h(194, 2) = (7 + 2 \cdot 9) \mod 11 = 3$ 

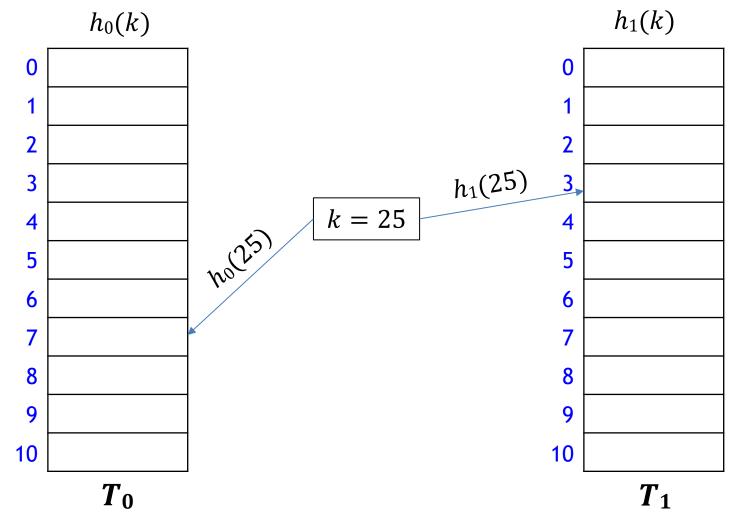


# Outline

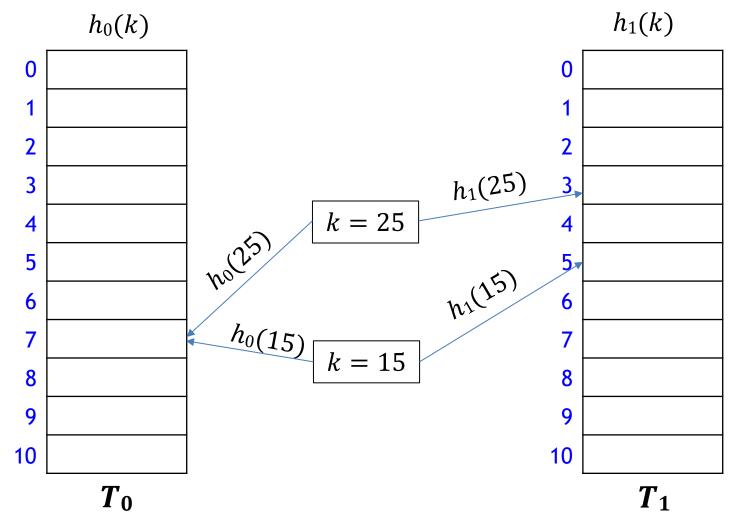
- Dictionaries via Hashing
  - Hashing Introduction
  - Hashing with Chaining
  - Open Addressing
    - probe Sequences

#### cuckoo hashing

Hash Function Strategies

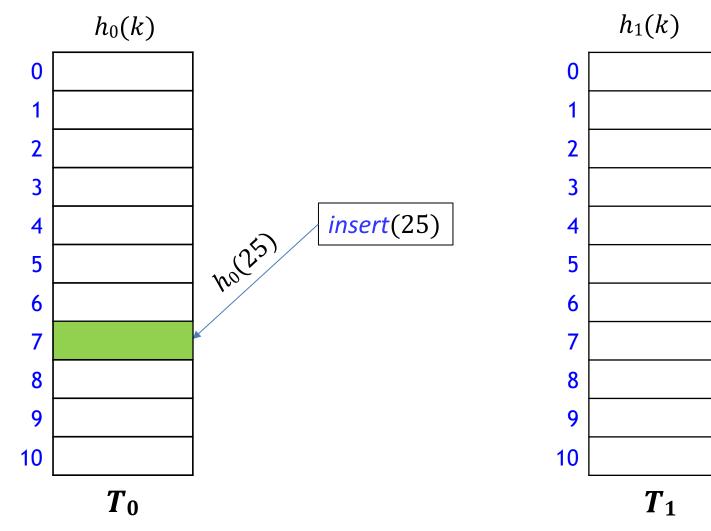


• Main idea: An item with key k can be only at  $T_0[h_0(k)]$  or  $T_1[h_1(k)]$ 

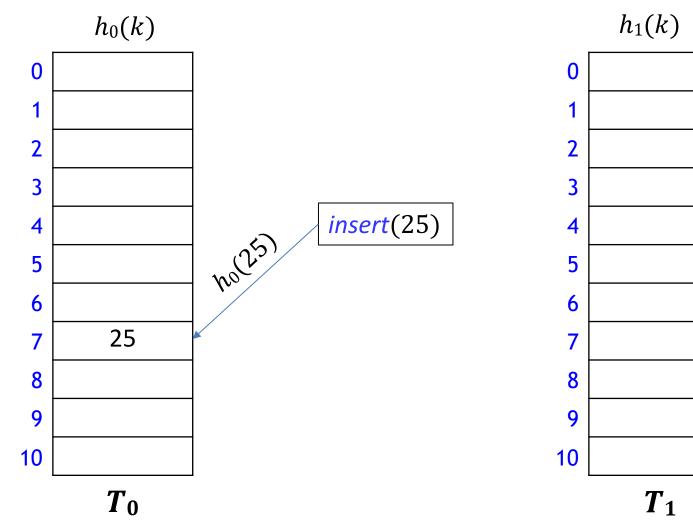


• Main idea: An item with key k can be only at  $T_0[h_0(k)]$  or  $T_1[h_1(k)]$ 

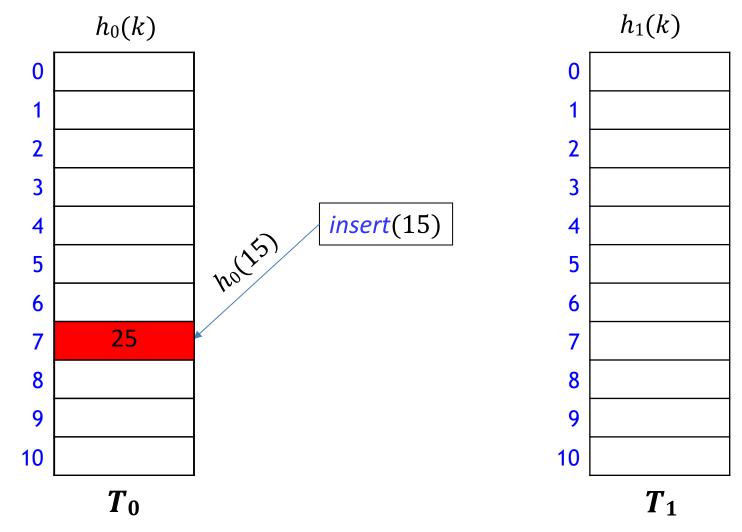
• *search* and *delete* take O(1) time



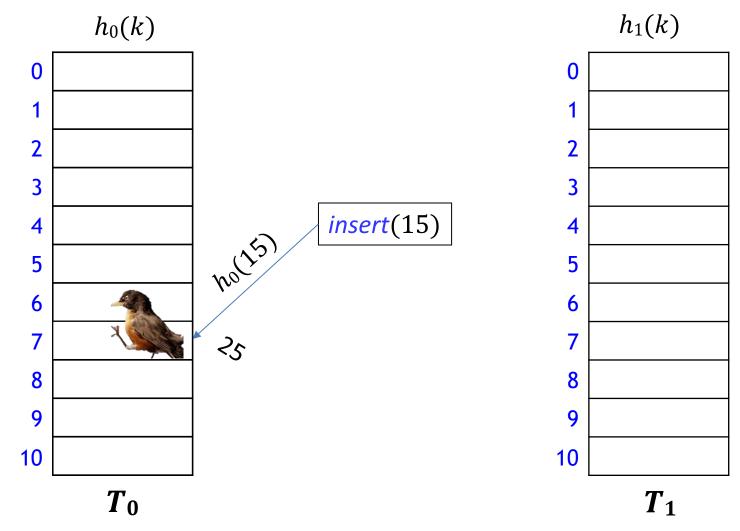
How to insert?



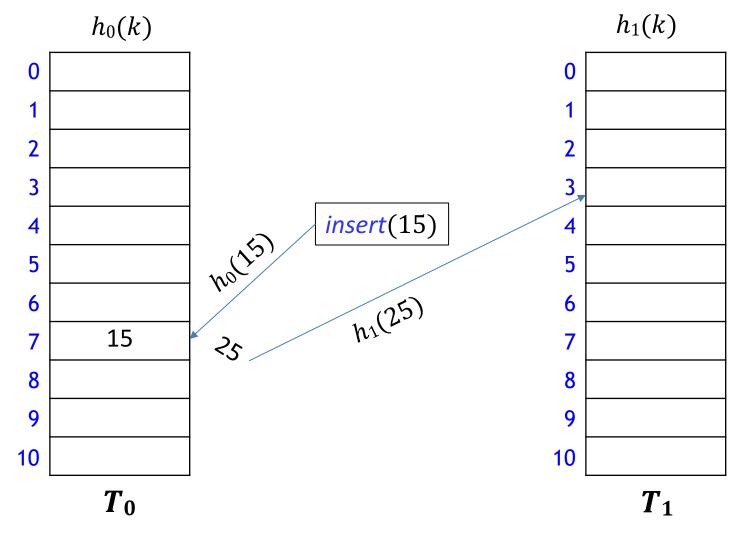
How to insert?



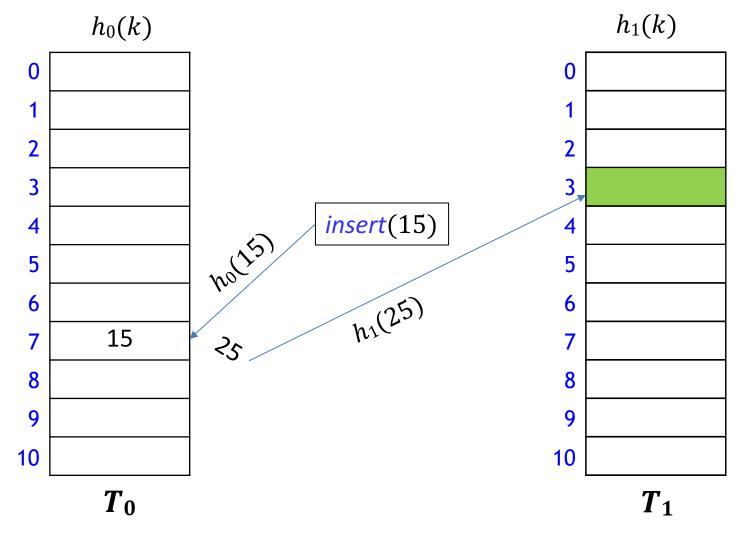
• How to insert k when  $h_0(k)$  is already occupied?



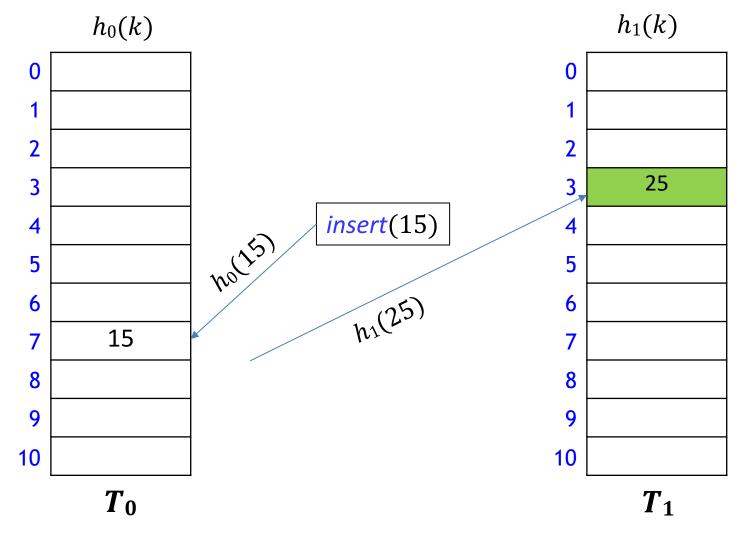
• How to insert k when  $h_0(k)$  is already occupied?



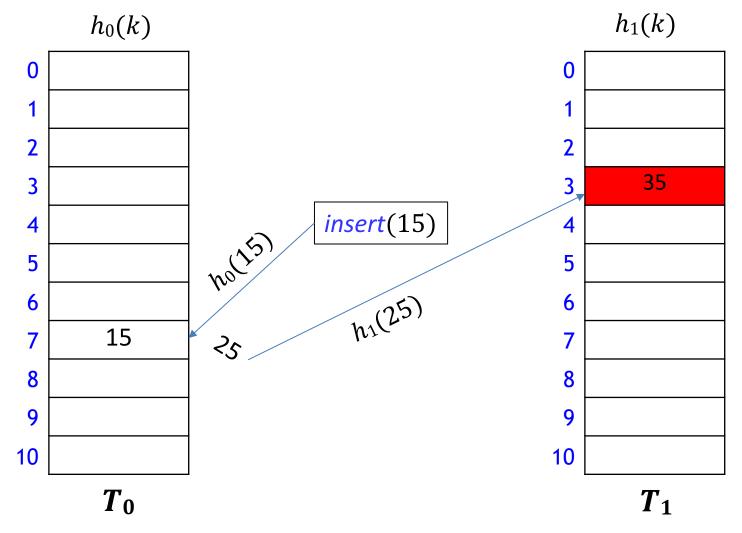
• How to insert k when  $h_0(k)$  is already occupied?



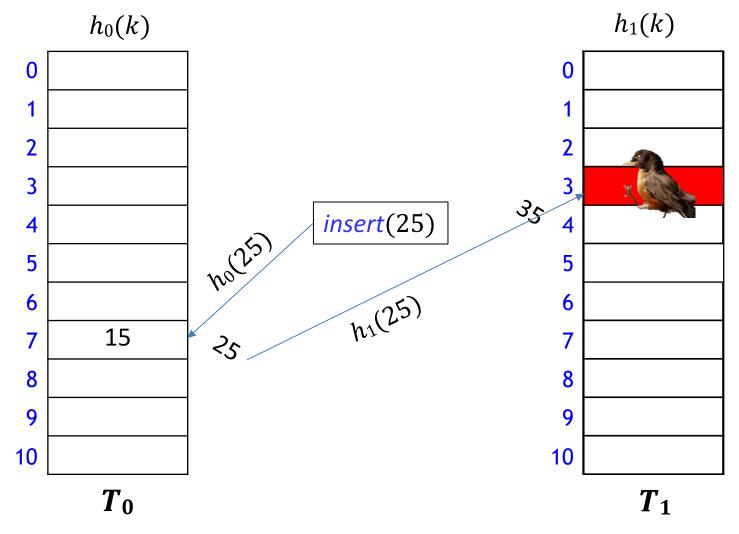
• How to insert k when  $h_0(k)$  is already occupied?



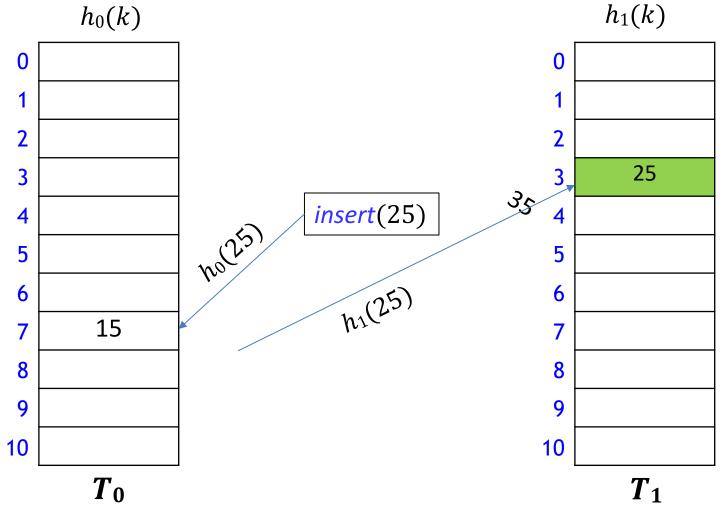
• How to insert k when  $h_0(k)$  is already occupied?



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• How to insert k when  $h_0(k)$  is already occupied?

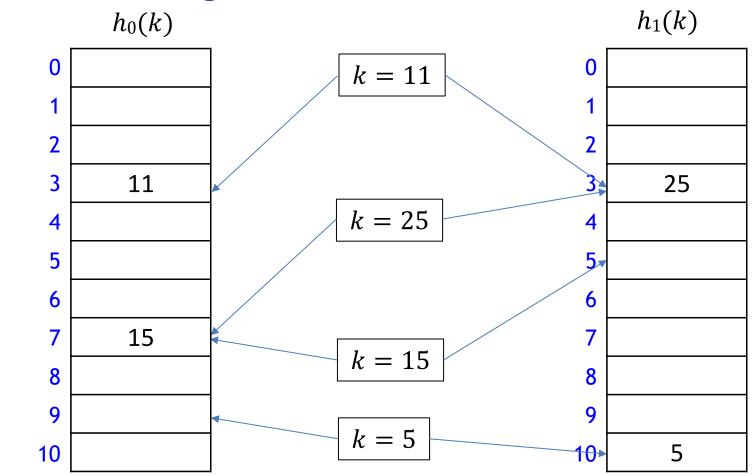


- Continue until all items placed, or *failure*
  - rehash if failure

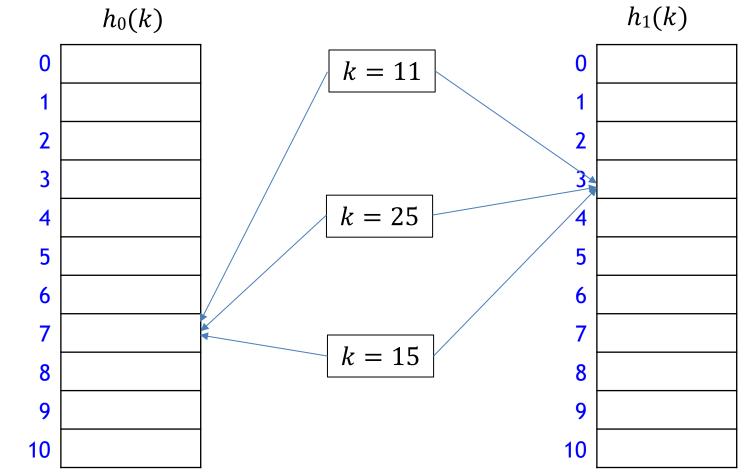
# Cuckoo Hashing [Pagh & Rodler, 2001]



- Use independent hash functions  $h_0$ ,  $h_1$  and two tables  $T_0$ ,  $T_1$
- Key k can be only at  $T_0[h_0(k)]$  or  $T_1[h_1(k)]$ 
  - search and delete take constant time
  - *insert* always initially puts key k into  $T_0[h_0(k)]$ 
    - evict item that my have been there already
    - if so, evicted item k' is inserted at T<sub>1</sub>[h<sub>1</sub>(k')]
    - may lead to a loop of evictions
    - can show that if insertion is possible, then there are at most 2n evictions
    - so abort after too many attempts



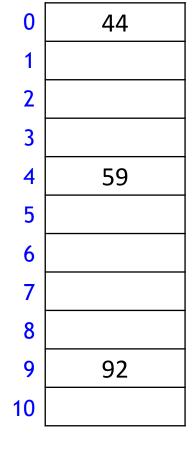
- Intuitively
  - each key has 2 locations (locations can coincide)
  - try to "match" keys to locations so that everyone is placed

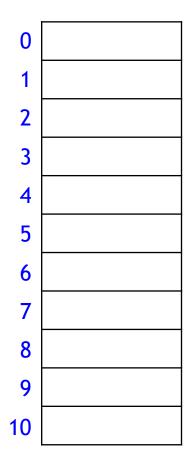


- Sometimes no solution for the "matching" problem
  - would loop infinitely if not stopped by force

 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

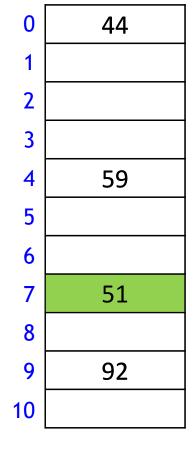
insert(51) i = 0 k = 51 $h_0(k) = 7$ 

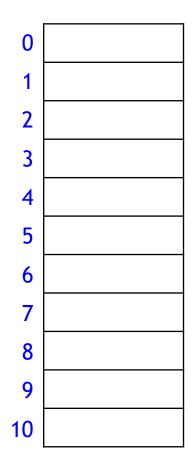




 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

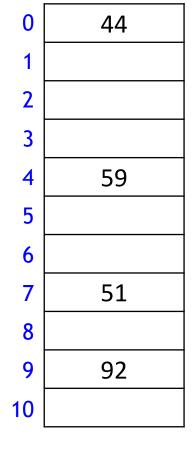
insert(51) i = 0 k = 51 $h_0(k) = 7$ 

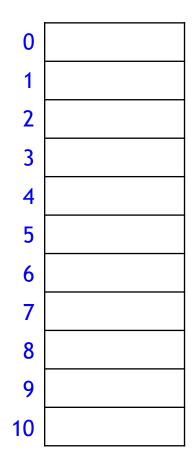




 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

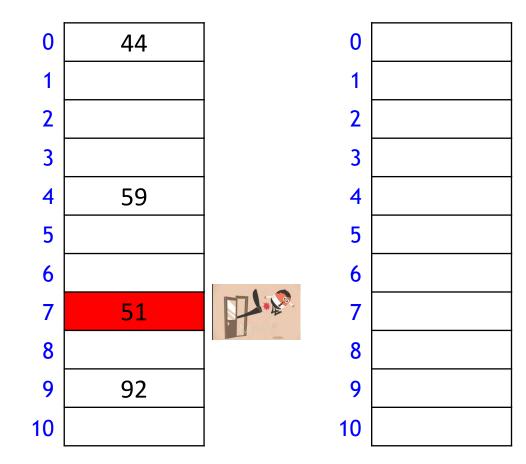
insert(95) i = 0 k = 95 $h_0(k) = 7$ 





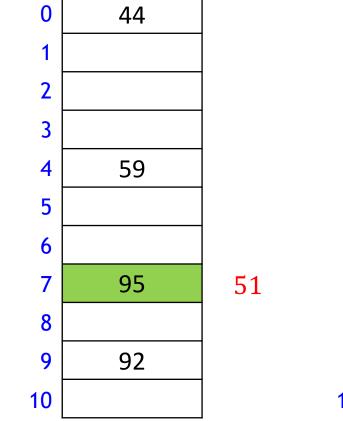
 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

insert(95) i = 0 k = 95 $h_0(k) = 7$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

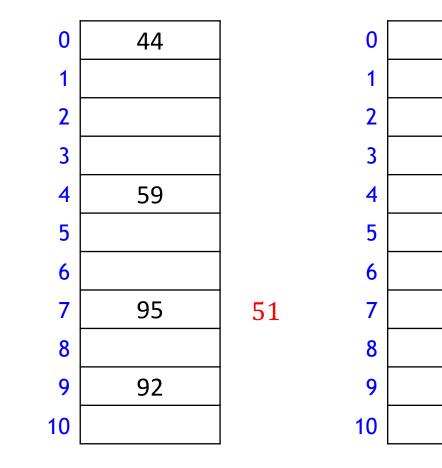
insert(95) i = 0 k = 95 $h_0(k) = 7$ 





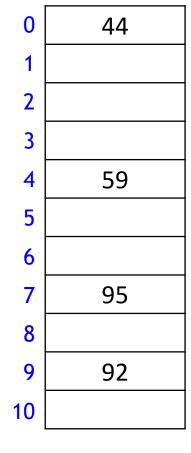
 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

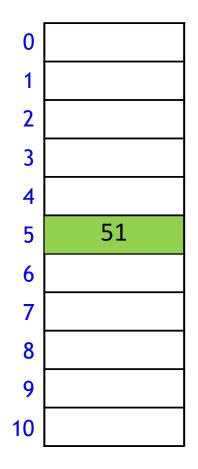
insert(95) i = 1 k = 51 $h_1(k) = 5$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

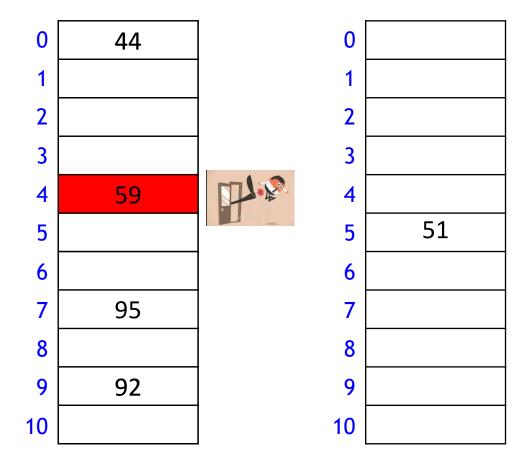
insert(95) i = 1 k = 51 $h_1(k) = 5$ 





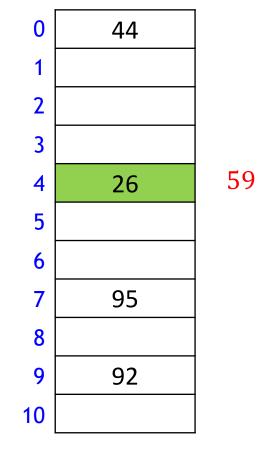
 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

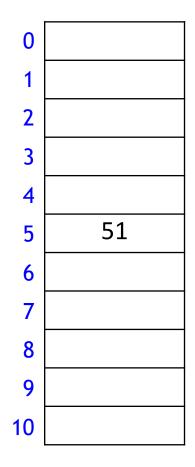
insert(26)i = 0k = 26 $h_0(k) = 4$ 



 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

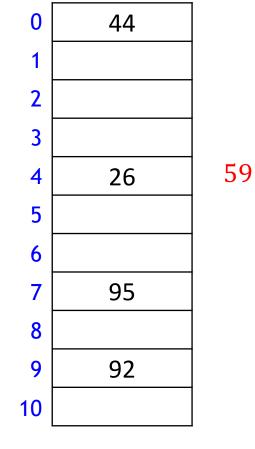
insert(26)i = 0k = 26 $h_0(k) = 4$ 

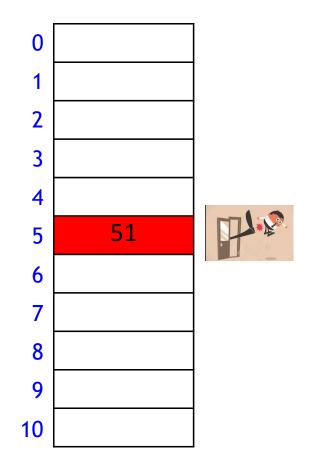




 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

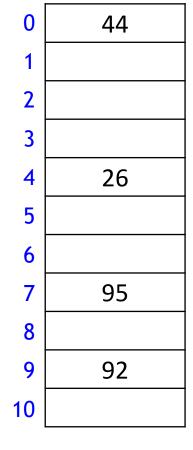
insert(26) i = 1 k = 59 $h_1(k) = 5$ 

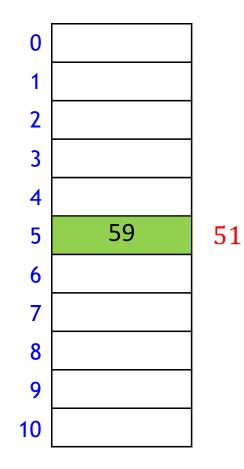


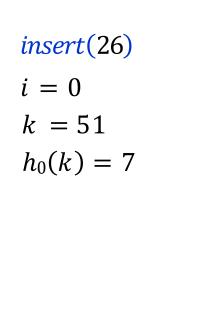


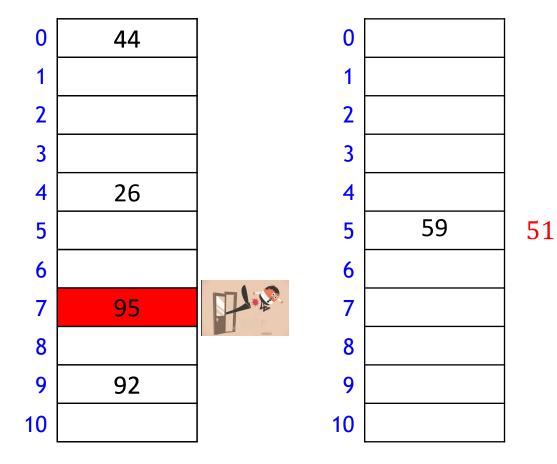
 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

insert(26) i = 1 k = 59 $h_1(k) = 5$ 



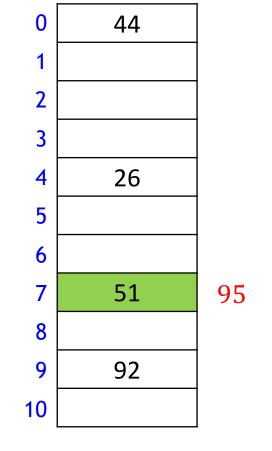


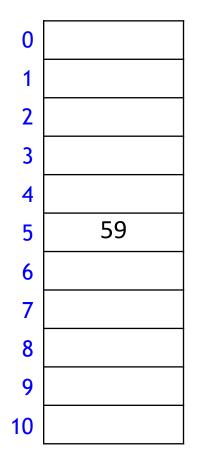




 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

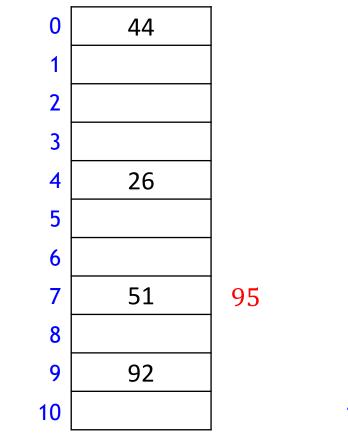
insert(26) i = 0 k = 51 $h_0(k) = 7$ 

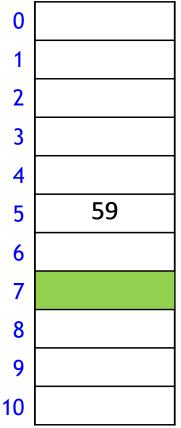




 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

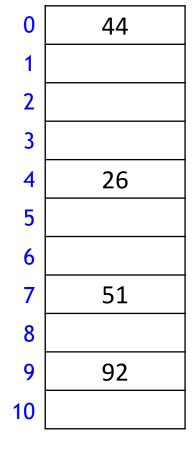
insert(26) i = 1 k = 95 $h_1(k) = 7$ 

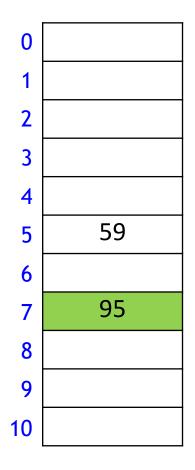




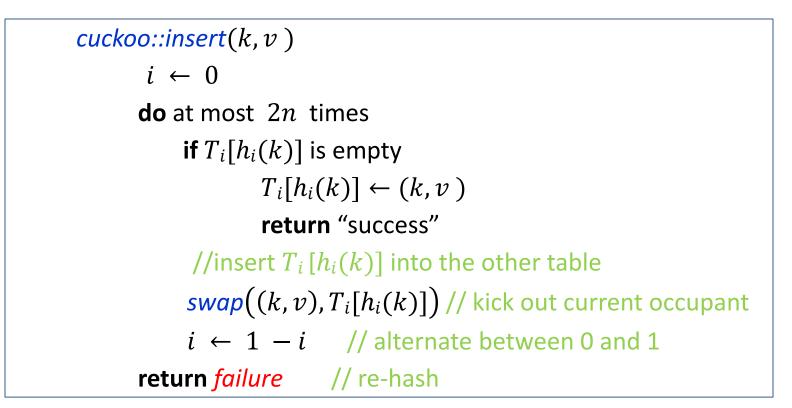
 $M = 11, h_0(k) = k \mod 11, h_1(k) = \lfloor 11(\varphi k - \lfloor \varphi k \rfloor) \rfloor$ 

insert(26) i = 1 k = 95 $h_1(k) = 7$ 



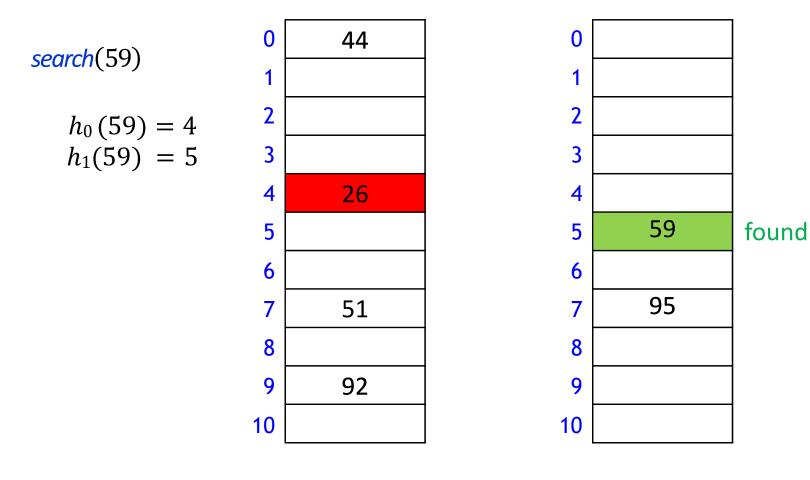


## Cuckoo Hashing: Insert Pseudocode

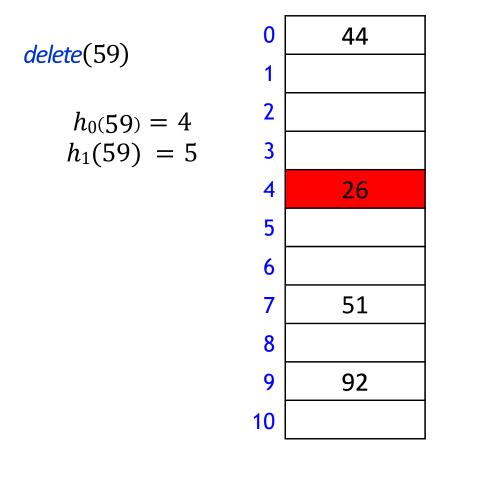


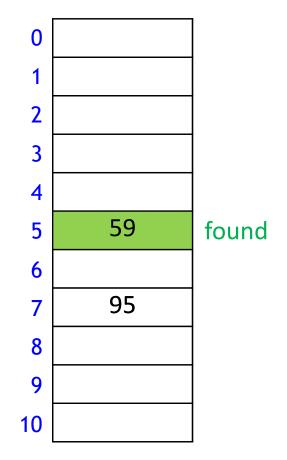
- Practical tip
  - do not wait for 2n unsuccessful tries to declare failure
  - In practice, declare failure much earlier than 2n

#### Cuckoo hashing: Search

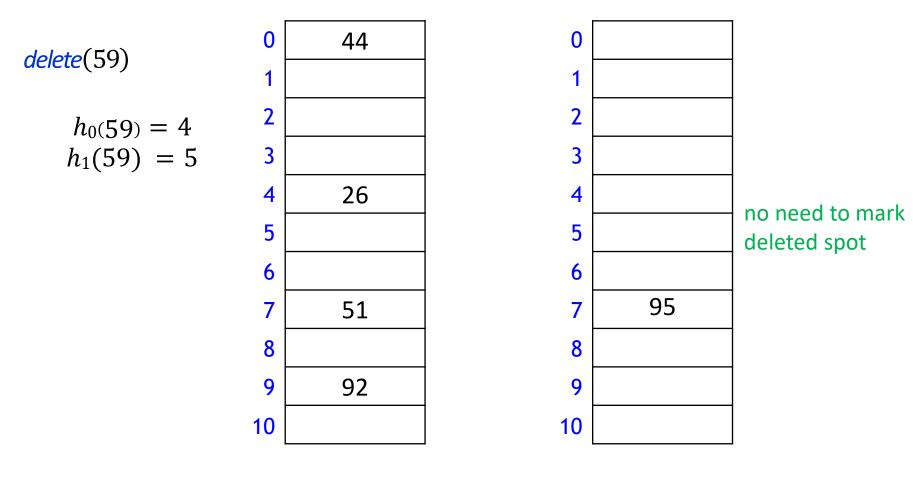


#### Cuckoo hashing: Delete





#### Cuckoo hashing: Delete



# Cuckoo hashing discussion

- Load factor  $\alpha = n/(\text{size of } T_0 + \text{size of } T_1)$
- Can show that if the load factor is small enough, then insertion has
   O(1) expected time
  - this requires  $\alpha < 1/2$
  - so wasted space
- Can show expected space is O(n)
- There are many variations of cuckoo hashing
  - two hash tables do not have to be of the same size
  - two hash tables can be combined into one
  - more flexible when inserting: always consider both possible positions
  - Use k > 2 allowed locations
    - *k* tables or *k* hash functions

# Running Time of Open Addressing Strategies

- For any open addressing scheme, we *must* have  $\alpha \leq 1$  (why?)
- For analysis, require  $0 < \alpha < 1$  , for Cuckoo hashing require  $\alpha < 1/2$ 
  - not arbitrarily close
- Under these restrictions and the Universal Hashing Assumption
  - All strategies have O(1) expected time for search, insert, delete
  - Cuckoo hashing has O(1) worst case for search, delete
  - Probe sequence use O(n) worst case space
  - Cuckoo hashing uses O(n) expected space
- For any hashing, the worst case runtime is  $\Theta(n)$  for insert
- In practice, double hashing is the most popular
  - Or cuckoo hashing if there are many more searches than insertions

## Outline

- Dictionaries via Hashing
  - Hashing Introduction
  - Hashing with Chaining
  - Open Addressing
    - probe Sequences
    - cuckoo hashing
  - Hash Function Strategies

# **Choosing Good Hash Function**

- Satisfying the uniform hashing assumption is impossible
  - too many hash functions and for most, computing h(k) is not cheap for most of them
- Two ways to compromise
  - 1. Deterministic: hope for a good performance by choosing a hash function that is
    - unrelated to any possible patterns in the data
    - depends on all parts of the key
  - 2. Randomized: choose randomly among a limited set of functions
    - but aim for  $P(\text{two keys collide}) = \frac{1}{M}$ 
      - this is enough to prove expected runtime bounds for chaining

## **Deterministic Hash Functions**

- We saw two basic methods (for integer keys)
- Modular method:  $h(k) = k \mod M$ 
  - chose *M* to be a prime
  - Means finding a suitable prime quickly when re-hashing
    - can be done in O(Mlog log n) time
      - no details
- Multiplicative method:  $h(k) = \lfloor M(kA \lfloor kA \rfloor) \rfloor$ 
  - multiplying with 0 < A < 1 is used to scramble keys</li>
  - so A should be irrational to avoid patterns in keys
  - experiments show that good scrambling is achieved when A is the golden ratio
  - should use at least  $\log|U| + \log M$  bits of  $\log|U|$

# Randomized Hash Functiosn: Carter-Wegman's Universal Hashing

- Randomization that uses easy-to-compute hash functions
  - Requires: all keys are in  $\{0, \dots p-1\}$  for some (big) prime p
  - At initialization and whenever rehash
    - choose number M < p</li>
    - *M* equal to some power of 2 is ok
    - choose (and store) two random numbers  $a, b \in \{0, \dots, p-1\}$ 
      - b = random(p)
      - a = 1 + random(p-1)
        - so that  $a \neq 0$
    - Use as hash function

 $h(k) = ((ak + b) \bmod p) \bmod M$ 

- can be computed quickly
- can prove that two keys collide with probability at most  $\frac{1}{M}$ 
  - enough to prove the expected runtime bounds for chaining, although uniform hashing assumption is not satisfied

# **Multi-dimensional Data**

- May need multi-dimensional non integer keys
  - example: strings in  $\Sigma^*$
- 1. Construct  $f(w) \in N$  for converting string w to integer
  - should depend on all parts of the key
  - ASCII representation of APPLE is (65, 80, 80, 76, 69)
  - simple addition: f(APPLE) = 65 + 80 + 80 + 76 + 69
  - many collisions, 'stop'='tops'='pots'
  - polynomial accumulation works better
    - choose radix R, e.g. R = 255
    - $f(APPLE) = 65R^4 + 80R^3 + 80R^2 + 76R^1 + 69R^0$
    - compute in O(|w|) time with Horner's rule
    - either ignoring overflow

 $f(APPLE) = \left( \left( (65R + 80)R + 80 \right)R + 76 \right)R + 69$ 

- or apply *mod M* after each addition
- 2. Now apply any hash function, such as  $h(w) = f(w) \mod M$

## Hashing vs. Balanced Search Trees

- Advantages of Balanced Search Trees
  - O(log n) worst-case operation cost
  - does not require any assumptions, special functions, or known properties of input distribution
  - predictable space usage (exactly n nodes)
  - never need to rebuild the entire structure
  - supports ordered dictionary operations (rank, select etc.)
- Advantages of Hash Tables
  - O(1) expected time operations (if hashes well-spread and load factor small)
  - can choose space-time trade-off via load factor
  - cuckoo hashing achieves O(1) worst-case for search & delete