## CS 341: Algorithms Lec 05: Breadth First Search

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## Goals

### This module:

- $\bullet \ basics \ on \ undirected \ graphs$
- undirected BFS and applications (shortest paths, bipartite graphs, connected components)
- undirected DFS and applications (cut vertices)
- basics on **directed graphs**
- directed DFS and applications (testing for cycles, topological sort, strongly connected components)

## Undirected graphs

### **Definition, notation:** a graph G is pair (V, E):

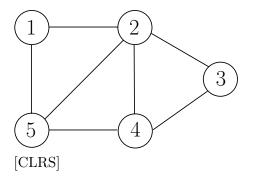
- $\bullet~V$  is a finite set, whose elements are called vertices
- E is a finite set, whose elements are unordered pairs of distinct vertices, and are called edges.

Convention: n is the number of vertices, m is the number of edges.

### Data structures:

- adjacency list: an array A[1..n] s.t. A[v] is the linked list of all edges connected to v.
  2m list cells, total size ⊖(n + m), but testing if an edge exists is not O(1)
- adjacency matrix: a (0,1) matrix M of size n × n, with M[v, w] = 1 iff {v, w} is an edge.
  size ⊖(n<sup>2</sup>), but testing if an edge exists is O(1)

## Representations of graphs



Connected graphs, path, cycles, trees

### **Definition:**

- path: a sequence v<sub>1</sub>,..., v<sub>k</sub> of vertices, with {v<sub>i</sub>, v<sub>i+1</sub>} in E for all i.
  k = 1 is OK.
- connected graph: G = (V, E) such that for all v, w in V, there is a path v → w
- cycle: a path  $v_1, \ldots, v_k, v_1$  with  $k \geq 3$  and  $v_i$ 's pairwise distinct
- tree: a connected graph without any cycle
- rooted tree: a tree with a special vertex called root

Subgraphs, connected components

**Definition:** 

- subgraph of G = (V, E): a graph G' = (V', E'), where
  - $\blacktriangleright V' \subset V$
  - $E' \subset E$ , with all edges E' joining vertices from V'
- connected component of G = (V, E)
  - $\blacktriangleright$  a connected subgraph of G
  - $\blacktriangleright$  that is not contained in a larger connected subgraph of G

Let  $G_i = (V_i, E_i), i = 1, ..., s$  be the connected components of G = (V, E).

- the  $V_i$ 's are a partition of V, with  $\sum_i n_i = n$   $n_i = |V_i|$
- the  $E_i$ 's are a partition of E, with  $\sum_i m_i = m$   $m_i = |E_i|$

# **Breadth-first search**

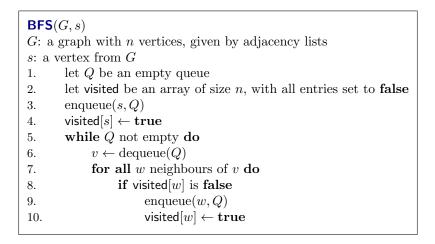
## Breadth-first exploration Idea

### Activity

Assume we are looking for a person in a social network and we don't want to use the usual search. What is a possible strategy?

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## Breadth-first exploration of a graph



## Complexity

### Anaysis:

- each vertex is enqueued at most once
- so each vertex is dequeued at most once
- so each adjacency list is read at most once

For all v, write  $d_v$  = number of neighbours of v = length of A[v] = **degree** of v.

Then total cost at step 7 is

$$O\left(\sum_v d_v\right) = O(m)$$

cf. the adjacency array A has 2m cells (handshaking lemma) Total: O(n + m)

### True/False

For all vertices v, there is a path  $s \rightsquigarrow v$  in G if and only if visited[v] is true at the end.

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### Correctness

#### Claim

For all vertices v, if  $\mathsf{visited}[v]$  is true at the end, there is a path  $s \rightsquigarrow v$  in G

**Proof.** Let  $s = v_0, \ldots, v_K$  be the vertices for which visited is set to true, in this order. We prove: for all *i*, there is a path  $s \rightsquigarrow v_i$ , by induction.

- OK for i = 0
- suppose true for  $v_0, \ldots, v_{i-1}$ .

when visited  $[v_i]$  is set to true, we are examining the neighbours of a certain  $v_j$ , j < i.

by assumption, there is a path  $s \rightsquigarrow v_j$ 

because  $\{v_j, v_i\}$  is in E, there is a path  $s \rightsquigarrow v_i$ 

### Correctness

#### Claim

For all vertices v, if there is a path  $s \rightsquigarrow v$  in G, visited[v] is true at the end

**Proof.** Let  $v_0 = s, \ldots, v_k = v$  be a path  $s \rightsquigarrow v$ . We prove visited  $[v_i]$  is true for all i, by induction.

- visited[v<sub>0</sub>] is true
- if visited[vi] is true, we will examine all neighbours u of vi so at the end of Step 7, all visited[u] will be true, for u neighbour of vi

in particular, visited $[v_{i+1}]$  will be true

### Correctness

#### Lemma

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For all vertices v, there is a path s \rightsquigarrow v in G if and only if visited[v] is true at the end
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### Applications

- testing if there is a path  $s \rightsquigarrow v$
- testing if G is connected

in O(n+m).

#### Exercise

For a connected graph,  $m \ge n-1$ .

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## Keeping track of parents and levels

$\boxed{BFS(G,s)}$	
1.	let $Q$ be an empty queue
2.	let parent be an array of size $n$ , with all entries set to <b>NIL</b>
3.	let level be an array of size $n$ , with all entries set to $\infty$
4.	enqueue(s, Q)
5.	$parent[s] \leftarrow s$
6.	$level[s] \leftarrow 0$
7.	while $Q$ not empty do
8.	$v \leftarrow \text{dequeue}(Q)$
9.	for all $w$ neighbours of $v$ do
10.	if parent $[w]$ is <b>NIL</b>
11.	$\operatorname{enqueue}(w,Q)$
12.	$parent[w] \leftarrow v$
13.	$level[w] \leftarrow level[v] + 1$

## BFS tree

### **Definition:** the **BFS tree** T is the subgraph made of:

- all w such that  $parent[w] \neq NIL$ .
- all edges  $\{w, parent[w]\}$ , for w as above (except w = s)

#### Claim

The BFS tree T is a tree

**Proof:** by induction on the vertices for which  $\mathsf{parent}[v]$  is not **NIL** 

- when we set  $parent[s] \leftarrow s$ , only one vertex, no edge.
- suppose true before we set  $parent[w] \leftarrow v$

v was in T before, w was not, so we add one vertex w and one edge  $\{v,w\}$  to T

so  ${\cal T}$  remains a tree

**Remark:** we make it a **rooted** tree by choosing s as root

## Shortest paths from the BFS tree

### Sub-claim 1

The levels in the queue are non-decreasing

**Proof:** Exercise.

#### Sub-claim 2

For all vertices u,v, if there is an edge  $\{u,v\},$  then  $\mathsf{level}[v] \le \mathsf{level}[u] + 1.$ 

### Proof:

- if we dequeue v before  $u,\, \mathsf{level}[v] \leq \mathsf{level}[u]$  sub-claim 1
- if we dequeue u before v, the parent of v is either u, or was dequeued before u

in any case,  $\mathsf{level}[\mathsf{parent}[v]] \le \mathsf{level}[u]$  sub-claim 1 but  $\mathsf{level}[\mathsf{parent}[v]] = \mathsf{level}[v] - 1$ , so OK

## Shortest paths from the BFS tree

Claim

For all v in G:

- there is a path  $s \rightsquigarrow v$  in G iff there is a path  $s \rightsquigarrow v$  in T
- if so, the path in T is a shortest path and |evel[v]| = dist(s, v)

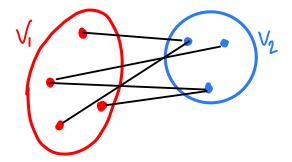
# **Proof.** First item: Exercise. Second item:

- $\operatorname{dist}(s, v) \leq \operatorname{\mathsf{level}}[v]$  (follow the path on T)
- for all i, for all v, if there is a path  $s \rightsquigarrow v$  of length i, then  $|eve|[v] \le i$ .
  - true for i = 0
  - suppose true for i − 1 and take v, a path s → v of length i and let u be the vertex before v.
     induction assumption: level[u] ≤ i − 1, so level[v] ≤ i sub-claim 2
- so  $\mathsf{level}[v] \le \operatorname{dist}(s, v)$ .

## Bipartite graphs

### Definition

a graph G = (V, E) is bipartite if there is a partition
 V = V<sub>1</sub> ∪ V<sub>2</sub> such that all edges have one end in V<sub>1</sub> and one end in V<sub>2</sub>.



## Using BFS to test bipartite-ness

### Claim.

Suppose G connected, run BFS from any s, and set

- $V_1$  = vertices with odd level
- $V_2$  = vertices with even level.

Then G is bipartite if and only if all edges have one end in  $V_1$  and one end in  $V_2$  (testable in O(m))

**Proof.**  $\Leftarrow$  obvious.

For  $\implies$ , let  $W_1, W_2$  be a bipartition. Because paths alternate between  $W_1, W_2$ :

- $V_1$  (= vertices with odd level) is included in  $W_1$  (say)
- $V_2$  (= vertices with even level) is included in  $W_2$

So  $V_1 = W_1$  and  $V_2 = W_2$ .

Computing the connected components

Idea: add an outer loop that runs BFS on successive vertices

#### Exercise

Fill in the details.

#### **Complexity:**

- each pass of BFS  $O(n_i + m_i)$ , if  $G_i(V_i, E_i)$  is the *i*th connected component
- total O(n+m)