## **Interprocess Communication Mechanisms**

- shared storage
- These mechanisms have already been covered. examples:
- \* shared virtual memory
- \* shared files
- processes must agree on a name (e.g., a file name, or a shared virtual memory key) in order to establish communication
- message based
- signals
- sockets
- pipes
- | |-|-

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Interprocess Communication sender sender send send Indirect Message Passing Direct Message Passing operating system operating system **Message Passing** receive receive receiver receiver

have some capacity to buffer (store) messages.

If message passing is indirect, the message passing system must

## **Properties of Message Passing Mechanisms**

Addressing: how to identify where a message should go

#### **Directionality:**

- simplex (one-way)
- duplex (two-way)
- half-duplex (two-way, but only one way at a time)

### **Message Boundaries:**

datagram model: message boundaries

stream model: no boundaries

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# Properties of Message Passing Mechanisms (cont'd)

# .

# **Connections:** need to connect before communicating?

- in connection-oriented models, recipient is specified at time of connection, have the same recipient. not by individual send operations. All messages sent over a connection
- in connectionless models, recipient is specified as a parameter to each send operation.

#### Reliability:

- can messages get lost?
- can messages get reordered?
- can messages get damaged?

#### Sockets

- a socket is a communication end-point
- if two processes are to communicate, each process must create its own socket
- two common types of sockets

stream sockets: support connection-oriented, reliable, duplex communication under the stream model (no message boundaries)

datagram sockets: support connectionless, best-effort (unreliable), duplex communication under the datagram model (message boundaries)

both types of sockets also support a variety of address domains, e.g.,

Unix domain: useful for communication between processes running on the same machine

INET domain: useful for communication between process running on different machines that can communicate using IP protocols

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## **Using Datagram Sockets (Receiver)**

```
s = socket(addressType, SOCK_DGRAM);
bind(s,address);
recvfrom(s,buf,bufLength,sourceAddress);
...
close(s);
```

- socket creates a socket
- bind assigns an address to the socket
- recvfrom receives a message from the socket
- buf is a buffer to hold the incoming message
- sourceAddress is a buffer to hold the address of the message sender
- both buf and sourceAddress are filled by the recvfrom call

\_

### **Using Datagram Sockets (Sender)**

```
s = socket(addressType, SOCK_DGRAM);
sendto(s,buf,msgLength,targetAddress)
...
close(s);
```

- socket creates a socket
- sendto sends a message using the socket
- buf is a buffer that contains the message to be sent
- msgLength indicates the length of the message in the buffer
- targetAddress is the address of the socket to which the message is to be delivered

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### **More on Datagram Sockets**

- sendto and recvfrom calls may block
- recyfrom blocks if there are no messages to be received from the specified socket
- sendto blocks if the system has no more room to buffer undelivered messages
- datagram socket communications are (in general) unreliable
- messages (datagrams) may be lost
- messages may be reordered
- The sending process must know the address of the receive process's socket. How does it know this?

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### **A Socket Address Convention**

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# IMAP	143/tcp	imap2
# POP version 2	109/tcp	pop2
# WorldWideWeb HTTP	80/tcp	WWW
	79/tcp	finger
# Internet Gopher	70/tcp	gopher
	37/udp	time
	25/tcp	smtp
	23/tcp	telnet
# SSH Remote Login Protocol	22/tcp	ssh
	21/tcp	ftp
	19/udp	chargen
	15/tcp	netstat
	11/tcp	systat
	7/udp	echo
Description	Port	Service

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## **Using Stream Sockets (Passive Process)**

```
\operatorname{sr}
                         close(ns); // close accepted connection
                                                                              send(ns,buf,bufLength);
close(s);
                                                                                                     recv(ns,buf,bufLength);
                                                                                                                                                         listen(s,backlog);
                                                                                                                                                                                   bind(s,address);
                                                                                                                                    П
                                                                                                                                                                                                          socket(addressType, SOCK_STREAM);
                                                                                                                               accept(s,sourceAddress);
   // don't
 accept more connections
```

- listen specifies the number of connection requests for this socket that will be queued by the kernel
- accept accepts a connection request and creates a new socket (ns)
- recv receives up to bufLength bytes of data from the connection
- send sends buf Length bytes of data over the connection.

## **Notes on Using Stream Sockets (Passive Process)**

- accept creates a new socket (ns) for the new connection
- sourceAddress is an address buffer. accept fills it with the address of the socket that has made the connection request
- additional connection requests can be accepted using more accept calls on the original socket (s)
- accept blocks if there are no pending connection requests
- connection is duplex (both send and recv can be used)

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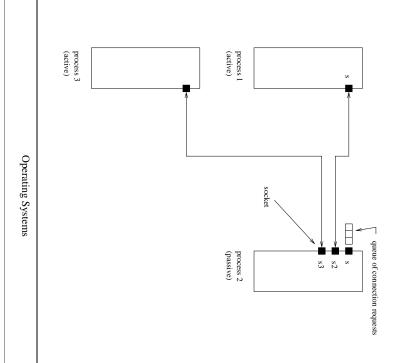
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## **Using Stream Sockets (Active Process)**

```
s = socket(addressType, SOCK_STREAM);
connect(s,targetAddress);
send(s,buf,bufLength);
recv(s,buf,bufLength);
...
close(s);
```

- connect sends a connection request to the socket with the specified address
- connect blocks until the connection request has been accepted
- active process may (optionally) bind an address to the socket (using bind) before connecting. This is the address that will be returned by the accept call in the passive process
- if the active process does not choose an address, the system will choose one

## **Illustration of Stream Socket Connections**



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#### **Pipes**

- pipes are communication objects (not end-points)
- pipes use the stream model and are connection-oriented and reliable
- some pipes are simplex, some are duplex
- parent pipes use an implicit addressing mechanism that limits their use to communication between related processes, typically a child process and its
- a pipe () system call creates a pipe and returns two descriptors, one for each end of the pipe
- for a simplex pipe, one descriptor is for reading, the other is for writing
- for a duplex pipe, both descriptors can be used for reading and writing

# One-way Child/Parent Communication Using a Simplex Pipe

```
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                                                                                                                                                                                                                                                                     pipe(fd); // create pipe
                                                                                                                                                                                                                                                                                                                                   int
                                                                                                                                                                                                                              if (pid == 0) {
                                                                                                                                                                                                                                                pid = fork(); // create child process
                                                                                                                                                                                                                                                                                       char y[100];
                                                                                                                                                                                                                                                                                                              char m[] =
                                                                                                                            else {
                                                                 read(fd[0],y,100);
                                                                                                                                                                  write(fd[1],m,19);
                                                                                                                                                                                       close(fd[0]); // close
                                                                                                                                                                                                           // child executes this
                                                                                     close(fd[1]); // close write end of pipe
                                                                                                         // parent executes this
                                                                                                                                                                                                                                                                                                                                  fd[2];
                                                                                                                                                                                                                                                                                                           "message for parent";
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                                                                                                                                                                                        read
                                                                                                                                                                                         end of
                                                                                                                                                                                         pipe
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```

Illustration of Example (after pipe())

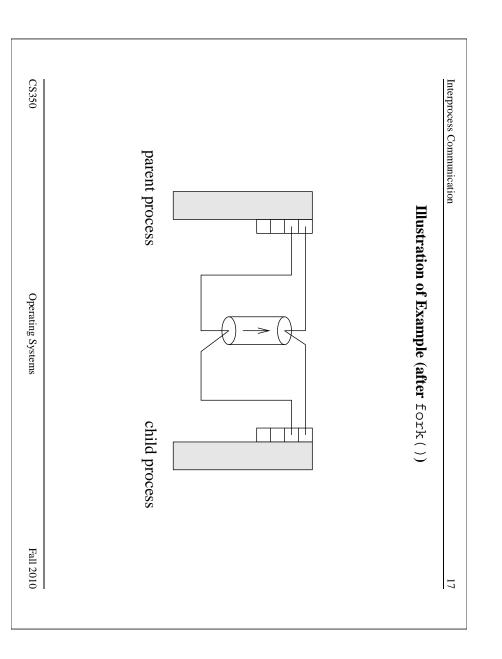
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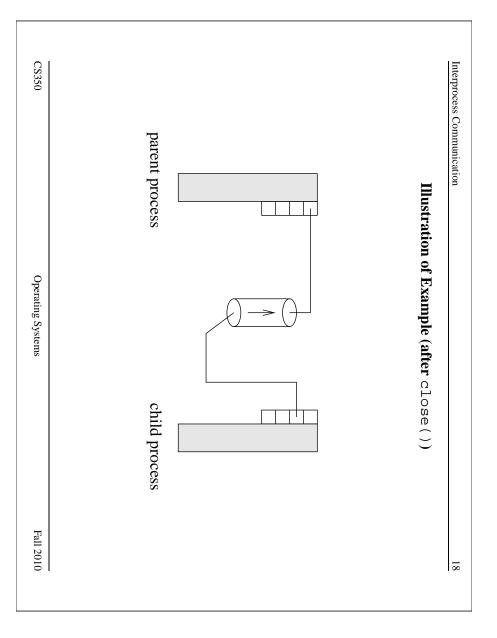
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parent process

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# **Examples of Other Interprocess Communication Mechanisms**

#### named pipe:

- similar to pipes, but with an associated name (usually a file name)
- name allows arbitrary processes to communicate by opening the same named pipe
- must be explicitly deleted, unlike an unnamed pipe

#### message queue:

- like a named pipe, except that there are message boundaries
- msgsend call sends a message into the queue, msgrecv call receives the next message from the queue

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#### **Signals**

- signals permit asynchronous one-way communication
- from a process to another process, or to a group of processes, via the kernel
- from the kernel to a process, or to a group of processes
- there are many types of signals
- the arrival of a signal may cause the execution of a signal handler in the receiving process
- there may be a different handler for each type of signal

### **Examples of Signal Types**

CS350	SIGSTOP	SIGXCPU	SIGBUS	SIGCHLD	SIGKILL	SIGILL	SIGINT	Signal
	17,19,23	24,24,30	10,7,10	20,17,18	9	4	Ν	Value
Operating Systems	Stop	Core	Core	Ign	Term	Core	Term	Action
ystems Fall 2010	Stop process	CPU time limit exceeded	Bus error	Child stopped or terminated	Kill signal	Illegal Instruction	Interrupt from keyboard	Comment

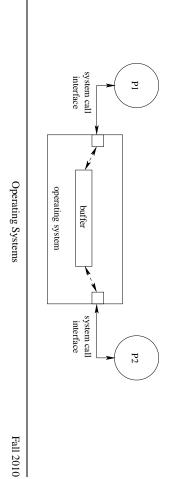
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#### **Signal Handling**

- operating system determines default signal handling for each new process
- example default actions:
- ignore (do nothing)
- kill (terminate the process)
- stop (block the process)
- a running process can change the default for some types of signals
- signal-related system calls
- calls to set non-default signal handlers, e.g., Unix signal, sigaction
- calls to send signals, e.g., Unix kill

### Implementing IPC

- refer to specific sockets and pipes, as well as files and other objects application processes use descriptors (identifiers) provided by the kernel to
- kernel descriptor tables (or other similar mechanism) are used to associate descriptors with kernel data structures that implement IPC objects
- kernel provides bounded buffer space for data that has been sent using an IPC mechanism, but that has not yet been received
- for IPC objects, like pipes, buffering is usually on a per object basis
- IPC end points, like sockets, buffering is associated with each endpoint

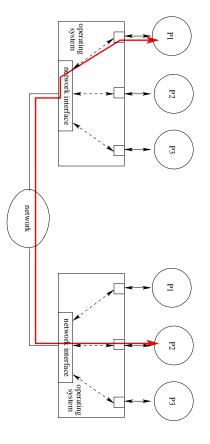


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## **Network Interprocess Communication**

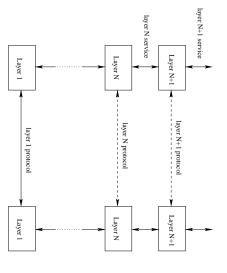
- some sockets can be used to connect processes that are running on different machines
- the kernel:
- controls access to network interfaces
- multiplexes socket connections across the network



### **Networking Reference Models**

• ISO/OSI Reference Model

Physical Layer	1
Data Link Layer	2
Network Layer	3
Transport Layer	4
Session Layer	5
Presentation Layer	9
Application Layer	7



- Internet Model
- layers 1-4 and 7

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### **Internet Protocol (IP): Layer 3**

- every machine has one (or more) IP address, in addition to its data link layer address(es)
- In IPv4, addresses are 32 bits, and are commonly written using "dot" notation,
- cpu06.student.cs = 129.97.152.106
- www.google.ca = 216.239.37.99 or 216.239.51.104 or ...
- IP moves packets (datagrams) from one machine to another machine
- should take to reach its destination principal function of IP is routing: determining the network path that a packet
- IP packet delivery is "best effort" (unreliable)

### IP Routing Table Example

Routing table for zonker.uwaterloo.ca, which is on three networks, and has IP addresses 129.97.74.66, 172.16.162.1, and 192.168.148.1 (one per network):

eth0	129.97.74.1	default
vmnet8	-	192.168.148.*
eth0	-	129.97.74.*
vmnet1	-	172.16.162.*
Interface	Gateway	Destination

• routing table key:

destination: ultimate destination of packet

gateway: next hop towards destination (or "-" if destination is directly

reachable)

interface: which network interface to use to send this packet

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## **Internet Transport Protocols**

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TCP: transport control protocol

- connection-oriented
- reliable
- stream
- congestion control
- used to implement INET domain stream sockets

**UDP:** user datagram protocol

- connectionless
- unreliable
- datagram
- no congestion control
- used to implement INET domain datagram sockets

### **TCP and UDP Ports**

- since there can be many TCP or UDP communications end points (sockets) on a single machine, there must be a way to distinguish among them
- each TCP or UDP address can be thought of as having two parts:

(machine name, port number)

- The machine name is the IP address of a machine, and the port number serves to distinguish among the end points on that machine.
- INET domain socket addresses are TCP or UDP addresses (depending on whether the socket is a stream socket or a datagram socket).

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CS350 Interprocess Communication Application Process Transport Instance Data Link Instance Network Instance network Data Link Instance **Example of Network Layers** Network Instance Operating Systems gateways network Data Link Instance Instance Network network Application Process Data Link Instance Transport Instance Network Instance Fall 2010 30

