

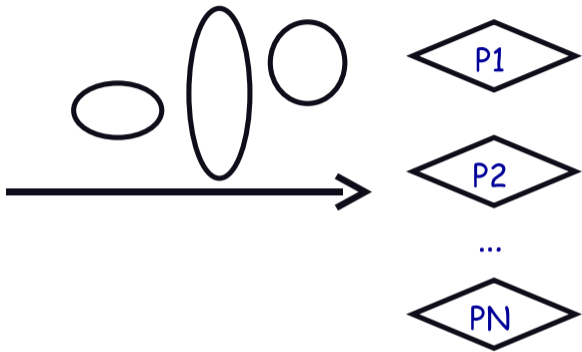
CS350: Operating Systems

Lecture 10: Scheduling

Ali Mashtizadeh

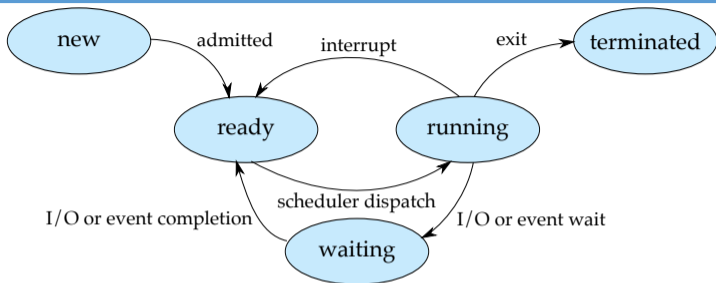
University of Waterloo

CPU Scheduling



- The scheduling problem:
 - ▶ Have K jobs ready to run
 - ▶ Have $N \geq 1$ CPUs
 - ▶ Which jobs to assign to which CPU(s)
- When do we make decision?

CPU Scheduling



- Scheduling decisions may take place when a process:
 1. Switches from running to waiting state
 2. Switches from running to ready state
 3. Switches from new/waiting to ready
 4. Exits
- Non-preemptive schedules use 1 & 4 only
- Preemptive schedulers run at all four points

Scheduling criteria

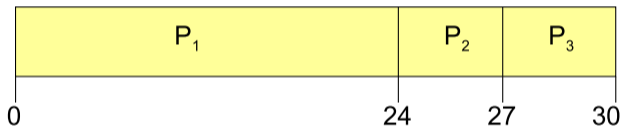
- What goals should we have for a scheduling algorithm?

Scheduling criteria

- What goals should we have for a scheduling algorithm?
- *Throughput* – # of procs that complete per unit time
 - ▶ Higher is better
- *Turnaround time* – time for each proc to complete
 - ▶ Lower is better
- *Response time* – time from request to first response (e.g., key press to character echo, not launch to exit)
 - ▶ Lower is better
- Above criteria are affected by secondary criteria
 - ▶ *CPU utilization* – fraction of time CPU doing productive work
 - ▶ *Waiting time* – time each proc waits in ready queue

Example: FCFS Scheduling

- Run jobs in order that they arrive
 - ▶ Called “*First-come first-served*” (FCFS)
 - ▶ E.g., Say P_1 needs 24 sec, while P_2 and P_3 need 3.
 - ▶ Say P_2, P_3 arrived immediately after P_1 , get:

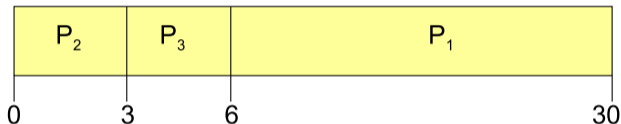


- Dirt simple to implement—how good is it?
- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround Time: $P_1 : 24, P_2 : 27, P_3 : 30$
 - ▶ Average TT: $(24 + 27 + 30)/3 = 27$
- Can we do better?

FCFS continued

- Suppose we scheduled P_2 , P_3 , then P_1

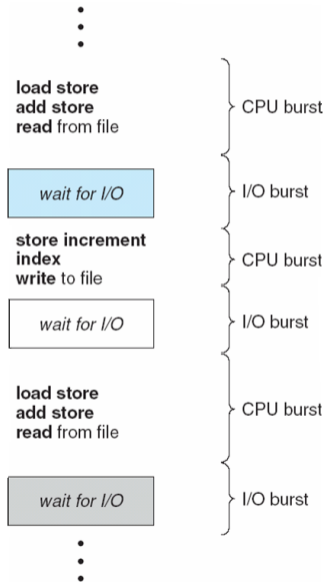
▶ Would get:



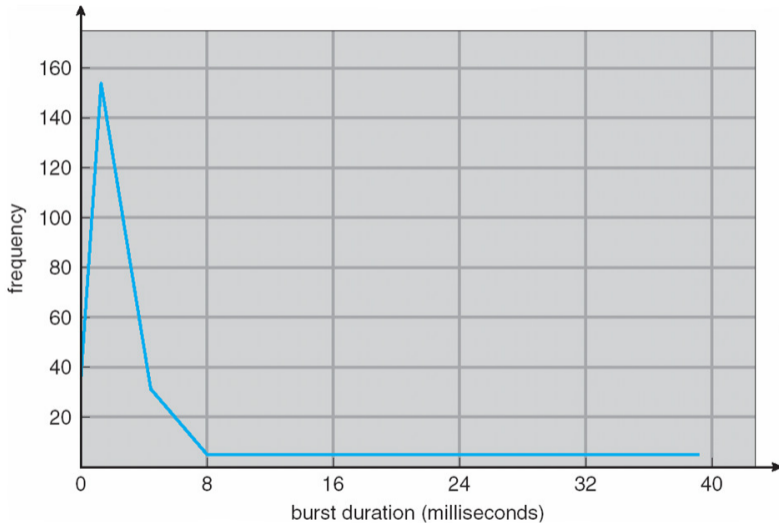
- Throughput: 3 jobs / 30 sec = 0.1 jobs/sec
- Turnaround time: P_1 : 30, P_2 : 3, P_3 : 6
 - ▶ Average TT: $(30 + 3 + 6)/3 = 13$ – much less than 27
- Lesson: scheduling algorithm can reduce TT
 - ▶ Minimizing waiting time can improve RT and TT
- What about throughput?

Bursts of computation & I/O

- Jobs contain I/O and computation
 - ▶ Bursts of computation
 - ▶ Then must wait for I/O
- To Maximize throughput
 - ▶ Must maximize CPU utilization
 - ▶ Also maximize I/O device utilization
- How to do?
 - ▶ Overlap I/O & computation from multiple jobs
 - ▶ Means *response time very important for I/O-intensive jobs*: I/O device will be idle until job gets small amount of CPU to issue next I/O request



Histogram of CPU-burst times



- What does this mean for FCFS?

FCFS Convoy effect

- CPU-bound jobs will hold CPU until exit or I/O
(but I/O rare for CPU-bound thread)
 - ▶ long periods where no I/O requests issued, and CPU held
 - ▶ Result: poor I/O device utilization
- Example: one CPU-bound job, many I/O bound
 - ▶ CPU-bound job runs (I/O devices idle)
 - ▶ CPU-bound job blocks
 - ▶ I/O-bound job(s) run, quickly block on I/O
 - ▶ CPU-bound job runs again
 - ▶ I/O completes
 - ▶ CPU-bound job continues while I/O devices idle
- Simple hack: run process whose I/O completed?
 - ▶ What is a potential problem?

SJF Scheduling

- *Shortest-job first* (SJF) attempts to minimize TT
 - ▶ Schedule the job whose next CPU burst is the shortest
- Two schemes:
 - ▶ *Non-preemptive* – once CPU given to the process it cannot be preempted until completes its CPU burst
 - ▶ *Preemptive* – if a new process arrives with CPU burst length less than remaining time of current executing process, preempt (Known as the *Shortest-Remaining-Time-First* or SRTF)
- What does SJF optimize?

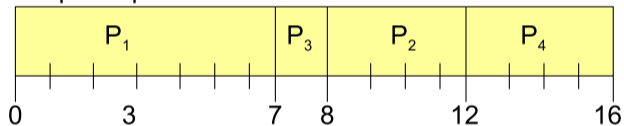
SJF Scheduling

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- What does SJF optimize?
 - ▶ Gives minimum average *waiting time* for a given set of processes

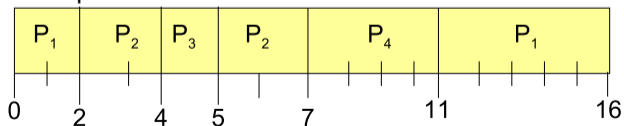
Examples

Process	Arrival Time	Burst Time
P_1	0.0	7
P_2	2.0	4
P_3	4.0	1
P_4	5.0	4

- Non-preemptive



- Preemptive



- Drawbacks?

SJF limitations

- Doesn't always minimize average turnaround time
 - ▶ Only minimizes waiting time, which minimizes response time
 - ▶ Example where turnaround time might be suboptimal?
- Can lead to unfairness or starvation
- In practice, can't actually predict the future

SJF limitations

- Doesn't always minimize average turnaround time
 - ▶ Only minimizes waiting time, which minimizes response time
 - ▶ Example where turnaround time might be suboptimal?
 - ▶ Overall longer job has shorter bursts
- Can lead to unfairness or starvation
- In practice, can't actually predict the future

Round robin (RR) scheduling



- Solution to fairness and starvation
 - ▶ Preempt job after some time slice or *quantum*
 - ▶ When preempted, move to back of FIFO queue
 - ▶ (Most systems do some flavor of this)
- Advantages:
 - ▶ Fair allocation of CPU across jobs
 - ▶ Low average waiting time when job lengths vary
 - ▶ Good for responsiveness if small number of jobs
- Disadvantages?

RR disadvantages

- Varying sized jobs are good . . . what about same-sized jobs?
- Assume 2 jobs of time=100 each:



- Even if context switches were free. . .
 - ▶ What would average completion time be with RR?
 - ▶ How does that compare to FCFS?

RR disadvantages

- Varying sized jobs are good . . . what about same-sized jobs?
- Assume 2 jobs of time=100 each:



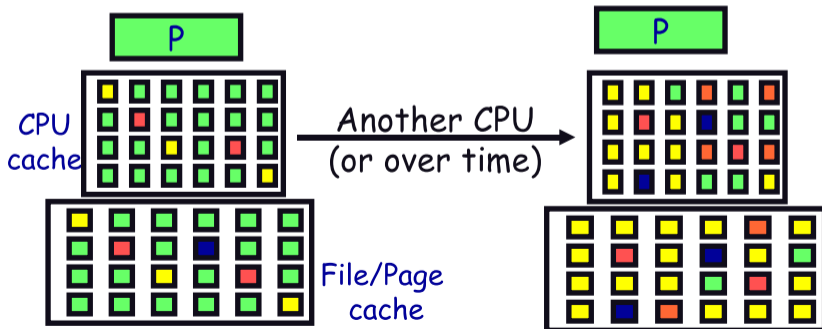
- Even if context switches were free. . .
 - ▶ What would average completion time be with RR? *199.5*
 - ▶ How does that compare to FCFS? *150*

Context switch costs

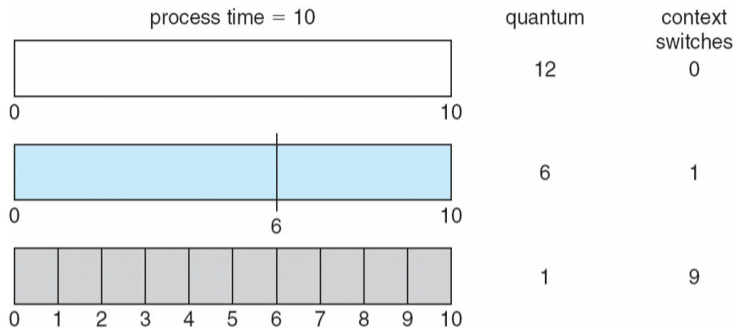
- What is the cost of a context switch?

Context switch costs

- What is the cost of a context switch?
- Brute CPU time cost in kernel
 - ▶ Save and restore registers, etc.
 - ▶ Switch address spaces (expensive instructions)
- Indirect costs: cache, buffer cache, & TLB misses

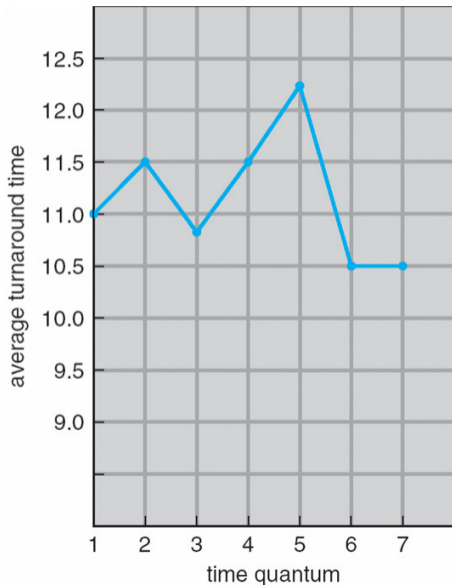


Time quantum



- How to pick quantum?
 - ▶ Want much larger than context switch cost
 - ▶ Majority of bursts should be less than quantum
 - ▶ But not so large system reverts to FCFS
- Typical values: 10–100 msec

Turnaround time vs. quantum



process	time
P_1	6
P_2	3
P_3	1
P_4	7

Priority scheduling

- Associate a numeric priority with each process
 - ▶ E.g., smaller number means higher priority (Unix/BSD)
- Give CPU to the process with highest priority
 - ▶ Can be done preemptively or non-preemptively
- Note SJF is a priority scheduling where priority is the predicted next CPU burst time
- Starvation – low priority processes may never execute
- Solution?

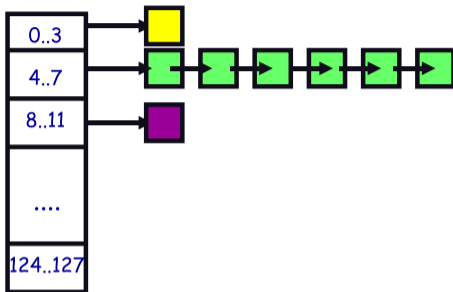
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- Starvation – low priority processes may never execute
- Solution?
 - ▶ Aging: increase a process's priority as it waits

Outline

- ① Multilevel feedback queues (BSD 4.4)
- ② Borrowed Virtual Time Scheduler

Multilevel feedback queues (BSD)



- Every runnable process on one of 32 run queues
 - ▶ Kernel runs process on highest-priority non-empty queue
 - ▶ Round-robins among processes on same queue
- Process priorities dynamically computed
 - ▶ Processes moved between queues to reflect priority changes
 - ▶ If a process gets higher priority than running process, run it
- Idea: Favor interactive jobs that use less CPU

Process priority

- `p_nice` – user-settable weighting factor
- `p_estcpu` – per-process estimated CPU usage
 - ▶ Incremented whenever timer interrupt found proc. running
 - ▶ Decayed every second while process runnable

$$p_estcpu \leftarrow \left(\frac{2 \cdot \text{load}}{2 \cdot \text{load} + 1} \right) p_estcpu + p_nice$$

- ▶ Load is sampled average of length of run queue plus short-term sleep queue over last minute
- Run queue determined by `p_usrpri/4`

$$p_usrpri \leftarrow 50 + \left(\frac{p_estcpu}{4} \right) + 2 \cdot p_nice$$

(value clipped if over 127)

Sleeping process increases priority

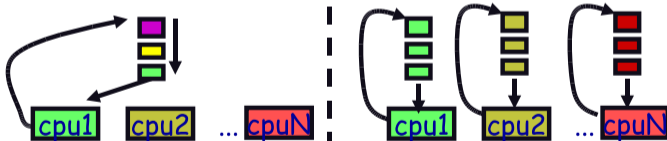
- `p_estcpu` not updated while asleep
 - ▶ Instead `p_slptime` keeps count of sleep time
- When process becomes runnable

$$p_estcpu \leftarrow \left(\frac{2 \cdot \text{load}}{2 \cdot \text{load} + 1} \right)^{p_slptime} \times p_estcpu$$

- ▶ Approximates decay ignoring nice and past loads
- Previous description based on *The Design and Implementation of the 4.4BSD Operating System* by McKusick

Multiprocessor scheduling issues

- Must decide on more than which processes to run
 - ▶ Must decide on which CPU to run which process
- Moving between CPUs has costs
 - ▶ More cache misses, depending on arch more TLB misses too
- *Affinity scheduling*—try to keep threads on same CPU



- ▶ But also prevent load imbalances
- ▶ Do *cost-benefit* analysis when deciding to migrate

Outline

- ① Multilevel feedback queues (BSD 4.4)
- ② Borrowed Virtual Time Scheduler

Borrowed Virtual Time Scheduler [Duda]

- Many modern schedulers employ notion of *virtual time*
 - ▶ Idea: Equalize virtual CPU time consumed by different processes
 - ▶ Examples: Linux CFS
- Idea: Run process w. lowest *effective virtual time*
 - ▶ A_i – *actual virtual time* consumed by process i
 - ▶ *effective virtual time* $E_i = A_i - (\text{warp}_i ? W_i : 0)$
- Supports real-time applications:
 - ▶ Warp factor allows borrowing against future CPU time
 - ▶ Allows an application to temporarily violate fairness

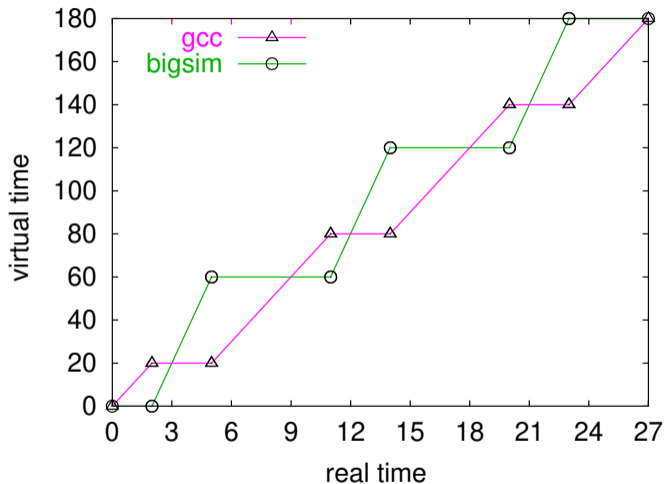
Process weights

- Each process i 's fraction of CPU determined by weight w_i
 - ▶ i should get $w_i / \sum_j w_j$ fraction of CPU
 - ▶ So w_i is seconds per virtual time tick while i has CPU
- When i consumes t CPU time, track it: $A_i += t/w_i$
- Example: gcc (weight 2), bigsim (weight 1)
 - ▶ Assuming no IO, runs: gcc, gcc, bigsim, gcc, gcc, bigsim, ...
 - ▶ Lots of context switches, not so good for performance
- Add in context switch allowance, C
 - ▶ Only switch from i to j if $E_j \leq E_i - C/w_i$
 - ▶ C is wall-clock time (\gg context switch cost), so must divide by w_i
 - ▶ Ignore C if j just became runnable... why?

Process weights

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 - ▶ C is wall-clock time (\gg context switch cost), so must divide by w_i
 - ▶ Ignore C if j just became runnable to avoid affecting response time

BVT example

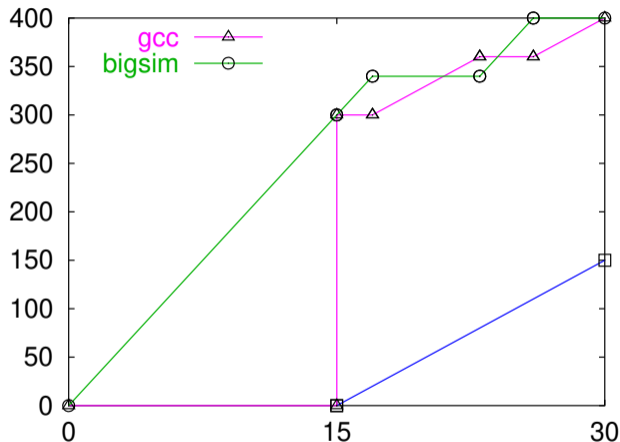


- gcc has weight 2, bigsim weight 1, $C = 2$, no I/O
 - ▶ bigsim consumes virtual time at twice the rate of gcc

Sleep/wakeup

- Must lower priority (increase A_i) after wakeup
 - ▶ Otherwise process with very low A_i would starve everyone
- Bound lag with Scheduler Virtual Time (SVT)
 - ▶ SVT is minimum A_j for all runnable threads j
 - ▶ When waking i from voluntary sleep, set $A_i \leftarrow \max(A_i, SVT)$
- Note voluntary/involuntary sleep distinction
 - ▶ E.g., Don't reset A_j to SVT after page fault
 - ▶ Faulting thread needs a chance to catch up
 - ▶ But do set $A_i \leftarrow \max(A_i, SVT)$ after socket read
- Note: Even with SVT A_i can never decrease
 - ▶ After short sleep, might have $A_i > SVT$, so $\max(A_i, SVT) = A_i$
 - ▶ i never gets more than its fair share of CPU in long run

gcc wakes up after I/O

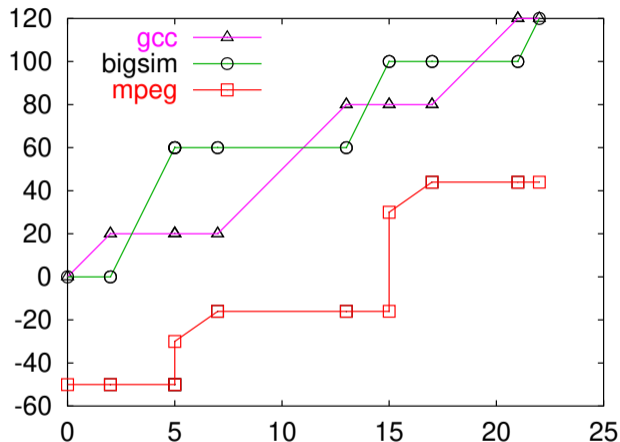


- gcc's A_i gets reset to SVT on wakeup
 - ▶ Otherwise, would be at lower (blue) line and starve bigsim

Real-time threads

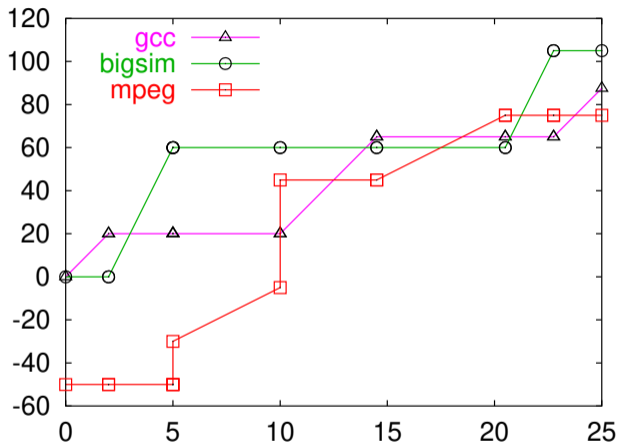
- Also want to support soft real-time threads
 - ▶ E.g., mpeg player must run every 10 clock ticks
- Recall $E_i = A_i - (\text{warp}_i ? W_i : 0)$
 - ▶ W_i is *warp factor* – gives thread precedence
 - ▶ Just give mpeg player i large W_i factor
 - ▶ Will get CPU whenever it is runnable
 - ▶ But long term CPU share won't exceed $w_i / \sum_j w_j$
- Note W_i only matters when warp_i is **true**
 - ▶ Can set warp_i with a syscall, or have it set in signal handler
 - ▶ Also gets cleared if i keeps using CPU for L_i time
 - ▶ L_i limit gets reset every U_i time
 - ▶ $L_i = 0$ means no limit – okay for small W_i value

Running warped



- mpeg player runs with -50 warp value
 - ▶ Always gets CPU when needed, never misses a frame

Warped thread hogging CPU



- mpeg goes into tight loop at time 5
- Exceeds L_i at time 10, so $\text{warp}_i \leftarrow \mathbf{false}$