

Data-Intensive Distributed Computing 431/451/631/651 (Fall 2021)

Part 1: MapReduce Algorithm Design (1/3)

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These slides are available at https://www.student.cs.uwaterloo.ca/~cs451/

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Data-intensive distributed computing

How can we process a large file on a distributed system?

MapReduce

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Just a single machine



Can we speed up this process by using more resources? How can we solve this problem using 20 servers instead? For simplicity assume that all 20 servers have a copy of the 10 TB file.



This is the logical view of how MapReduce works in our simple count Waterloo example.

Each of the 20 servers are responsible for a chunk of the 10TB file. Each server counts the number of times Waterloo appears in the text assigned to it.

Then, all servers send these partial results to another server (can be one of the 20 servers). This server adds up all of the partial results to find the total number of times Waterloo appears in the 10TB file.

Physical view details such as how each server gets the chunk it should process, and how intermediate results are moved to the reducer should be ignored for now.





In our simple example, one reducer was enough because it only had to add up some (i.e., number of mappers) numbers.

But in general we might have a ton of partial results from the map phase. Let's see another example.



The expected output is ...

For each word in the input file, count how many times it appears in the file.

Word	Count
Waterloo	36
Kitchener	27
City	512
Is	12450
The	16700
University	123



All mappers send list of (key, value) pairs to the reducer, where the key is word and value is its count.

The reducer adds up all intermediate results. But it can now be a bottleneck.

Can we have multiple reducers like mappers?







Each mapper can independently hash any key like k to find out which reducer it should go to.





The process of moving intermediate results from mappers to reducers called shuffling





Unfortunately if we want to accumulate all stats in a dictionary, it may need too much memory. Although in the case of English Text the size of the dictionary is limited to the number of English words, no assumption can be made for an arbitrary input.



For every word we read emit (word, 1) to the reducer! This way the memory we need is almost 0.



We need no change in the reduce phase. Reducers should still add all numbers for each key.



Mapper: simply process line by line. For every line emit (word, 1). Reducer: for every word, count all of the 1s.



Apache Hadoop is the most famous open-source implementation of MapReduce





MapReduce

Programmer specifies two functions:

$$\begin{split} & \textbf{map} \; (k_1, v_1) \rightarrow \text{List}[(k_2, v_2)] \\ & \textbf{reduce} \; (k_2, \text{List}[v_2]) \rightarrow \text{List}[(k_3, v_3)] \end{split}$$

All values with the same key are sent to the same reducer

The execution framework handles everything else... What's "everything else"?

MapReduce "Runtime"

Handles scheduling Assigns workers to map and reduce tasks

> Handles "data distribution" Moves processes to data

Handles synchronization Groups intermediate data

Handles errors and faults Detects worker failures and restarts

Everything happens on top of a distributed FS



MapReduce

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All values with the same key are sent to the same reducer

The execution framework handles everything else... Not quite...



The slowest operation is shuffling intermediate results from mappers to reducers

MapReduce

Programmer specifies to functions: $\begin{array}{c} \text{map} (k_1, v_1) \neq \text{List}[(k_2, v_2)] \\ \text{reduce} (k_2, \text{List}[v_2]) \neq \text{List}[(k_3, v_3)] \end{array}$

All values with the same key are sent to the same reducer

partition $(k', p) \rightarrow 0 \dots p-1$ Often a simple hash of the key, e.g., hash $(k') \mod n$ Divides up key space for parallel reduce operations

 $\begin{array}{l} \mbox{combine } (k_2, \mbox{List}[v_2]) \rightarrow \mbox{List}[(k_2, v_2)] \\ \mbox{Mini-reducers that run in memory after the map phase} \\ \mbox{Used as an optimization to reduce network traffic} \end{array}$



Partition is not a component that the data goes through, but rather a policy that determines to which reducer the output of mappers should go.





Map side:

Map outputs are buffered in memory in a circular buffer When buffer reaches threshold, contents are "spilled" to disk Spills are merged into a single, partitioned file (sorted within each partition) Combiner runs during the merges

First, map outputs are copied over to reducer machine

"Sort" is a multi-pass merge of map outputs (happens in memory and on disk) Combiner runs during the merges

Final merge pass goes directly into reducer

MapReduce hides the complexities of the physical view so that the programmer can focus on "what" rather than "how" it's done

With this approach, the datacenter with all of its complexities is like a computer.