

Lecture 10

Backup

Sol 1, 2, 3

Q1 : 4:00 Thu 2/12
15min

L10-2

Lecture Notes IV – Neural Networks, Part 2

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With Thanks to Pascal Poupart & Gautam Kamath
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February 8, 2026

Backpropagation

Train n.n. by G.D.

Training a single unit ←

Training a 2-layer network ←

Training a L -layer network ←

Reading HTF Ch.: 11.3 Neural networks, Murphy Ch.: (16.5 neural nets), Bach Ch.: –, Deep Learning Book (Goodfellow, Bengio, Courville) 6.1-4, ResNet 7.6, ConvNet 9., Autoencoders 14.1, Dive Into Deep Learning 4.1-4.3.

Training a neural network

BIG PICTURE

- ▶ Model is multilayer network.
- ▶ Layers $l = 1, 2, \dots, L$, with $x^{(l)} \in \mathbb{R}^{m_l}$, for $l = 1 : L - 1$, $m_0 = d$, $m_L = 1$ (for regression and binary classification).

$$x^{(0)} = x \quad (1)$$

$$x^{(L)} = f(x) \quad (2)$$

$$x^{(l)} = \phi(z^{(l)}) \quad \text{for } l = 1 : L - 1 \quad (3)$$

$$x^{(L)} = z^{(L)} \equiv \phi_{\text{out}}(z^{(L)}\mathbf{1}) \quad (4)$$

$$z^{(l)} = W^{(l)}x^{(l-1)} \quad (5)$$

(6)

- ▶ Parameters $\mathbb{W} = \{W^{(l)} \in \mathbb{R}^{m_l \times m_{l-1}}\}$
- ▶ $W_k^{(l)}$ is row k of $W^{(l)}$ and corresponds to unit k of layer l
- ▶ $\mathcal{D} = \{(x^1, y^1), \dots, (x^n, y^n)\}$

- ▶ **How to train this network?**
- ▶ Minimize $\mathcal{L}(\mathbb{W})$ (remember ϕ_{out} is associated with \mathcal{L})

- ▶ Minimization by **Gradient Descent**

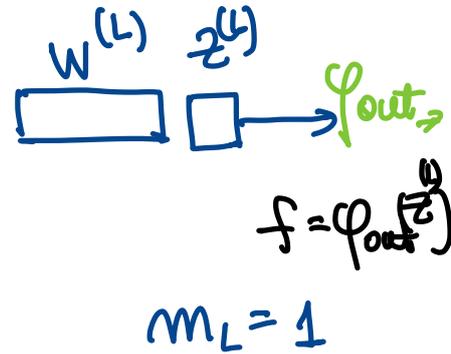
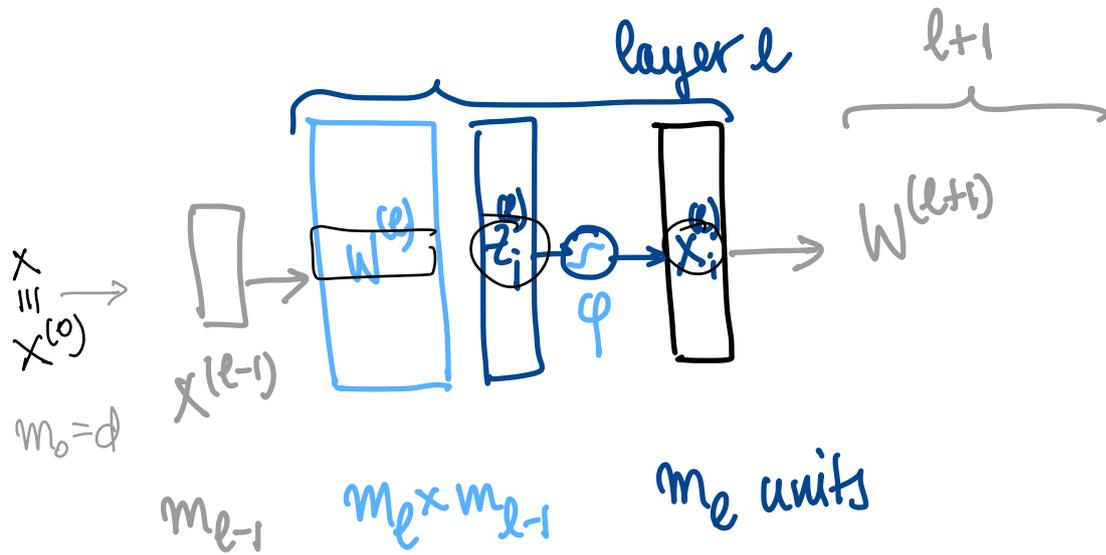
- ▶ Initialize \mathbb{W} to **small random values**
- ▶ for $t = 1, 2, \dots$ do $\mathbb{W} \leftarrow \mathbb{W} - \eta \frac{\partial \mathcal{L}}{\partial \mathbb{W}}(\mathbb{W}^t)$

- ▶ **We need to compute gradient** $\frac{\partial \mathcal{L}(\mathbb{W})}{\partial W_{ij}^{(l)}}$ for all $i = 1 : m_l, j = 1 : m_{l-1}, l = 1 : L$.

$$W_i^{(l)} \sim N(0, \frac{\sigma^2}{m_l} \mathbf{I})$$

$$\uparrow$$

$$\mathbb{R}^{m_l}$$

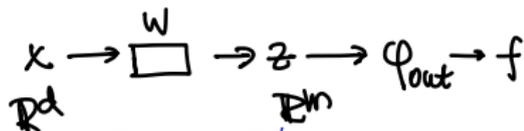


$$l = 1:L \quad z^{(l)} = W^{(l)} x^{(l-1)}$$

$$\varphi(z_i^{(l)}) = x_i^{(l)}$$

$$\left[\text{parameters } W = \{ W^{(1)}, W^{(2)}, \dots, W^{(L)} \} \right]$$

Training a single unit *single* (x, y)



- ▶ The function $f(x; \mathbb{W}) = \phi_{out} \left(\underbrace{\sum_{j=1}^d w_j x_j}_z \right)$ with parameters $\mathbb{W} = \underline{w} \in \mathbb{R}^d$.

- ▶ The loss function $\mathcal{L}(y, f(x; \mathbb{W})) =$ Least Squares, or Logistic (Max Likelihood) binary or multiclass.

Fact For each \mathcal{L} , there exists a mapping $y \rightarrow y_*$, $z \rightarrow \phi_{out}(z)$ such that

$$\boxed{-\frac{\partial \mathcal{L}(y, f(x; \mathbb{W}))}{\partial f}} = \underbrace{y_* - \phi_{out}}_{\text{target output} - \text{network output}}$$

- ▶ Let's use **chain rule**

$$z = Wx$$

$$y \rightarrow y_*$$

$$-\frac{\partial \mathcal{L}}{\partial f} = y_* - \phi_{out}(z) \quad (7)$$

$$\frac{\partial f}{\partial z} = \phi'_{out}(z) \quad (8)$$

$$\frac{\partial f}{\partial w} = \phi'_{out}(z)x \quad (9)$$

$$\frac{\partial f}{\partial x} = \phi'_{out}(z)w \quad (10)$$

$$-\frac{\partial \mathcal{L}}{\partial w} = (y_* - \phi_{out}(z))\phi'_{out}(z)x$$

$$\mathcal{L}_{LS} = \frac{1}{2} (y_* - \phi_{out})^2$$

$$\frac{\partial \mathcal{L}}{\partial \phi_{out}} = \phi_{out} - y_*$$

- ▶ Remember $\phi'_{out}(z) = z$ for \mathcal{L}_{LS} , $\phi'_{out}(z) = \phi(x)(1 - \phi(z))$ for \mathcal{L}_{logit} .
- ▶ Notice that $\frac{\partial \mathcal{L}}{\partial w}$ is a vector collinear with x .

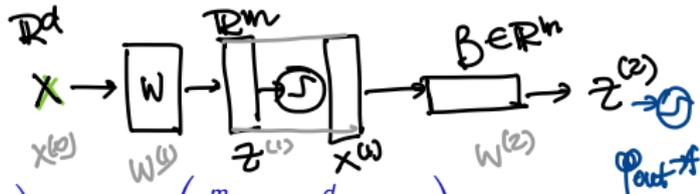
Training a single unit, n data points

- ▶ $\mathcal{D} = \{(x^1, y^1), \dots, (x^n, y^n)\}$
- ▶ For single pair (x, y) , $\frac{\partial L}{\partial w} = (y - \phi_{\text{out}}(z))\phi'_{\text{out}}(z)x$
- ▶ For entire \mathcal{D} , $\mathcal{L}(\mathbb{W}) = \frac{1}{n} \sum_{i=1}^n \mathcal{L}(y^i, f(x^i; \mathbb{W}))$.
- ▶ The gradient of this loss is

$$-\frac{\partial L}{\partial w} = \frac{1}{n} \sum_{i=1}^n \left(\frac{\partial}{\partial w} \mathcal{L}(y^i, f(x^i; \mathbb{W})) \right) = \frac{1}{n} \sum_{i=1}^n (y^i - \phi_{\text{out}}(z^i))\phi'_{\text{out}}(z^i)x^i. \quad (11)$$

Training a 2-layer network

- Consider a two layer neural network



$$f(x) = \phi_{\text{out}} \left(\sum_{i=1}^m \beta_i x_i^{(1)} \right) = \phi_{\text{out}} \left(\sum_{i=1}^m \beta_i \phi \left(\sum_{j=1}^d w_{ij} x_j \right) \right) \quad (12)$$

The parameters \mathbb{W} are β and $\mathbb{W} = [w_{ij}]_{i=1:m, j=1:d}$
Gradient w.r.t. β (same as before! $w \leftarrow \beta$)

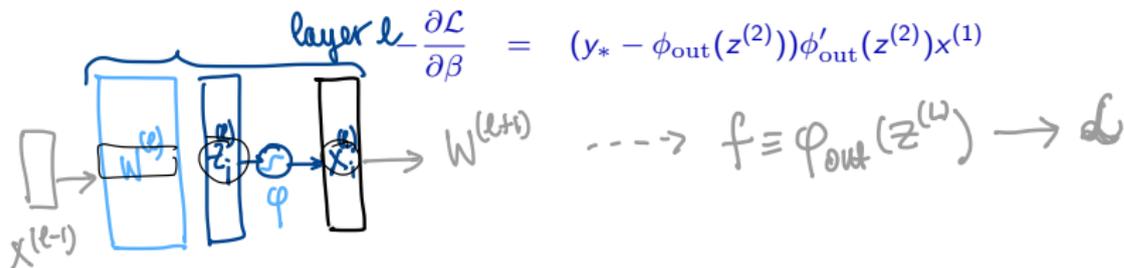
$$-\frac{\partial \mathcal{L}}{\partial f} = y_* - \phi_{\text{out}}(z^{(2)}) \quad (13)$$

$$\frac{\partial f}{\partial x^{(1)}} = \phi'_{\text{out}}(z^{(2)}) \beta \quad (14)$$

$$\frac{\partial f}{\partial x_i^{(1)}} = \phi'_{\text{out}}(z^{(2)}) \beta_i \quad (15)$$

$$\frac{\partial f}{\partial \beta} = \phi'_{\text{out}}(z^{(2)}) x^{(1)} \quad (16)$$

$$\frac{\partial \mathcal{L}}{\partial \beta} = (y_* - \phi_{\text{out}}(z^{(2)})) \phi'_{\text{out}}(z^{(2)}) x^{(1)}$$



Training a 2-layer network – hidden layer parameters

Gradient w.r.t. W

- ▶ Let's break $W \in \mathbb{R}^{m \times d}$ into rows. $W_i = [w_{ij}]_{j=1:d}$ is the column vector of weights for unit i in hidden layer.
- ▶ We have $z_i = W_i^T x$ and $x_i^{(1)} = \phi(z_i)$.
- ▶ Again, as before, with $\phi_{\text{out}} \leftarrow \phi$, $w \leftarrow W_i$, $z \leftarrow z_i$, $z^{(2)} = \beta^T x_i^{(1)}$, $f = \phi_{\text{out}}(z^{(2)})$ we have

$$\frac{\partial x_i^{(1)}}{\partial z_i} = \phi'(z_i) \quad z_i = W_i x \quad (17)$$

$$\frac{\partial x_i^{(1)}}{\partial W_i} = \phi'(z_i) x \quad \frac{\partial z_i}{\partial x} = W_i \quad (18)$$

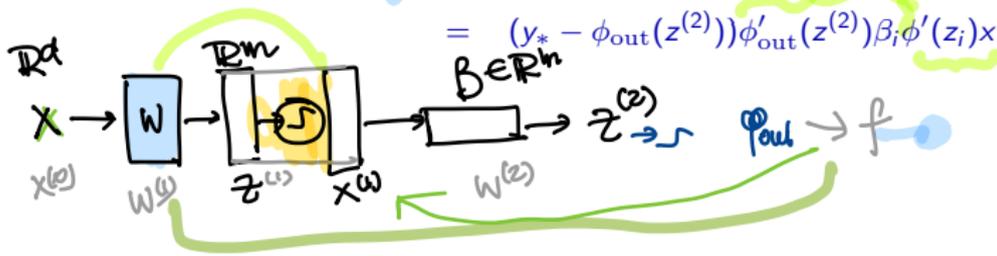
$$\frac{\partial f}{\partial W_i} = \frac{\partial f}{\partial x_i^{(1)}} \frac{\partial x_i^{(1)}}{\partial W_i} \quad (19)$$

$$= \phi'_{\text{out}}(z^{(2)}) \beta_i \phi'(z_i) x \quad (20)$$

$$-\frac{\partial \mathcal{L}}{\partial W_i} = \frac{\partial \mathcal{L}}{\partial f} \frac{\partial f}{\partial W_i} \quad (21)$$

$$= (y_* - \phi_{\text{out}}(z^{(2)})) \phi'_{\text{out}}(z^{(2)}) \beta_i \phi'(z_i) x \quad (22)$$

$$(23)$$



From 2 layers to L layers
 $|z| \text{ large} \Rightarrow \phi' \approx 0$ "saturation"

$$\frac{\partial x_i^{(l)}}{\partial z_i^{(l)}} = \phi'(z_i^{(l)})$$

$$\frac{\partial x_i^{(l)}}{\partial w_i^{(l)}} = \phi'(z_i^{(l)}) x^{(l-1)}$$

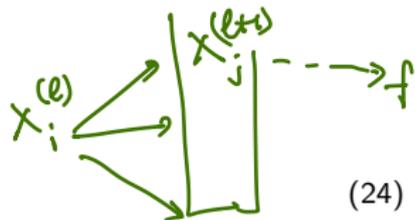
$$\frac{\partial x_i^{(l)}}{\partial x_i^{(l-1)}} = \phi'(z_i^{(l)}) w_i^{(l)}$$

used for
 $\frac{\partial \mathcal{L}}{\partial w^{(l-1)}}$

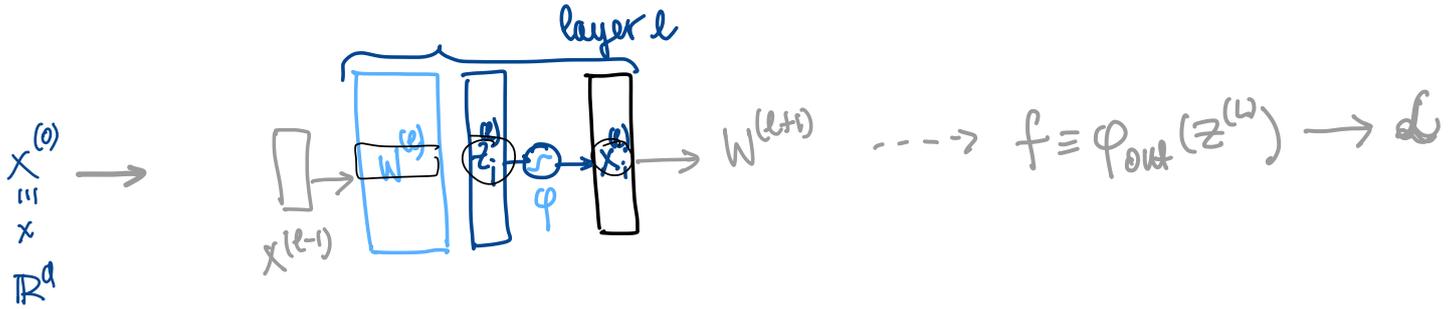
$$\frac{\partial f}{\partial x_i^{(l)}} = \sum_{j=1}^m \frac{\partial f}{\partial x_j^{(l+1)}} \frac{\partial x_j^{(l+1)}}{\partial x_i^{(l)}}$$

$$\frac{\partial f}{\partial w_i^{(l)}} = \frac{\partial f}{\partial x_i^{(l)}} \frac{\partial x_i^{(l)}}{\partial w_i^{(l)}}$$

$$\frac{\partial \mathcal{L}}{\partial w_i^{(l)}} = (y_* - \phi_{\text{out}}) \frac{\partial f}{\partial w_i^{(l)}}$$



$$z_j^{(l+1)} = w_j^{(l+1)} x_i^{(l)}$$



for $t = 1, 2, \dots$
for $k = 1:n$ (examples)

FORWARD
(Prediction)

for $l = 1:L$ store!
compute $x^{(l)}, z^{(l)}$ from $x^{(l-1)}, W^{(l)}$

$f = \varphi_{\text{out}}(z^{(L)})$, $\mathcal{L}^{\text{train}} += \frac{1}{n} \mathcal{L}(y^i, f(x^i))$ } \rightarrow used for stopping
not $\frac{\partial \mathcal{L}}{\partial W}$

BACK PROP.

for $l = L:-1:1$
compute $\frac{\partial \mathcal{L}}{\partial W_i^{(l)}}$ from $x^{(l)}, \frac{\partial \mathcal{L}}{\partial x^{(l)}}, W^{(l)}, \frac{\partial x^{(l+1)}}{\partial x^{(l)}} \frac{\partial \mathcal{L}}{\partial f}$
 $i = 1:m_e$
 $\frac{\partial x^{(l)}}{\partial x^{(l-1)}} \rightarrow$ for $\frac{\partial \mathcal{L}}{\partial W^{(l-1)}}$