

# Generalizing Greenwald-Khanna Streaming Quantile Summaries for Weighted Inputs

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# Introduction

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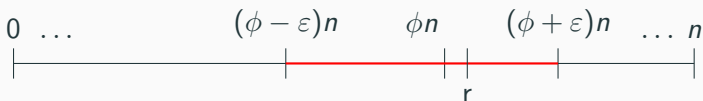
# Streaming Quantile Estimation Problem

- **Input:**

1.  $S = \{x_1, \dots, x_n\}$  of elements from an **ordered** universe (in the streaming fashion).
2. Fixed approximation parameter  $\varepsilon > 0$ .

- **Goal:** At the end of the stream, for any  $\phi \in (0, 1]$ , we want to estimate  **$\phi$ -quantile of  $S$**  up to an additive error of  $\varepsilon$ .
- On queried for any  $\phi \in (0, 1]$ , we want to be able to return  $x \in S$  such that

$$(\phi - \varepsilon)n \leq \text{rank}(x, S) \leq (\phi + \varepsilon)n.$$



- Rank of an element:

$$\text{rank}(x, S) = |\{y \in S \mid y \leq x\}|$$

# Weighted Generalized Problem

- **Input:**

1. A weighted stream  $S_w = \{(x_1, w_1), \dots, (x_n, w_n)\}$ .
2.  $w(x)$  is a **positive integer**.

$$W_n = \sum_{i=1}^n w(x_i)$$

3. Fixed  $\varepsilon > 0$

1	1	1	1	3	3	6	6	6	6	6	10	10	10	10
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# Weighted Generalized Problem

- **Input:**

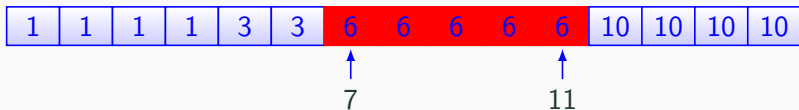
1. A weighted stream  $S_w = \{(x_1, w_1), \dots, (x_n, w_n)\}$ .
2.  $w(x)$  is a **positive integer**.

$$W_n = \sum_{i=1}^n w(x_i)$$

3. Fixed  $\epsilon > 0$



- **Range of rank:**



# Weighted Generalization Problem

- **Goal:** At the end, for any  $\phi \in (0, 1]$ , we want to return an element  $x_j$  such that

$$(\text{Range of Ranks of } x_j) \cap [(\phi - \varepsilon)W_n, (\phi + \varepsilon)W_n] \neq \emptyset$$



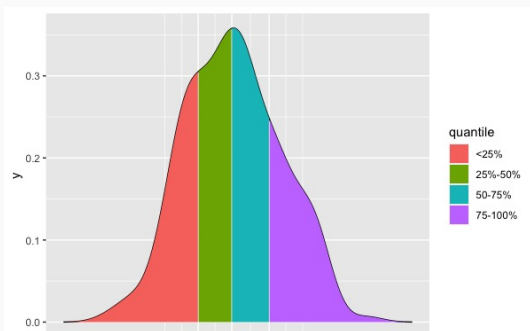
$$(\phi \pm \varepsilon)W_n$$

# Motivation

A fundamental problem in:

- Data Mining and Data Science
- Machine Learning
- Computer Science

Quantiles provide concise information about the data distribution as they allow us to estimate the CDF of the underlying distribution.



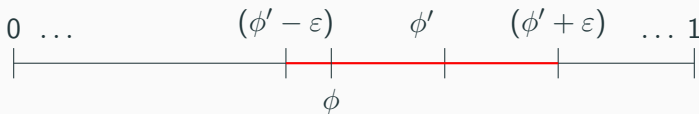


## Information Theoretic Lower Bound (Unweighted)

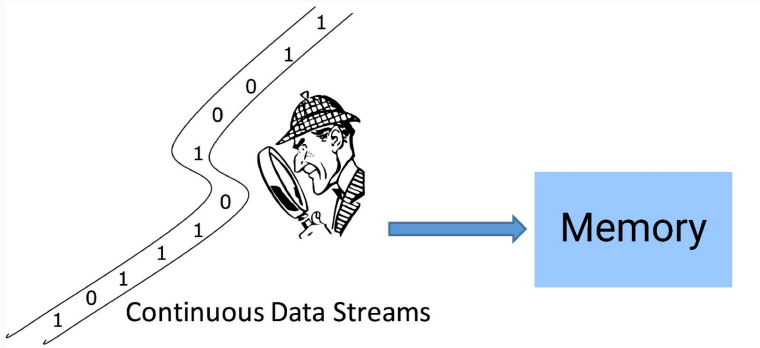
- $S = \{x_1, \dots, x_n\}$  known **apriori**
- Which elements to store to **approximately answer** quantiles queries?
- Store  $\varepsilon$ -quantile,  $3\varepsilon$ -quantile,  $5\varepsilon$ -quantile,  $\dots$ . This requires only  $O(1/\varepsilon)$  elements.



- This is also necessary!! We must store  $\Omega(1/\varepsilon)$  elements.



# Streaming Setting



Memory  $\lll$  Input Size

Elements  $x_1, \dots, x_n$  come one by one in any **arbitrary** order.

### Deterministic Algorithms:

- Manku, Rajagopalan and Lindsay [MRL'98, SIGMOD] the **MRL** algorithm: uses  $O(\frac{1}{\epsilon} \log^2(\epsilon n))$  space.
- Greenwald and Khanna [GK'01, SIGMOD] proposed the **GK** algorithm: uses  $O(\frac{1}{\epsilon} \log(\epsilon n))$  space.
- The **best-known** 22-year-old **deterministic** quantile summary.

### Randomized Algorithm:

- [KLL'16, FOCS]: answers with probabilistic guarantee  $(1 - \delta)$  and achieves  $O((\frac{1}{\epsilon}) \log \log(1/\epsilon\delta))$  space.

### Question 1

Can we improve this space-bound of  $O(\frac{1}{\epsilon} \log(\epsilon n))$  bound? Or is this optimal?

### Answer

Cormode and Vesleý [CV'20, PODS] recently resolved this question by proving  $\Omega(\frac{1}{\epsilon} \log(\epsilon n))$  lower bound.

### Question 2

Can we **simplify** the GK Algorithm so that it allows for generalization to related problems, such as the **weighted quantile problem**?

### Answer

This paper!!

## Results

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## Result 1

A **simple** and **greedy** algorithm that admits  $O(\frac{1}{\epsilon} \log^2(\epsilon n))$  space guarantee.

- Similar to the “GK-Adaptive” [LWYC’16, VLDB] that has **no theoretical guarantee**.
- Leads to intuitions behind the **counter-intuitive** choices of the GK algorithm.

## Result 2

A new **simpler description** of the GK algorithm, which requires  $O(\frac{1}{\epsilon} \log(\epsilon n))$  space.

## Result for the Weighted Setting

- **Trivial way:** Feed **multiple copies** of the same element.
- Update time  $O(\max_i w_i)$  – prohibitively large.

### Result 3

A non-trivial extension of the GK algorithm for weighted inputs that uses

- $O(\frac{1}{\epsilon} \log(\epsilon n))$  space.
- $O(\log(1/\epsilon) + \log \log(\epsilon n))$  update time per element.

assuming weights are **poly**( $n$ ) and  $\epsilon \geq 1/n^{1-\delta}$  for any  $\delta > 0$

- If  $\epsilon \approx 1/n$ , even information-theoretically  $\Omega(1/\epsilon) = \Omega(n)$  elements needed.

This matches the best unweighted case guarantees.



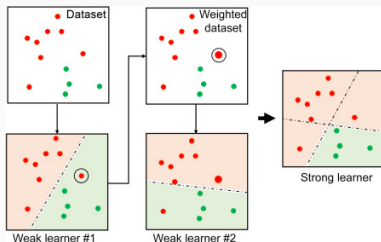
# Application

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Weak  
Learning



- Combine **weak predictors** to boost the **confidence** and **accuracy**



- Algorithm: **XGBoost** library by Nvidia
- Uses the **weighted extension** of the MRL algorithm:  
 $O\left(\frac{1}{\epsilon} \log^2(\epsilon n)\right)$  space
- Our GK extension can be used here....

## **Basic Setup: Unweighted to Weighted Extension**

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## Unweighted Quantile Summary (QS)

- **QS**: A data structure that allows us to answer  $\varepsilon$ -approximate quantile queries
- It simply stores a **subset of elements** seen so far.

$$\text{QS} = \{e_1, \dots, e_s\}$$

$$e_1 < e_2 < \dots < e_s$$

- For each element  $e \in \text{QS}$ :

**rmin**( $e_i$ ) = **lower bound** on the rank of  $e_i$

**rmax**( $e_i$ ) = **upper bound** on the rank of  $e_i$



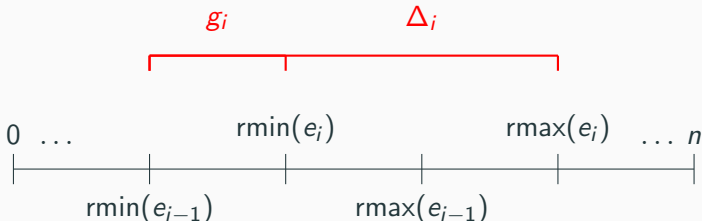
- Space Complexity =  $|\text{QS}| = \#$  of elements stored at any time.

## $(g, \Delta)$ : Indirectly Handling $(rmin, rmax)$

For each element  $e_i \in QS$ :

$$g_i := rmin(e_i) - rmin(e_{i-1})$$

$$\Delta_i = rmax(e_i) - rmin(e_i)$$

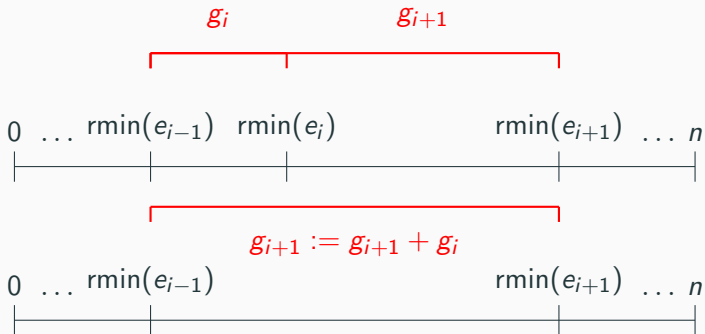


$$(rmin, rmax) \iff (g, \Delta)$$

High  $(g, \Delta) \iff$  High  
uncertainty in the Ranks

## Insert and Delete

- We can define **Insert(x)** operation
- **Delete( $e_i$ )**: Just forget  $e_i$  and keep **rmin** and **rmax** values unchanged.





### Delte( $e_i$ )

1. Delete  $e_i$  from QS.
2. Keep  $rmin$  and  $rmax$  values changed
3. Update  $g_{i+1} = g_{i+1} + g_i$ .

## Weighted Quantile Summary WQS

- **WQS**: A data structure that allows us to answer  $\varepsilon$ -approximate weighted quantile queries
- It simply stores a **subset of elements** seen so far.

$$\text{WQS} = \{e_1, \dots, e_s\}$$

$$e_1 < e_2 < \dots < e_s$$

- Store  $w(e_i)$  for each element
- For each element  $e \in \text{WQS}$ :

$\text{rmin}(e_i)$  = **lower bound** on the rank of **first copy**  $e_i$

$\text{rmax}(e_i)$  = **upper bound** on the rank of **first copy**  $e_i$

## Weighted Quantile Summary WQS

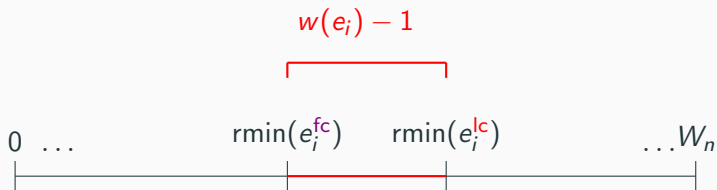
$$\text{rmin}(j\text{-th copy of } e_i) = \text{rmin}(e_i) + j - 1$$

$$\text{rmax}(j\text{-th copy of } e_i) = \text{rmax}(e_i) + j - 1$$

In particular,

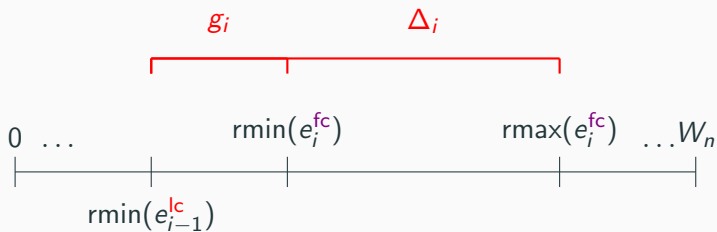
$$\text{rmin}(e_i^{\text{lc}}) = \text{rmin}(e_i) + w(e_i) - 1$$

$$\text{rmax}(e_i^{\text{lc}}) = \text{rmax}(e_i) + w(e_i) - 1$$



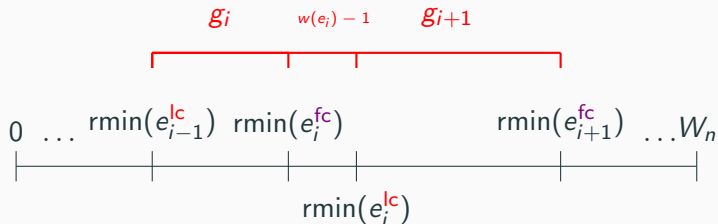
$$\Delta_i := \text{rmax}(e_i) - \text{rmin}(e_i)$$

$$g_i := \text{rmin}(e_i^{\text{fc}}) - \text{rmin}(e_{i-1}^{\text{lc}})$$

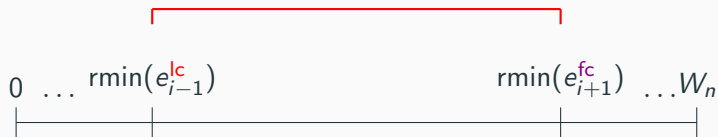


## Insert-Delete

You can also define **Insert(x)** operation.



$$g_{i+1} := g_{i+1} + g_i + w(e_i) - 1$$



$$G_i = g_i + w(e_i) - 1$$

Delete( $e_i$ )

1. Delete  $e_i$  from QS.
2. Update  $g_{i+1} = g_{i+1} + g_i + w(e_i) - 1 = g_{i+1} + G_i$ .

**Note:**  $G_i = g_i$  in the unweighted case

## Algorithm Sketch

1. **Insertion Step:** Insert **all** arriving elements  $x$  in the chunk using  $Insert(x)$ .
2. **Deletion Step:** Delete a **few elements** from QS, according to **some rule**.

The only **cleverness** of the algorithm is in the **deletion step!**

**1. To be able to answer the quantile queries**

**2. Minimize the space**

**Let's focus on the first...**

**Quantitatively, what  $(g, \Delta) \rightarrow$  allows answering quantile queries??**

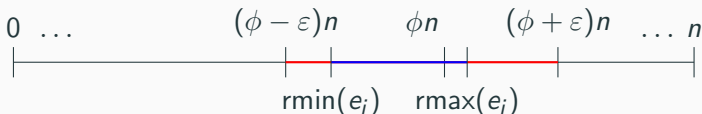


## Invariant: Sufficient Condition

Unweighted: After  $n$  insertions, for all elements  $e_j \in QS$

$$g_i + \Delta_i \leq \varepsilon n$$

then we can answer any  $\phi$ -quantile query with  $\varepsilon$ -precision.



Weighted:

$$g_i + \Delta_i \leq \varepsilon W_n$$

Delete elements as long as  $(g, \Delta)$  invariant holds....

Allows us to answer quantile queries... ✓

Space complexity ✗

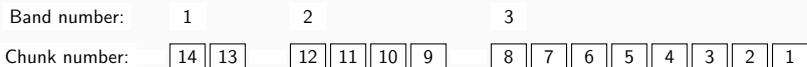
What is the magical GK deletion rule?

# **Simplified GK for the Unweighted Case**

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## Bands $\approx$ Geometric grouping of elements

- Band  $\alpha$  contains  $\approx 2^\alpha$  chunks of  $1/\epsilon$  elements
- After  $n$  insertions we have, # of bands =  $O(\log(\epsilon n))$ .



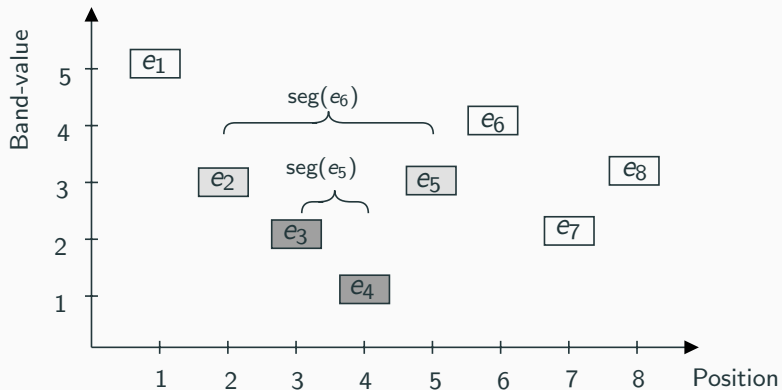
## Segment

The **segment** of an element  $e_i$  in QS, denoted by  $\text{seg}(e_i)$ , is defined as the **maximal** set of **consecutive** elements

$$e_j, e_{j+1}, \dots, e_{i-1}$$

in QS with b-value **strictly less** than  $\text{b-value}(e_i)$ .

# Segment



Treat the element and its segment as one unit!

## Simpler GK Algorithm

For arriving item  $x_k$ :

1. **Insertion Step:** Insert arriving element  $x_k$  using  $Insert(x_k)$ .
2. **Deletion Step:** For any  $e_i \in QS$ , delete  $e_i$  along with  $seg(e_i)$  if the following two conditions hold:

$$\text{b-value}(e_i) \leq \text{b-value}(e_{i+1}) \quad \text{and} \quad g_i^* + g_{i+1} + \Delta_{i+1} \leq \epsilon k$$

$$g_i^* = g_i + \sum_{j \in \text{seg}(e_i)} g_j$$

$(g + \Delta) \leq \epsilon n$  invariant holds after the deletion!

- Only  $O(1/\epsilon)$  elements per band:

Total elements =  $O(\log(\epsilon n)/\epsilon)$ .

Delete element **without segment?**

$O(\frac{1}{\epsilon} \log^2(\epsilon n))$  space

**Greedy!!**

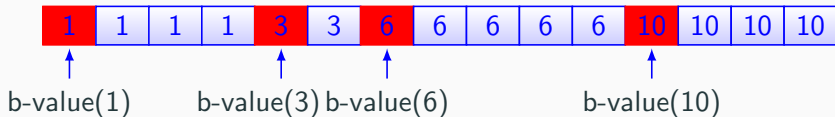


# **Non-trivial extension of the GK for Weighted Inputs**

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## Bands (Weighted)

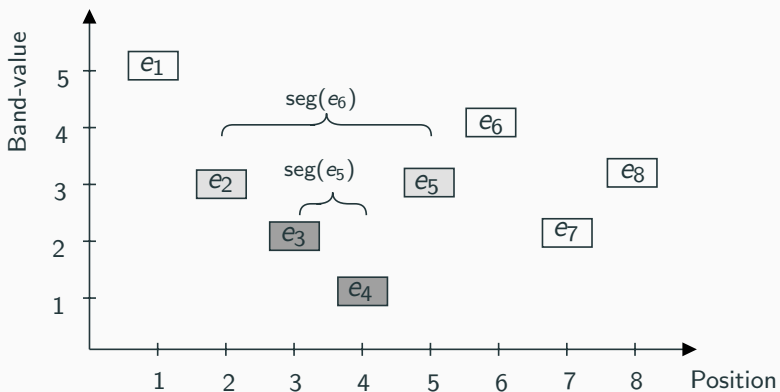
$$b\text{-value}(x) = b\text{-value}(\text{first copy of } x)$$



Different copies may have different  $b\text{-values}$  in the corresponding unweighted stream because of weights!!

$$\# \text{ bands} = O(\log \epsilon W_n)$$

## Segment (Weighted)



Treat the element and its segment as one unit!

## Weighted extension GK Algorithm

For any arriving item  $(x_k, w(x_k))$ :

1. **Insertion Step:** Run  $Insert(x_k)$ .
2. **Deletion Step:** For any  $e_i \in WQS$ , delete  $e_i$  along with  $seg(e_i)$  if the following two conditions hold:

$$\text{b-value}(e_i) \leq \text{b-value}(e_{i+1}) \text{ and } G_i^* + g_{i+1} + \Delta_{i+1} \leq \varepsilon W_k$$

$$G_i^* = G_i + \sum_{j \in \text{seg}(e_i)} G_j$$

$$(G = g + w - 1)$$

- $W_n$  = Total weight of  $n$  elements
- Using similar counting argument:

$$\text{Space Complexity} = O\left(\frac{1}{\epsilon} \log(\epsilon W_n)\right).$$

Under assumption weights are poly( $n$ ):

$$\text{Space Complexity} = O\left(\frac{1}{\epsilon} \log(\epsilon n)\right).$$

- This is **not** just some “**smart**” implementation of the “**trivial**” GK extension!!

### Trivial extension GK Algorithm

For any arriving item  $(x_k, w(x_k))$ :

1. **Insertion Step:** Insert  $w(x_k)$  copies of  $x_k$  in QS.
2. **Deletion step:** Run unweighted GK deletion rule on QS.
3. At the end, **collapse** multiple copies of the remaining elements into one element.

May delete a **partial number** of copies of one element into the other and then delete remaining copies later.....

## Weighted extension GK Algorithm

For any arriving item  $(x_k, w(x_k))$ :

1. **Insertion Step:** Run  $Insert(x_k)$ .
2. **Deletion Step:** For any  $e_i \in WQS$ , delete  $e_i$  along with  $seg(e_i)$  if the following two conditions hold:

$$\text{b-value}(e_i) \leq \text{b-value}(e_{i+1}) \text{ and } G_i^* + g_{i+1} + \Delta_{i+1} \leq \varepsilon W_k$$

**Runtime:** Already Update time doesn't depend on  $\max_{i \in [n]} w_i$ .

**Goal Accomplished!**

## Faster Runtime

- We can get  $O(\log |WQS|) = O(\log(1/\epsilon) + \log \log(\epsilon n))$  runtime.
- Store **WQS** as a balanced Binary Search Tree (**BST**).
- Insert and Delete takes  $O(\log |WQS|)$  time.
- But still, deciding which elements to delete takes time **linear in  $|WQS|$** .....
- Perform deletion only after  **$|WQS|$  doubles** by **delaying deletions** (the space increases only by a constant factor)
- Total time spent over  $n$  insertion is

$$O(n \cdot (\log(1/\epsilon) + \log \log(\epsilon n)))$$

$O(\log(1/\epsilon) + \log \log(\epsilon n))$  **amortized** update-time



## Amortized to Worst-Case Conversion

- Standard Techniques of delaying deletions
- **Spread the time** required for **the deletion step** which is linear in  $|WQS|$
- Over the **next few insertions**.
- **Interleave** between Insertions and Deletions!!
- More details in the full version: [arXiv 2303.06288](#)

### Main result

A non-trivial extension of the GK algorithm for weighted inputs, under mild assumptions:

- $O(\frac{1}{\epsilon} \log(\epsilon n))$  space.
- $O(\log(1/\epsilon) + \log \log(\epsilon n))$  update time per element.

## Open Question

- Stream  $S_1$  of length  $n_1$  and  $S_2$  of length  $n_2$
- $QS_1 = \mathcal{A}(S_1)$  and  $QS_2 = \mathcal{A}(S_2)$  with size  $f(n_1)$  and  $f(n_2)$ .

### Mergeable Summaris

An algorithm  $\mathcal{A}$  creates mergeable summaries if we can create

$$QS = \mathcal{A}(S_1 \cup S_2)$$

just using  $QS_1$  and  $QS_2$ . We then have  $|QS| = f(n_1 + n_2)$ .

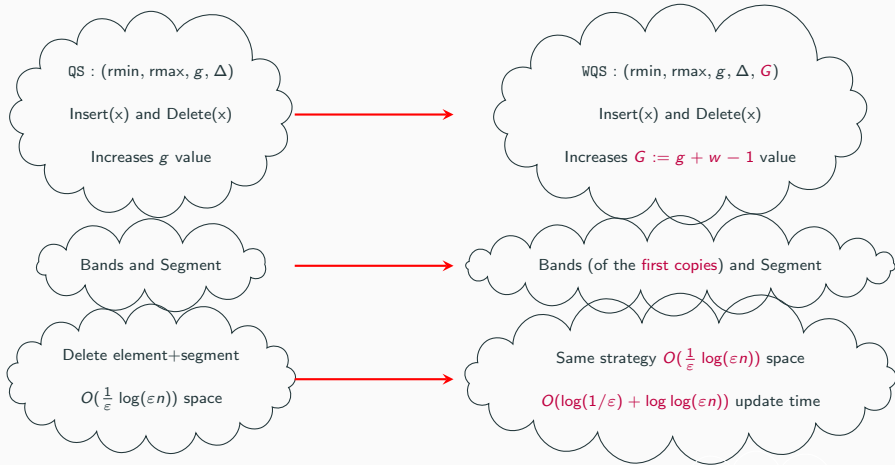
- The MRL summaries are mergeable:  $O((1/\varepsilon) \log^2(\varepsilon n))$  space.
- Is the GK summary also mergeable?

Any algorithm that uses **optimal space**, i.e.

$f(n) = O(\frac{1}{\varepsilon} \log(\varepsilon n))$  and produce **mergeable** summaries?

- Important to parallelize the algorithm.

# Summary



GK mergeable? Optimal mergeable summaries?

**Thank you!**  
**Questions?**